

NASA Contractor Report 181722

Expansion Tube Test Time Predictions

(NASA-CR-181722) EXPANSION TUBE TEST TIME
PREDICTIONS Final Report (Queensland Univ.)
S E F CSCl 14B

N89-11756

G3/09 0169992
Unclass

C.M. Gourlay

UNIVERSITY of QUEENSLAND

**St. Lucia, Queensland, 4067
AUSTRALIA**

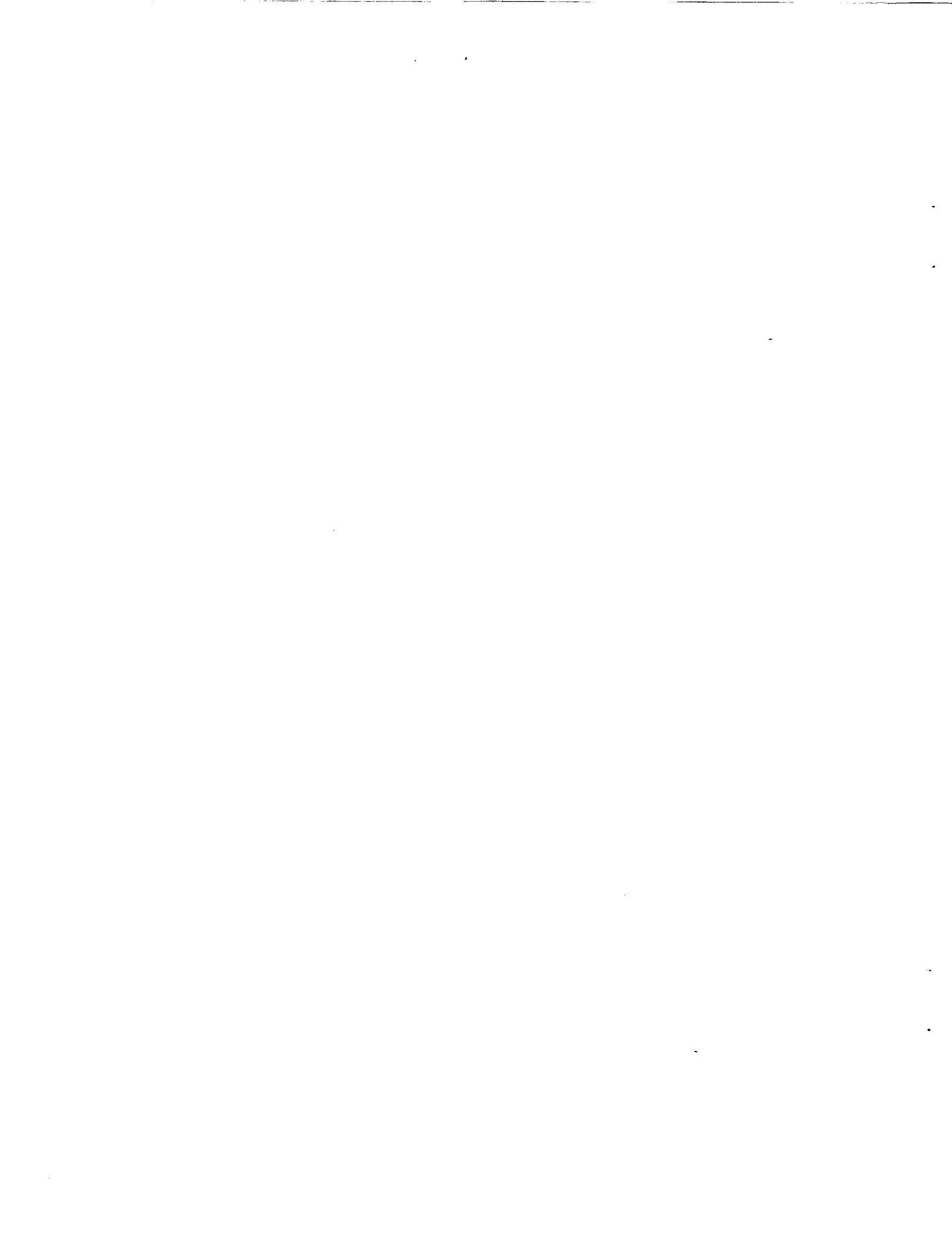
Grant NAGW-674

September 1988



National Aeronautics and
Space Administration

Langley Research Center
Hampton, Virginia 23665



ABSTRACT

The interaction of an interface between two gases and a strong expansion is investigated and the effect on flow in an expansion tube is examined. Two mechanisms for the unsteady pitot-pressure fluctuations found in the test section of an expansion tube are proposed. The first mechanism depends on the Rayleigh-Taylor instability of the driver-test gas interface in the presence of a strong expansion. The second mechanism depends on the reflection of the strong expansion from the interface. Predictions compare favourably with experimental results. The theory is expected to be independent of the absolute values of the initial expansion tube filling pressures.

**ORIGINAL PAGE IS
OF POOR QUALITY**



ACKNOWLEDGEMENTS

The author would like to thank Professor R. J. Stalker for the opportunity of working on this project and NASA Langley for funding it.

**ORIGINAL PAGE IS
OF POOR QUALITY**

TRANSPORT PROBLEMS
OF POOR QUALITY

TABLE OF CONTENTS

| | | |
|------------|---|----|
| 1. | INTRODUCTION | 1 |
| 2. | THE EXPANSION TUBE | 2 |
| 2.1 | The Ideal Expansion Tube | 2 |
| 2.2 | Boundary Layer Entrainment Effect | 3 |
| 2.3 | Real Gas Effects | 3 |
| 2.4 | Experimental Results from Expansion Tubes | 4 |
| 3. | LITERATURE REVIEW | 6 |
| 3.1 | Turbulence at the Interface and Development of Mixing | 6 |
| 3.2 | Rayleigh-Taylor Instability | 7 |
| 3.3 | Conditions for Rayleigh-Taylor Instability in Shock Tubes | 7 |
| 4. | MECHANISMS CAUSING EARLY PRESSURE FLUCTUATIONS | 10 |
| 4.1 | Equations of Motion of a Minimum Density Blob | 10 |
| 4.2 | Reflection of Waves from the Contact Surface | 13 |
| 5. | IMPLEMENTATION OF SOLUTION | 16 |
| 5.1 | Basic Assumptions | 16 |
| 5.2 | Computer Program | 16 |
| 5.3 | Verification of Computer Code and Truncation Error | 17 |
| 6. | COMPARISON OF COMPUTATIONS WITH EXPERIMENT | 19 |
| 6.1 | Shock Speed | 19 |
| 6.2 | Langley Results | 19 |
| 6.3 | U.Q. Argon Driver Results | 19 |
| 6.4 | U.Q. Helium Driver Results | 19 |
| 6.5 | U.Q. Air Driver Result | 20 |
| 7. | CONCLUSIONS | 21 |
| 8. | REFERENCES | 22 |
| 9. | FIGURES | 24 |
| APPENDICES | | |
| A. | Complete Set of Finite Difference Equations | |
| B | Program Listing | |



1. INTRODUCTION

An expansion tube is a facility for producing high-enthalpy short-duration hypersonic gas flows. The principle of operation is to use an unsteady expansion for the purpose of expanding the test gas, rather than a nozzle as in a shock tunnel. A facility built at NASA Langley (Moore, 1975) was expected to outperform conventional shock tunnels due to total-enthalpy multiplication (Trimpi, 1962). Experimental experience in the Langley expansion tube (Moore, 1975; Miller, 1977; Miller, 1978; Shinn and Miller, 1978) indicated that the duration of useful test gas flow was much less than expected. Evidence for this was primarily in the form of pitot-pressure time-histories measured at the test section. The pitot pressure time-histories indicated two unexpected phenomena. Firstly, the region of constant pressure test flow was found to be disturbed by large pitot pressure perturbations and, secondly, the magnitude of the pitot pressure was seen to 'dip' under some circumstances (Miller, 1977; Miller, 1978).

This work is aimed at explaining the first mentioned phenomenon, that is the pitot-pressure perturbations. It is expected that explanation of the basic phenomenon, or phenomena, will enable a range of useful test conditions to be established for expansion tubes. The theory formulated here will be applicable to free-piston driven expansion tubes such as at the University of Queensland.

The chapters in this report have been arranged in the following order; firstly, a description of the expansion tube (ideal and real); secondly, a review of the literature relating to the basic mechanisms causing reduction in expansion tube test times; thirdly, the new theory and computer implementation; fourthly, comparison to experiment; and fifthly, the conclusions.

UNIVERSITY OF QUEENSLAND
QF. REPORT NO. 1

2. THE EXPANSION TUBE

2.1 The Ideal Expansion Tube

The expansion tube in which the experimental data was obtained is the small 'TQ' expansion tube in the Department of Mechanical Engineering at the University of Queensland, Brisbane, Australia. The major difference in operation between this facility and the Langley facility is the free-piston driver (Stalker, 1967). The first advantage of this type of driver is that higher driver temperatures can be achieved than with a conventional driver. Secondly, the temperature and pressure of the driver gas can be varied over a wide range by different choice of diaphragm rupture pressure and filling pressures. Thirdly, the driver is at approximately constant pressure during the shock/expansion tube flow rather than the driver being a constant volume.

Figure 1 shows the wave diagram for a free-piston driven expansion tube. The flow is in three stages. In the first stage the piston is driven down the compression tube by air at high pressure thus compressing the driver gas. The driver gas is chosen to have a high speed of sound. When the piston has imparted most of its energy to the driver gas the pressure of the gas is enough to rupture the primary diaphragm.

In the second stage the hot, high pressure driver gas flows into the shock tube causing a strong shock wave to be propagated down the tube through the test gas. As driver gas flows out of the driver tube the piston velocity is chosen to match this flow-rate and hence to maintain the driver pressure at an approximately constant level. An interface, or contact surface, separates the driver and test gases.

Upon the primary shocks arrival at the secondary diaphragm, which initially separates the test gas from the low pressure acceleration gas, the third stage of flow is initiated. The secondary diaphragm bursts and a strong shock wave propagates through the acceleration gas. An second interface separates the test gas and the acceleration gas. A shock wave may be reflected at the secondary diaphragm. The test gas expands through the strong isentropic centred expansion wave generated by the low gas pressure in the expansion tube, thus acquiring kinetic energy. This expanded test gas arrives at the end of the tube and flows into the test section.

Figure 2 shows the ideal pitot pressure time history at the test section. The acceleration tube flow causes the initial step in pitot pressure and the test gas causes the second much greater step (the magnitude of the step is greater because the temperature of the test gas is significantly less than the acceleration gas). The test period continues until the arrival of the tail of the strong expansion when the pitot pressure begins to ramp up (due to the decrease in Mach number).

2.2 Boundary Layer Entrainment Effect

The effect on shock tube flow of unsteady boundary layers which develop behind the primary shock wave have been studied by Mirels (1963) and (1954) for laminar and turbulent boundary layers. The effect of the boundary layer is to entrain fluid from the region between the primary shock and the interface (see Figure 3). This causes the shock wave and the interface to approach each other, reaching a maximum separation if the tube is long enough. It can be seen that the flow between the shock and the interface is non-uniform in shock-fixed coordinates. When the limiting separation has been reached the free-stream flow has a finite subsonic speed after processing by the (fixed) shock but the contact surface is stationary. Therefore the flow between the shock and the contact surface is non-uniform. As a first approximation the free-stream flow can be assumed to be uniform. This will be true exactly for strong shocks as the shock speed approaches infinity. To find the separation of the shock and the contact surface as a function of distance the approximation of a uniform free-stream can be made and the flow is further assumed to be steady at each instant. The shock is assumed to be strong with constant speed and hence each gas particle undergoes the same increase in entropy as it is processed by the shock. Mirels has derived expressions for the limiting separations and the separation function with distance for both laminar and turbulent boundary layers for a range of real and ideal gases.

This effect has important ramifications on expansion tube flow since it means that the time interval between incident shock and tail of expansion wave arrival at the test section will be decreased (Figure 4).

2.3 Real Gas Effects

Since high enthalpies are expected behind strong shock waves such as those generated in an expansion tube (up to 5 kms^{-1} in TQ acceleration tube section and about 2 kms^{-1} in shock tube section with helium driver - Pauli, Stalker and Stringer, 1988) real gas effects such as vibrational excitation, dissociation and relaxation are expected to occur. However,

according to Trimpi (1962), less dissociation would be expected to occur than in a reflected shock tunnel. There is the possibility of the flow freezing while being expanded but this should not be significant due to the fact that, except for near the centre of the expansion wave, the expansion is spread over a significant proportion of the acceleration tube length as opposed to the relatively short length of a nozzle in a shock tunnel. Hence it would be expected that there would be time for the gas to relax to equilibrium.

Moore (1975) used two real air model to predict the wall static pressure and pitot-pressure at the test section of the Langley expansion tube as a function of interface velocities. The interface velocity was inferred from measurements of the incident shock wave and by using the theory of Mirels. The two models of air were firstly, thermodynamic equilibrium and secondly, vibrational and chemical freezing. The reflected shock wave from the secondary diaphragm was assumed to lie between the limits of being degenerate or of standing at the secondary diaphragm station. The measured wall static pressures agreed closely with the equilibrium model while the pitot-pressures were between the equilibrium and the frozen predictions. However, Miller (1975) found that predictions assuming equilibrium expansion for air with no reflected shock wave gave the best comparison with experiment.

2.4 Experimental Results from Expansion Tubes

Unsteadiness in Test Section Pitot-Pressure

Results from the Langley and the TQ expansion tubes both reveal unsteady pitot pressure effects showing variation of the acceleration tube pressure (Figure 5). The flow conditions in the University of Queensland facility were chosen to duplicate the Reynolds number, based on shock tube diameter, at the same shock velocities as in the Langley tube (Paull, Stalker and Stringer, 1988). The pitot pressure traces are similar except for the 'dip' phenomenon observed in the Langley tube (Moore, 1975; Miller, 1977 and Miller, 1978). It can be seen from the experimental results that when the acceleration tube pressure is increased, for a constant shock tube pressure, that the frequency of the pressure fluctuations increases. This suggests that there could be more than one mechanism causing fluctuations.

Shock Generated by Secondary Diaphragm Rupture

Ideally the secondary diaphragm which initially separates the test and acceleration tube gases, should be light and rupture instantaneously. However experiments by Shinn and Miller (1978) indicated that these

conditions were very often not met in practice. They obtained from tube wall pressure transducers evidence that a shock wave was reflected from the secondary diaphragm and traveled upstream against the oncoming test gas flow. Subsequently the shock wave reflected from the interface between the driver and test gases. In some cases, the shock overtook the acceleration tube incident shock thus increasing wall pressures (see Figure 6). This effect was more pronounced when the secondary diaphragm was of greater thickness and when helium was used as a test gas. In the case of air and carbon dioxide test gases the shock wave was not strong enough to travel upstream and consequently was swept downstream by the oncoming test gas flow (Miller, 1975).

Boundary Layer Transition Effect

It was shown by Shinn and Miller (1978) that the reason for the dip in the pitot pressure of the Langley tube is due to the transition of the boundary layer behind the incident shock wave in the acceleration tube section.

3. LITERATURE REVIEW

3.1 Turbulence at the Interface and Development of Mixing Region

The interface between the driver and test gases in a shock tunnel is expected to be a region of high turbulence (Hooke, 1961) partly explained by non-ideal diaphragm rupture (White, 1958) and Rayleigh-Taylor instability (Taylor, 1950; Lewis, 1950; Lin and Fyfe, 1961). This turbulence leads to mixing of the driver and test gases. Because of mixing, less test gas will be available for expansion through the nozzle into the test section since the interface becomes a mixing region. This phenomenon is also relevant to the driver-test gas interface in an expansion tube since less test gas will be available for processing by the strong expansion and hence the test time will be shortened.

An early analysis to determine the conditions under which a mixing region developed was by White (1958). White considered equal amounts of driver and test gas (volume $V/2$), at different temperatures (T_a and T_b), mixing at the interface at constant pressure. Taking the limit where the temperature ratio across the interface, $N = T_a/T_b$, was large, the change in volume of the interface could be determined. Making the assumption that the driver gas had a smaller molar specific heat, C_{P_a} , (i.e. a monatomic gas) than the test gas, C_{P_b} , an increase in volume was obtained when the driver gas was cooler than the test gas at the interface. The change in volume is given by,

$$1 + \frac{\Delta V}{V} = \frac{1 + N}{2} \left(\frac{1 + C_{P_a}/C_{P_b}}{N + C_{P_a}/C_{P_b}} \right) \quad (1)$$

and for $N \gg 1$,

$$1 + \frac{\Delta V}{V} = \frac{1}{2} (1 + C_{P_a}/C_{P_b}) \quad (2)$$

This situation occurs in conventional shock tubes where there is no pre-heating of the driver gas, and in free-piston driven facilities for some conditions. It should be noted that the higher the primary shock Mach number the hotter the test gas in relation to the driver gas and hence the more spread out the mixing region. The flow between the incident shock wave and the interface will be affected by this change in contact region volume, which can be thought of as an increase in effective "piston" velocity. In

the other limit where the expanded driver gas is much hotter than the test gas a decrease in volume of the mixing region would be expected.

Lin and Fyfe (1961) showed by dimensional arguments that the eddy diffusivity, which controls the spreading rate of the mixing region, was proportional to primary diaphragm diameter.

3.2 Rayleigh-Taylor Instability

Taylor (1950) and Lewis (1950) showed theoretically and experimentally that "...when two superposed fluids of different densities are accelerated in a direction perpendicular to their interface, this surface is stable or unstable according to whether the acceleration is directed from the heavier to the lighter fluid or vice-versa." The amplification and suppression of interface instability is shown in Figure 7. This phenomenon is known as Rayleigh-Taylor instability of accelerated interfaces and is applicable in shock and expansion tube flow to the driver/test gas interface.

3.3 Conditions for Rayleigh-Taylor Instability in Shock Tubes

An analysis was carried out by Levine (1970) who assumed that Rayleigh-Taylor instability of the driver/test gas interface caused a reduction in available test gas in a shock tube. A density gradient was produced by the mixing of cold driver gas with hot test gas at the interface in different proportions assuming constant pressure. A minimum density was found since the driver gas has a smaller average molecular weight than the test gas. This meant that the density of some of the gas in the mixing region was less than the hot gas sample and the driver gas. The acceleration field required to accelerate the less dense gas was provided by relaxation effects in an ionized monatomic test gas behind a strong shock wave. The test gas ionised a certain time after being processed by the primary shock wave, resulting in a reduction in temperature and an increase in density and hence, by continuity, an acceleration (Figure 8).

Levine used a semi-empirical approach to determine the mixing rate at the interface and hence the minimum density and the resulting test gas sample size. He derived an equation of motion for a 'blob' of light gas projected ahead of the contact surface in the presence of a heavier test gas. A simplifying assumption was made that the ratio of less to more dense gas remained constant during the period of the shock tube flow. From this he determined whether a test gas sample was likely to accumulate or not for given shock tube conditions. Gas at density ρ_{min} is buoyant in fluid of

ORIGINAL PAGE IS
OF POOR QUALITY

density ρ_{\max} under pseudo-gravitational field g where v_r is the velocity at which fluid is propelled ahead of the contact surface. The equation is,

$$\rho_{\min} \frac{dv_r}{dt} = (\rho_{\max} - \rho_{\min}) g \quad (3)$$

Houwing, Hornung and Sandeman (1981) and Houwing and Sandeman (1983) investigated Rayleigh-Taylor instability of an interface in shock tube flow similar to the case of Levine. They showed that less dense "blobs" can occur under two conditions. Firstly when the driver gas was less dense than the test gas or, as in the case of Levine, when the driver and test gases were mixed. Density profiles as a function of the proportion of driver gas are shown in Figure 9 and are reproduced from Houwing, Hornung and Sandeman (1981). In both cases the test gas temperature was greater than that of the driver gas. Houwing and Sandeman make the statement that if the ratio of the minimum density to the test gas density is calculated using the same method as Levine it is approximately equal to the ratio of average molecular weights across the interface.

Houwing, Hornung and Sandeman considered acceleration fields caused firstly by relaxation effects, due to vibrational non-equilibrium and dissociation behind the primary shock wave, and secondly from boundary layer mass entrainment effects. Only the mass entrainment effect is considered here since real gas effects are not expected to be as significant in expansion tube flow; and will not be taken into account in this analysis.

Houwing et al. (1981) and (1983) derived a more complete equation of motion for the blobs than Levine by including the virtual mass of the buoyant sphere. The equation of motion follows that derived by Batchelor (1967) and is reproduced from Houwing and Sandeman (1983),

$$M \frac{du_b}{dt} = M_0 \frac{du_2}{dt} - \frac{1}{2} M_0 \frac{d(u_b - u_2)}{dt} \quad (4)$$

where ρ_r is the density and u_b is the velocity of a non-deforming sphere in a frictionless accelerating fluid of density ρ_2 and velocity u_2 . Here M is the mass of the sphere and M_0 is the mass of the fluid displaced. The blobs are assumed to be typical of a large number of particles which comprise the mixing region. When the sphere distorts to conform to the enveloping streamlines, as in the actual flow, the buoyant gas acts like a continuum. The equation of motion is then integrated to obtain the blob velocity as a

ORIGINAL MATERIAL
OF THIS DOCUMENT

function of distance downstream of the diaphragm station with the lower limit that the blobs have the same velocity as the contact surface immediately after diaphragm rupture. It is assumed that the flow is steady and that the free-stream velocity decreases monotonically with distance from the shock wave.

Boundary layer entrainment will cause the interface to accelerate due to removal of gas from the region of flow behind the primary shock wave. Hence if blobs which are less dense than the test gas have been generated by interface mixing then a mechanism exists for accelerating some of the interface gas more than the test gas.

ORIGINAL PAGE IS
OF POOR QUALITY

4. MECHANISMS CAUSING EARLY PRESSURE FLUCTUATIONS

4.1 Equations of Motion of a Minimum Density Blob

This section discusses pitot-pressure fluctuations caused by blobs of light gas. Due to Rayleigh-Taylor instability of accelerated interfaces blobs of gas, of a lower density than the test gas, can be generated by mixing at the interface. These blobs tend to accelerate more rapidly than the surrounding test gas, in the direction of the acceleration. Hence in the acceleration field of the strong expansion they overtake the test gas and have the potential to arrive at the test section during the period of useful test flow causing pressure fluctuations (see Figure 10). As mentioned above there are two ways of generating lower density blobs. Firstly if the driver gas is less dense than the test gas blobs of driver gas will be buoyant in the test gas; and secondly by mixing in different proportions a cold monatomic driver gas with a hot diatomic test gas, where the driver gas has a smaller average molecular weight than the test gas, a blob with a density less than that of both gases can be produced.

The mechanism is implemented in three stages. Firstly the driver and test gases mix generating less dense blobs of gas. Secondly the blobs separate from the contact surface in the shock tube flow region, due to Rayleigh-Taylor instability, and are propelled forward of the test gas by the boundary layer entrainment effect in the shock tube region. Thirdly the blobs are propelled forward by the strong expansion in the acceleration tube region. The mixing model of Levine was used for the generation of the blobs at the interface. In the shock tube the equations used were similar to those of Houwing and Sandeman. New equations are developed for flow in the strong expansion region.

Generation of Density Minimum

The minimum density due to mixing at the interface is derived below.

-Conservation of Energy

$$m_d h_d + m_t h_t = mh \quad (5)$$

$$\alpha \frac{5}{2} R_d T_d + (1 - \alpha) \frac{9}{2} R_t T_t = h \quad (6)$$

$$\alpha = \frac{m_d}{m_d + m_t} \quad (7)$$

$$R_i = \frac{R}{K_i} \quad (8)$$

where σ = denotes driver gas
 t = denotes test gas
 m = mass
 h = static enthalpy
 R = engineering gas constant
 T = static temperature
 α = driver mass fraction
 R^{∞} = universal gas constant
 w_i = molecular weight

-Enthalpy of Mixture at Interface (average translational and rotational kinetic energy)

$$\frac{h}{m} = \frac{n_t \left(\frac{3}{2} R \bar{T} + 3R \bar{T} \right) + n_{\sigma} \left(\frac{3}{2} R \bar{T} \right)}{m_t + m_{\sigma}} \\ = \alpha \frac{5}{2} R_d T + (1 - \alpha) \frac{7}{2} R_t T \quad (9)$$

$$T = \frac{5\alpha R_d T_d + 7(1 - \alpha) R_t T_t}{5\alpha R_d + 7(1 - \alpha) R_t} \quad (10)$$

-Equation of State

$$\rho = \frac{m_d + m_t}{V} = \frac{p}{(\alpha R_d + (1 - \alpha) R_t) T} \\ \rho = \frac{p ((5R_d - 7R_t)\alpha + 9R_t)}{((R_d - R_t)\alpha + R_t) ((5R_d T_d - 7R_t T_t)\alpha + 7R_t T_t)} \quad (11)$$

where p = static pressure
 ρ = static density

-Density Ratio

$$\frac{\rho}{\rho_t} = \frac{\left(\frac{W_t}{W_d} - 7 \right)\alpha + 7}{\left(\left(\frac{W_t}{W_d} - 1 \right)\alpha + 1 \right) \left(\left(5 \frac{T_d}{T_t} \frac{W_t}{W_d} - 7 \right)\alpha + 7 \right)} \quad (12)$$

when $\alpha \rightarrow 0$ then $\frac{\rho}{\rho_t} \rightarrow 1$

when $\alpha \rightarrow 1$ then $\frac{\rho}{\rho_t} \rightarrow \frac{T_t}{T_d} \frac{W_d}{W_t}$

Hence for an ideal gas the density minimum depends on the ratio of molecular weights and the temperature ratio across the interface, assuming monatomic driver gas and diatomic test gas.

-Minimum Density Ratio, obtained by differentiating (12),

$$a = -\frac{b}{a} \pm \sqrt{\left(\frac{b}{a}\right)^2 - \frac{bd}{ac} - \frac{bf}{ae} + \frac{df}{ce}} \quad (13)$$

where $a = 5 \frac{W_t}{W_d} - 7$

$b = 7$

$c = \frac{W_t}{W_d} - 1$

$d = 1$

$e = 5 \frac{T_d}{T_t} \frac{W_t}{W_d} - 7$

$f = 7$

(14)

In a real gas an increase in C_p due to vibration and dissociation will produce a lower minimum density than for an calorically ideal gas.

Acceleration of Blobs and Interface during Expansion Tube Flow

It is assumed that no heat is transferred to the blobs from the test gas during their flight. An analysis was performed to determine the maximum blob size which could be heated significantly during the period of the shock tube flow. The heated blobs were found to be too small to be important with a diameter less than one thirtieth of the expansion tube diameter.

The blobs are assumed to be in mechanical equilibrium with the test gas during the period of their flight through the test gas, i.e. at the same pressure. Thus when the test gas pressure changes due to the expansion wave the blob properties change accordingly, assuming no heat transfer, to keep them at the same pressure as the surrounding test gas.

Following Batchelor,

$$M U = -\frac{M_0}{2} (U - V) + M_0 V \quad (15)$$

where M is the mass of the sphere, M_0 is the mass of the fluid displaced by the sphere, U is the velocity of the sphere, and V is the velocity the

surrounding fluid would have had if the sphere was not present. The first term represents the acceleration of the sphere, the second represents the acceleration reaction of the displaced fluid on the sphere and the third represents the buoyancy force. Rearranging and taking differentials one obtains,

$$dU = \frac{\frac{3}{2} M_0}{M + \frac{1}{2} M_0} dV \quad (16)$$

for a small change in the velocity of the sphere as a function of a small change in velocity of the surrounding fluid. It can be seen that when $M/M_0 < 1$ that $dU > dV$ and hence if this model was applied to blobs of less dense gas generated at the interface then they would accelerated more quickly than the surrounding test gas. The equation of motion can be integrated one mesh step at a time taking local values of V and M/M_0 .

Effect on Pitot Pressure

The effect of blobs on the test section pitot-pressure, is expected to be fluctuations due to the difference in temperature and density of the blobs compared to the test gas. The frequency of the fluctuations is expected to relate to the most probable blob size. Thus the presence of blobs means the pitot-pressure trace will display a contact region spread over a considerable time period instead of a sharply defined interface.

4.2 Reflection of Waves from the Contact Surface

Another possible mechanism for producing pitot-pressure perturbations is now discussed. Under some circumstances the strong expansion through which the test gas expands, after reflecting from the driver-test gas interface, can arrive at the test section during the test period. Since the interface is expected to be a region of high turbulence due to non-ideal diaphragm rupture there is the potential for unsteady pressure perturbations to be propagated along the characteristics of the reflected expansion and hence to disrupt conditions at the test section during the test period. The effect of the reflected expansion on the pitot pressure trace is shown in Figure 11. It can be seen that the pitot pressure falls, until the arrival of the contact surface, rather than rises as in the case where the reflected expansion does not arrive at the test section. This is due to the reversal of the velocity gradient. Unsteady effects which exist at the interface can then be propagated along the characteristics of the reflected expansion. It should be noted that the trajectory of the reflection of the head of the strong expansion can be determined analytically.

ORIGINAL PAGE IS
OF POOR QUALITY

If small perturbations of the flow properties, generated at the contact surface, are assumed this is equivalent to having another two families of physical characteristics and another two families of state characteristics corresponding to the perturbations of the gas properties. Mirels and Braun (1962) solved the problem of the propagation of small perturbations in uniform and self-similar flows. In their cases the physical characteristics were coincident for both the perturbed and unperturbed components of the state properties. Hence the magnitude of the perturbations of the state-variables could be integrated along characteristics in the expansion wave, since it was self-similar, and the pitot pressure fluctuations calculated. The magnitudes of the fluctuations depended on the turbulence at the interface. However in this analysis only the time of arrival of pressure perturbations is sought so the magnitude of the perturbations is not required.

As found from the Langley experiments an upstream propagating shock wave can be generated by the rupture of the secondary diaphragm. An estimate of the effect of this shock wave on the test section flow can be obtained by noting that the trajectory of a very weak shock wave is the same as that of the reflected head of the strong expansion (Figure 12). Thus an approximation to the time of arrival of such a shock wave can be gained by finding the time at which the reflected head of the strong expansion arrives at the test section.

Another possible effect of the reflected shock wave is that after it has been transmitted through the driver-test gas interface bifurcation may occur. Bifurcation occurs when the tube wall boundary layer stagnation pressure is not great enough to allow it to be decelerated by a normal shock and hence oblique shocks form and gas collects at the foot causing it to grow with time (Figure 13). This means that a jet of gas can be generated on the walls of the tube, formed by the oblique shock waves, which has a greater velocity towards the test section end of the tube than does the gas processed by the normal shock wave. Thus driver gas can arrive at the test section earlier than expected. This mechanism has been examined by Davies and Wilson (1969) and others. It will not be pursued here.

It should be noted that no pitot-pressure perturbations occurred in the Langley tube without the presence of a secondary diaphragm (Shinn and

**ORIGINAL PAGE IS
OF POOR QUALITY**

Miller, 1978). Hence the secondary diaphragm must be important in the generation of pitot-pressure fluctuations.

5. IMPLEMENTATION OF SOLUTION

The method of characteristics for unsteady flow in one dimension has been used to predict the flow in the expansion tube assuming perfect gases. The effect of boundary layer entrainment has been included approximately by calculating new trajectories for the driver-test and test-acceleration gas interfaces. The effect of the entrainment on the free-stream flow has not been considered; this is known as the uniform free-stream approximation. The pitot pressure has been predicted as a function of time at the test section by the Rayleigh pitot pressure formula with an empirical correction being employed to account for the higher predicted shock speeds than those measured in experiment.

5.1 Basic Assumptions

The gases are all assumed to be thermally and calorifically perfect and in thermodynamic equilibrium. In the expansion tube flow ideal diaphragm rupture has been assumed. The free-piston driver is treated as a constant pressure reservoir with the conditions calculated using isentropic compression of the driver gas. The Mirels boundary layer entrainment effect has been included assuming the uniform free-stream approximation for the contact surface trajectories. Primary shock waves have been assumed to have constant velocity and hence no entropy variation exists for different particles of gas. The latter two assumptions are both applicable for strong shock waves. At the interface mixing occurs adiabatically and isobarically in an initial thin contact surface. The blobs of low density gas generated are small, non-deforming spheres in mechanical equilibrium with the surrounding gas flow and are typical of a large number of such which make up the mixing front. The test section flow is assumed to be quasi-steady for the pitot pressure determination.

5.2 Computer Program

The finite difference equations for the method of characteristics for one-dimensional unsteady flow are given in Appendix A. The method was implemented on a Apple Macintosh Plus Personal Computer in compiled BASIC. The method uses a combined graphical-numerical approach. The computer implementation is interactive and the procedure is similar to that required if the wave diagram were to be constructed on graph paper, except the machine does all the calculations and the 'house-keeping'. A flow chart of the program logic is shown as Figure 14. The program waits for the user to select from the menu the next type of point he wishes to calculate, for example; 'Interior', 'Contact', or 'Expansion'. Once the user has defined this he then selects, using the mouse, the existing points from which he

wants the new point to be calculated. The computer then calculates the new point and displays its location on the screen. The properties at a point can be perused at any time by the user. A database is generated on disc as calculation proceeds so that the solution can be regenerated or added to at a later date. The program listing can be found in Appendix B.

When calculating the wave diagram it becomes necessary to refine the mesh if flow properties are changing rapidly. In this case the program has a facility for 'splitting' the mesh by linear interpolation of properties between known points. This raises the problem of how to save the data for each point in the database such that it can be retrieved and the flowfield reconstructed correctly. The storage of data adopts a method of inter-relating records known as linked records. Stored with the values of the properties at each point are two numbers. These numbers give the numbers of the records where the properties of the two upwind points on which the point depends are stored. It is easy therefore to split the mesh and to change the way the records are linked when a new intermediate point is created.

5.3 Verification of Computer Code and Truncation Error

The computer code was checked by calculating the trajectory of the contact surface through the expansion fan when the same gas at the same conditions is on either side. This is the same as calculating a particle path. The three families of characteristics give,

$$\frac{dt}{dx} = \frac{1}{u - a} \quad (17)$$

$$\frac{u}{2} + \frac{a}{\gamma - 1} = \frac{u_1}{2} + \frac{a_1}{\gamma - 1} = \frac{u_2}{2} + \frac{a_2}{\gamma - 1} \quad (18)$$

$$\frac{dt}{dx} = \frac{1}{u} \quad (19)$$

$$x = \frac{t}{1 - \gamma} \left[a_1 \left(1 + \gamma \left(\frac{t}{t_1} \right)^{\frac{1-\gamma}{1+\gamma}} - 2 \left(a_1 + \frac{\gamma-1}{2} u_1 \right) \right) \right] \quad (20)$$

The numerical solution to the wave diagram is given as Figure 15. The analytical solution for the path line is exactly coincident to the numerical solution to the resolution of the diagram.

The compatibility relations of the method of characteristics depend on the mesh and so approximations must be made in computing flow properties. Prior

to use of this procedure, the point properties are assumed to vary in a polynomial fashion along characteristics between the known and unknown points. The order of the polynomial variation can be selected according to the desired accuracy required of the solution. A method of improving these inherent approximations is to use a mesh size which is appropriate for the level of accuracy required. The average value of the properties was used for calculation of the physical characteristics hence the accuracy of the mesh is of the order of $(\Delta x)^3$ and $(\Delta t)^3$. For calculations of flow properties on the contact surface average values were also used but iteration was required hence the maximum accuracy expected, after convergence, is of the order of $(\Delta u)^3$ and $(\Delta p)^3$. The calculation of flow properties at other points is exact.

ORIGINAL PAGE IS
OF POOR QUALITY

6. COMPARISON OF COMPUTATIONS WITH EXPERIMENT

6.1 Shock Speed

The predicted shock speeds are up to thirty percent higher than the measured ones. (All the following experimental results are taken from Paull, Stalker and Stringer, 1988.) This was accounted for in the pitot-pressure prediction by the use of an empirical correction factor.

6.2 Langley Results

As the acceleration tube pressure is increased the model predicts that unsteady effects, due to the reflected expansion, should arrive earlier. Blobs are predicted but they arrive very much later than in the useful test time and so are not relevant. There is evidence of another unsteady effect at the lower acceleration tube pressures possibly due to waves being reflected from the walls of the tube. The dip noted in the case with the highest shock tube pressure is due to boundary-layer transition in the acceleration tube.

The reflected expansion trends compare favourably to reflected shock trends as determined by wall pressures measurements (Shinn and Miller (1978)). Hence the reflected head of the expansion predicts the reflected shock behaviour at least qualitatively.

6.3 U.Q. Argon Driver Results

As the acceleration tube pressure is increased the model predicts that unsteady effects, due to the reflected expansion, should arrive earlier. Blobs are not predicted. There is evidence of another unsteady effect at the lower acceleration tube pressures possibly due to waves being reflected from the walls of the tube.

No blobs are predicted for any case with an argon driver. (For an ideal gas the density minimum depends on the ratio of molecular weights and the temperature ratio across the interface, assuming monoatomic driver and diatomic test gas).

The absence of the dip phenomenon can be explained by the fact that boundary layer transition would not be expected from Reynolds number calculations based on the acceleration tube length of TQ.

6.4 U.Q. Helium Driver Results

Taking the column of results for which the acceleration tube pressure is approximately 120 mm it can be seen for lower shock tube pressures the

reflected expansion arrives before the blobs while for the higher shock tube pressures the blobs arrive before the reflected expansion. The blobs arrive latest for the central case ($p_1 = 13.8$ kPa), while the reflected expansion arrives latest for the $p_1 = 101$ kPa case. It can also be seen that the blobs tend to produce large scale pitot pressure fluctuations while the reflected expansion causes fluctuations on a smaller scale.

Considering holding shock tube pressure constant while varying the acceleration tube pressure; an increase in acceleration tube pressure causes both the blobs and the reflected expansion to arrive earlier. This agrees with the Langley and argon driver predictions (for the reflected expansion). These effects can be seen by considering either the top row or the bottom row of the array.

(It should be noted that for the case in the extreme upper right corner of the array that the expansion reflected from the driver-test gas interface is predicted to further interact with the test-acceleration gas interface. This effect was not included in the model and hence this prediction is less certain. What is certain is that the reflected expansion arrives very early.)

6.5 U.Q. Air Driver Result

There were no blobs predicted for the case with an air driver and although the reflected expansion is predicted to arrive reasonably early the fluctuations are not sufficient to degrade to a serious extent the relatively long period of test flow found in this case.

ORIGINAL PAGE IS
OF POOR QUALITY

7. CONCLUSIONS

The model developed here explains some of the previously unexplained features of expansion tube flow tolerably well. It also indicates that the two mechanisms considered are pressure independent, except for a small pressure dependence of the boundary layer entrainment effect. Therefore either scaling the initial pressure filling ratios either up or down should produce flow with the same characteristics. Hence the initial filling pressure ratios that produce the longest period of test flow can be obtained. Therefore no additional work is required to determine the best pressure ratios for higher absolute pressure conditions.

8. REFERENCES

- Batchelor, G. K. (1967) *An Introduction to Fluid Dynamics*. Cambridge, University Press.
- Davies, L. and Wilson, J.L. (1969) "Influence of Reflected Shock and Boundary-Layer Interaction on Shock-Tube Flows." *Phys Fluids Suppl I*. 37-43.
- Ferri, A. ed. (1961) *Fundamental Data Obtained from Shock-Tube Experiments*. AGARD, Pergamon.
- Hoeker, W. J. (1961) "Testing Time and Contact-Zone Phenomena in Shock Tube-Flows." *Phys Fluids* 4. 1451-1463.
- Houwing, A. F. P. and Sandeman, R. J. (1983) "Contact Zone Instability due to Real Gas Effects in Shock Tube Flows." *Proc 14th Int Sym Shock Tubes Waves*, Sydney. 285-292.
- Houwing, A. F. P., Hornung, H. G. and Sandeman, R. J. (1981) "Investigation of the Distortion of Shock-Fronts in Real Gases." *Proc 13th Int Sym Shock Tubes Waves*, Niagara Falls. 176-184.
- Levine, M. A. (1970) "Turbulent Mixing at the Contact Surface in a Driven Shock Wave." *Phys Fluids* 13. 1166-1171.
- Lewis, D. J. (1950) "The Instability of Liquid Surfaces when Accelerated in a Direction Perpendicular to their Planes. II" *Proc Roy Soc A202*, London. 81-96.
- Liepmann, H. W. and Roshko, A. (1957) *Elements of Gas Dynamics*. New York, John Wiley.
- Lin, S-C and Fyfe, W. I. (1961) "Low-Density Shock Tube for Chemical Kinetics Studies." *Phys Fluids* 4. 238-249.
- Miller, C. G. (1975) "Shock Shapes on Blunt Bodies in Hypersonic-Hypervelocity Helium, Air, and CO₂ Flows, and Calibration Results in Langley 6-Inch Expansion Tube." *NASA Technical Note D-7800*.
- Miller, C. G. (1977) "Operational Experience in the Langley Expansion Tube with Various Test Gases." *NASA Technical Memorandum 78637*.
- Miller, C. G. (1978) "Operational Experience in the Langley Expansion Tube with Various Test Gases." *AIAA Journal* 16. 195-196.
- Mirels, H. (1963) "Test Time in Low-Pressure Shock Tubes." *Phys Fluids* 6. 1201-1214.
- Mirels, H. (1964) "Shock Tube Test Time Limitation Due to Turbulent-Wall Boundary Layer." *AIAA Journal* 2. 84-93.
- Mirels, H. and Braun, W. H. (1962) "Perturbed One-Dimensional Unsteady Flows Including Transverse Magnetic-Field Effects." *Phys Fluids* 5. 259-265.

ORIGINAL PAGE IS
OF POOR QUALITY

- Mirels, H. and Mullen, J. F. (1964) "Small Perturbation Theory for Shock-Tube Attenuation and Nonuniformity." *Phys Fluids* 7. 1208-1218.
- Moore, J. A. (1975) "Description and Initial Operating Performance of the Langley 6-Inch Expansion Tube using Heated Helium Driver Gas." NASA Technical Memorandum X-3240.
- Rudinger, G. (1955) *Wave Diagrams for Nonsteady Flow in Ducts*. New York, Van Nostrand.
- Shinn, J. L. and Miller, C. G. (1978) "Experimental Perfect-Gas Study of Expansion-Tube Flow Characteristics." NASA Technical Paper 1317.
- Stalker, R. J. (1964) "Area Change with a Free-Piston Shock Tube." *AIAA Journal* 2. 396-397.
- Stalker, R. J. (1967) "A Study of the Free-Piston Shock Tunnel." *AIAA Journal* 5. 2160-2165.
- Faull, A., Stalker, R. J. and Stringer, I. (1968) "Experiments on an Expansion Tube with a Free-Piston Driver." Submitted to *AIAA Journal*.
- Taylor, Sir G. I. (1950) "The Instability of Liquid Surfaces when Accelerated in a Direction Perpendicular to their Planes. I" *Proc Roy Soc A201*, London. 192-196.
- Trimpi, R. L. (1962) "A Preliminary Theoretical Study of the Expansion Tube, a New Device for Producing High-Enthalpy Short-Duration Hypersonic Gas Flows." NASA Technical Report R-133.
- White, D. R. (1958) "Influence of Diaphragm Opening Time on Shock-Tube Flows." *J Fluid Mech* 4. 585-599.

ORIGINAL PAGE IS
OF POOR QUALITY

9. FIGURES

ORIGINAL PAGE IS
OF POOR QUALITY

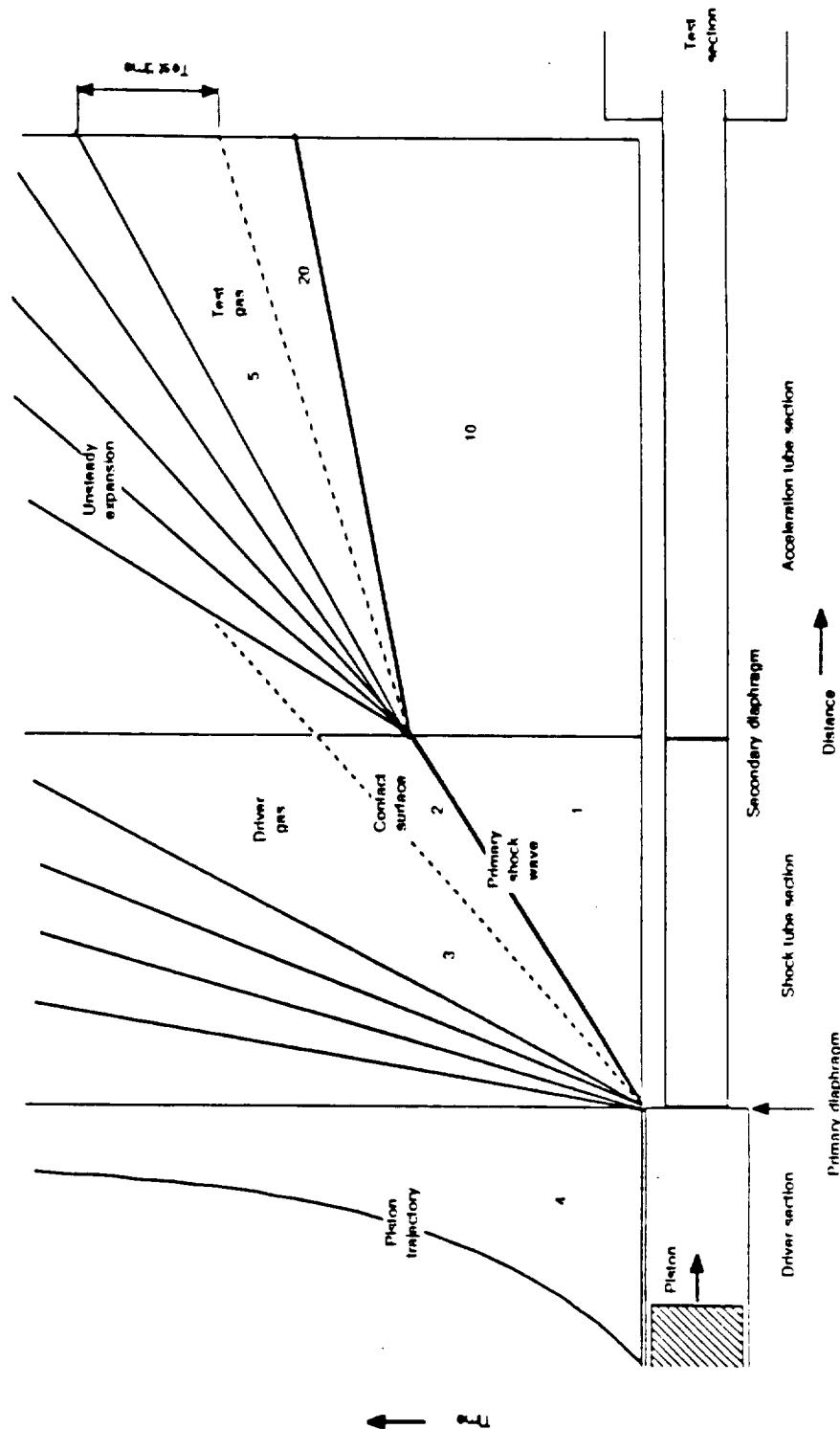


Figure 1: Wave diagram of ideal expansion tube flow.

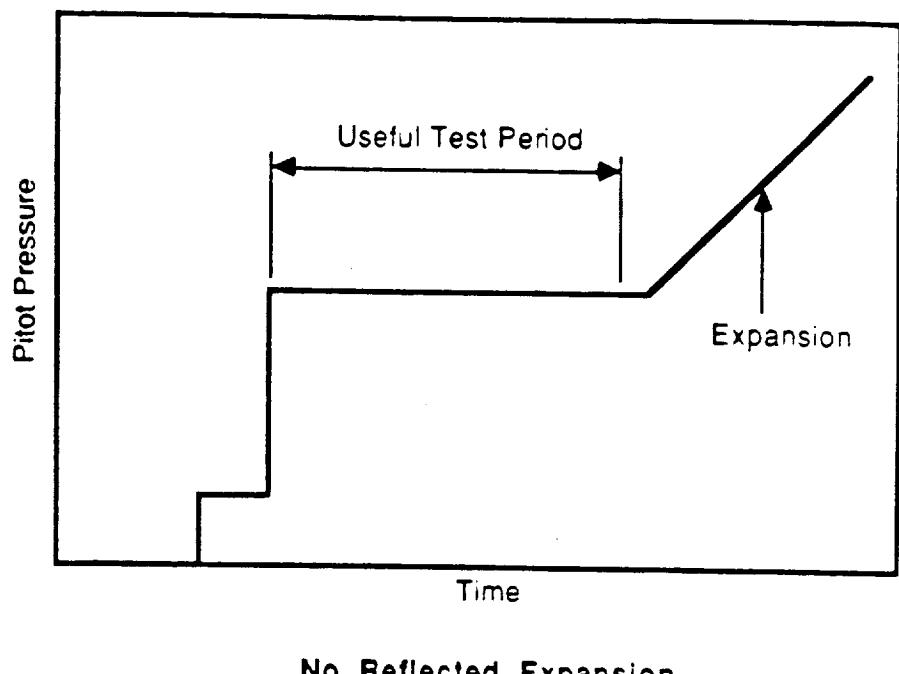


Figure 2: Ideal pitot-pressure time-history at the test section.

ORIGINAL PAGE IS
OF POOR QUALITY

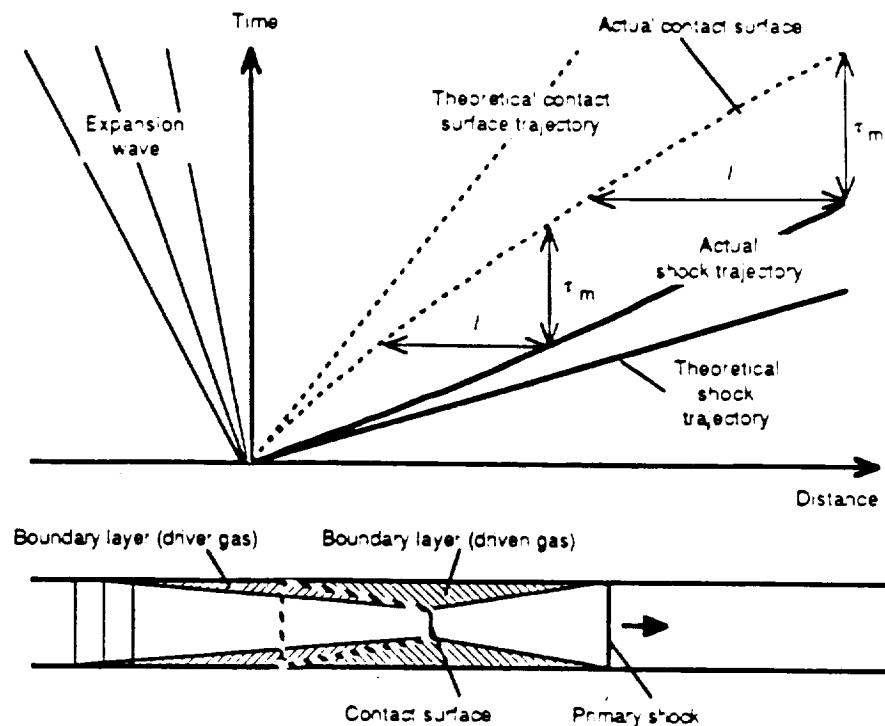


Figure 3: Mirel's boundary layer entrainment effect.

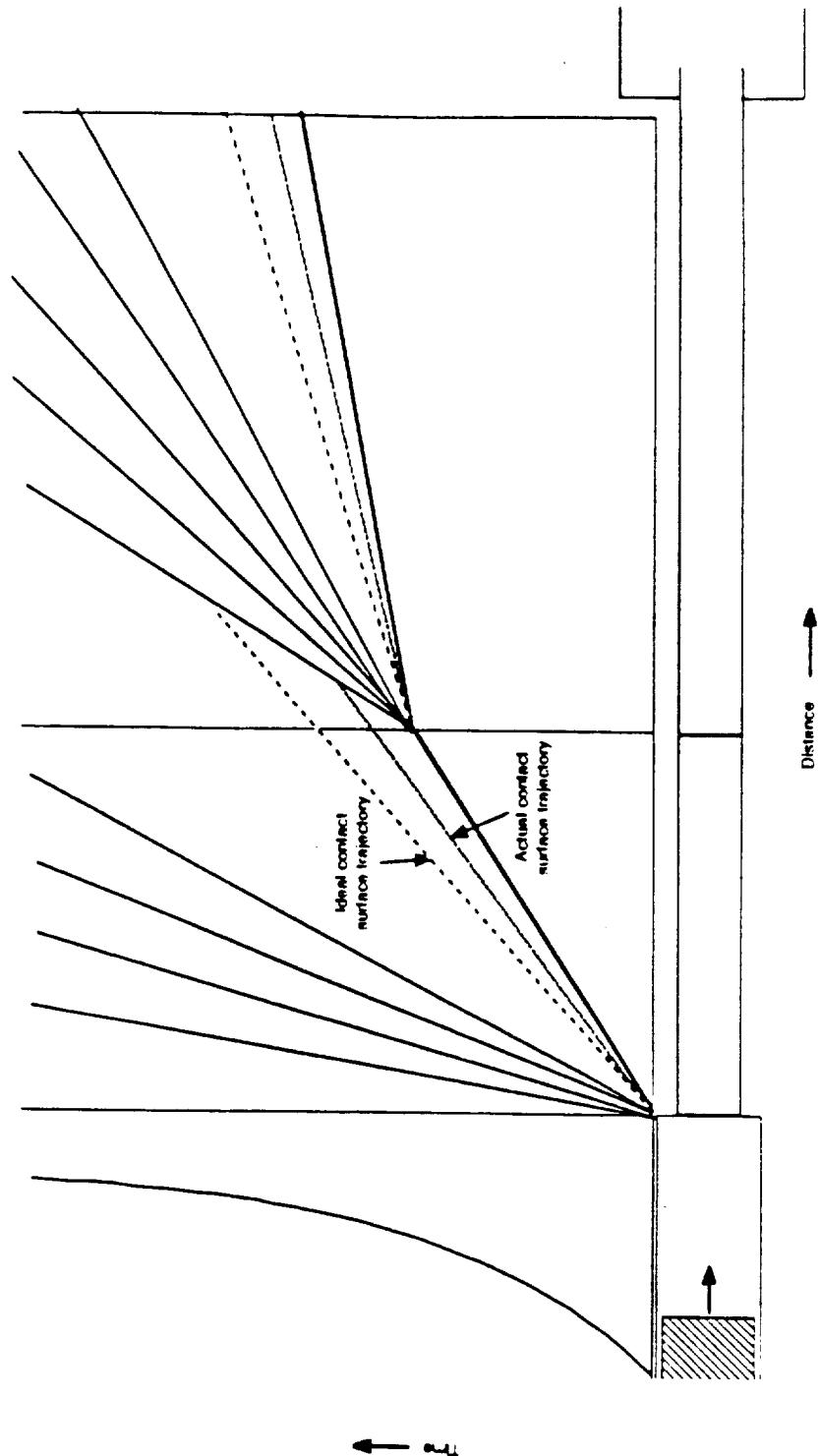


Figure 4: Entrainment effect on expansion tube flow.

ORIGINAL PAGE IS
OF POOR QUALITY

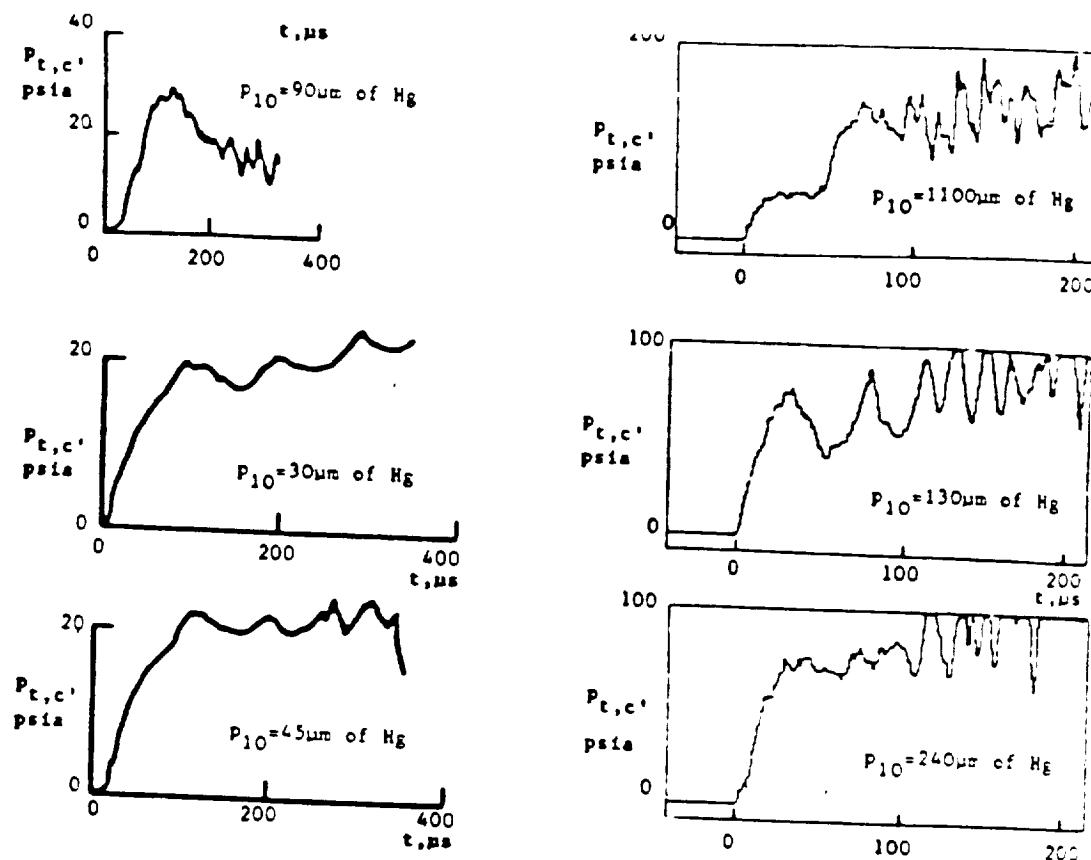
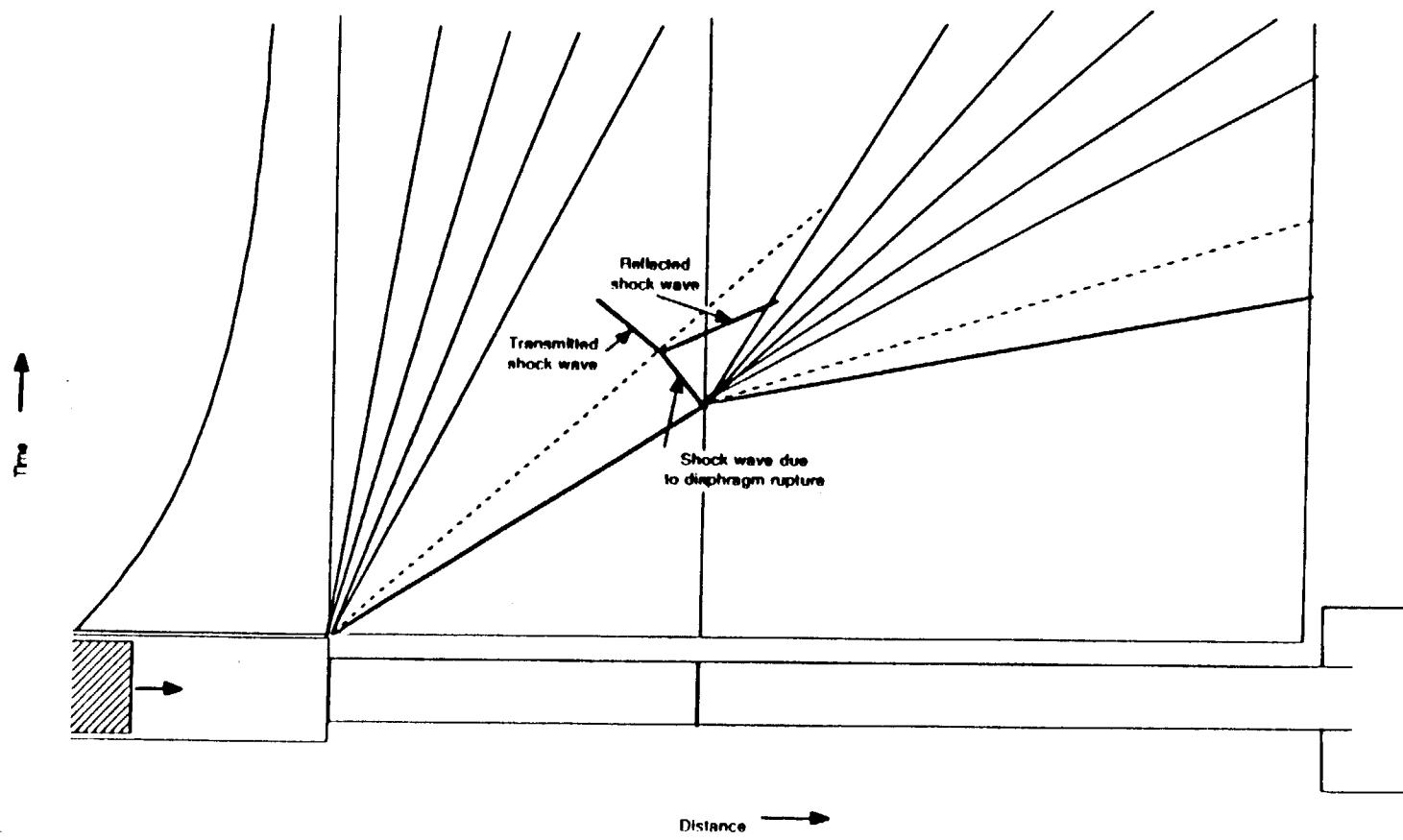


Figure 5: Typical measured pitot-pressure time-histories.

Figure 6: Shock wave generated by the secondary diaphragm



ORIGINAL PAGE IS
OF POOR QUALITY

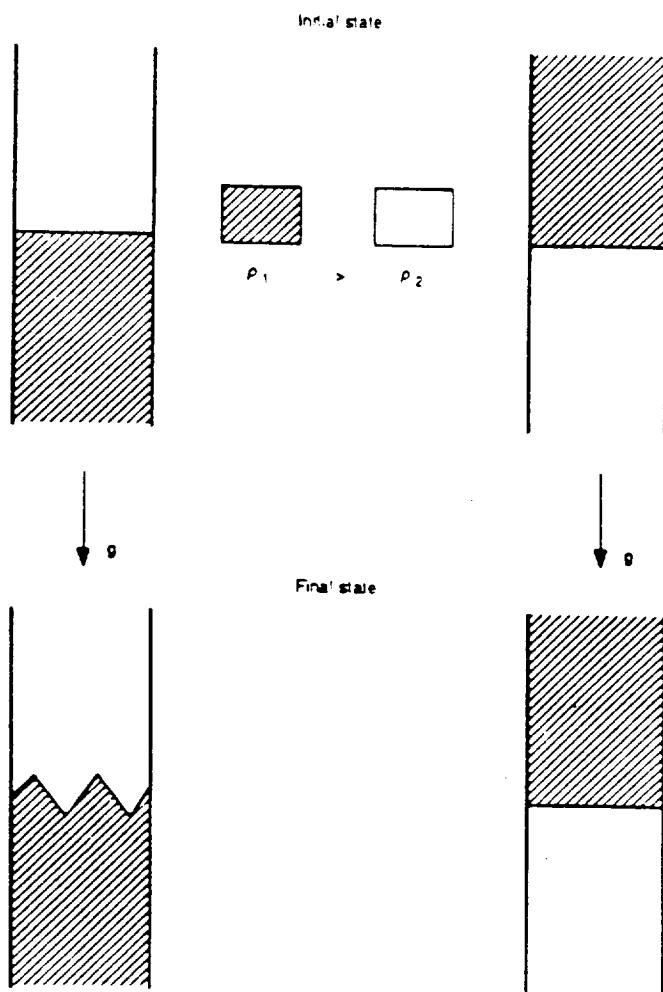


Figure 7: Rayleigh-Taylor instability of accelerated interfaces.

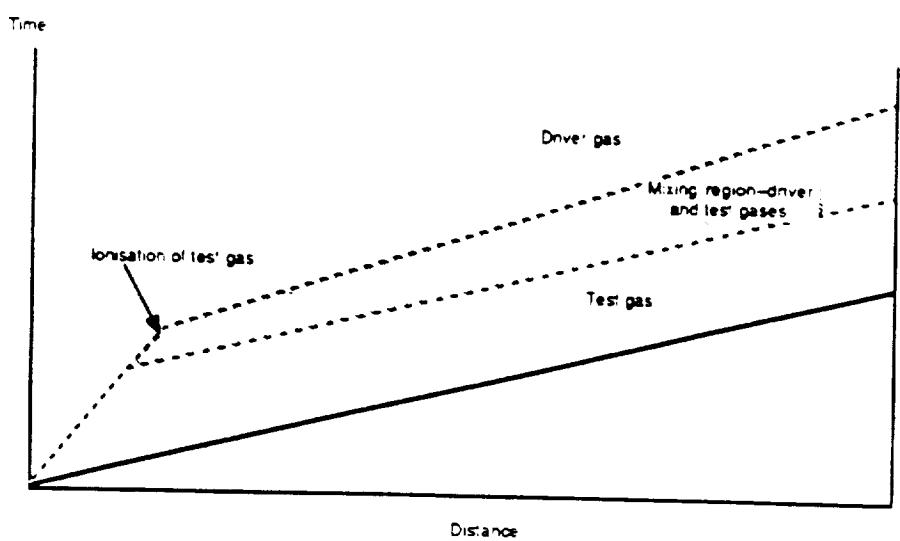


Figure 8: Wave diagram of development of mixing region.

ORIGINAL PAGE IS
OF POOR QUALITY

ORIGINAL PAGE IS
OF POOR QUALITY

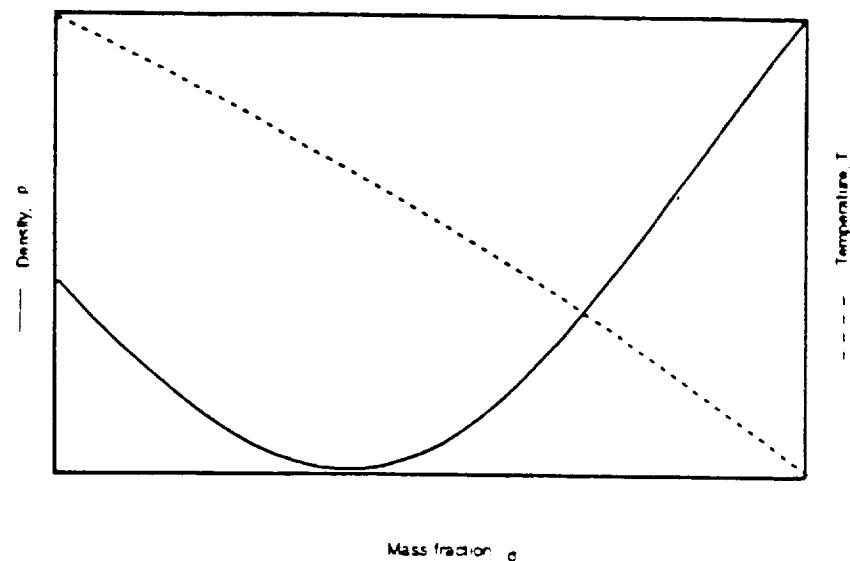
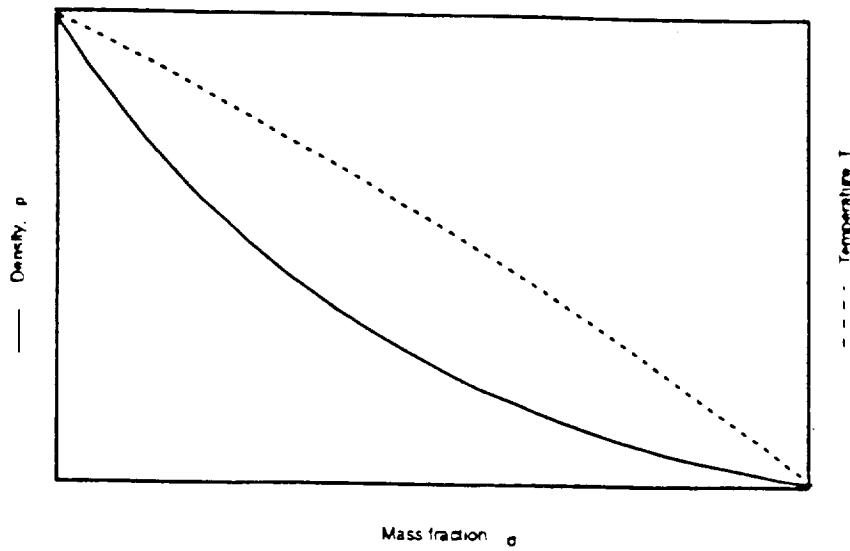


Figure 9: Profiles showing the minimum density in the mixing region.

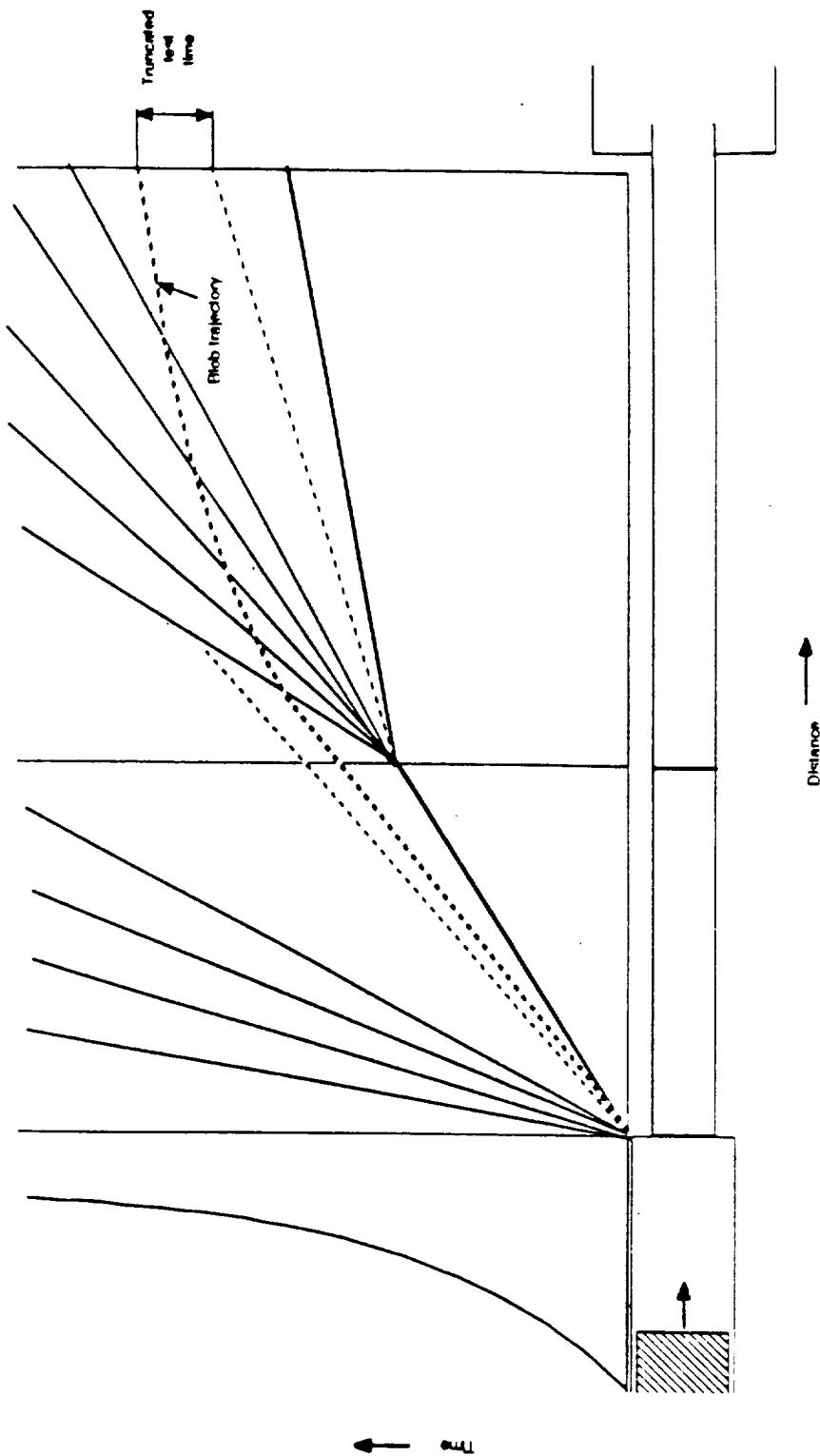


Figure 10: Wave diagram of time of arrival of tick at test section.

ORIGINAL PAGE IS
OF POOR QUALITY

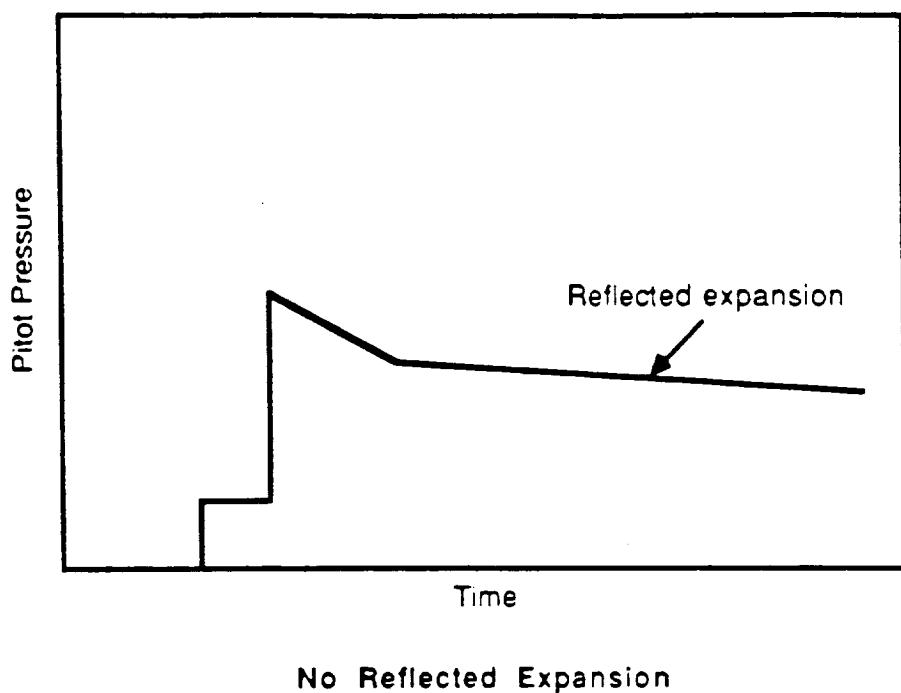


Figure 11: Ideal pitot-pressure trace showing affect of reflected head of expansion.

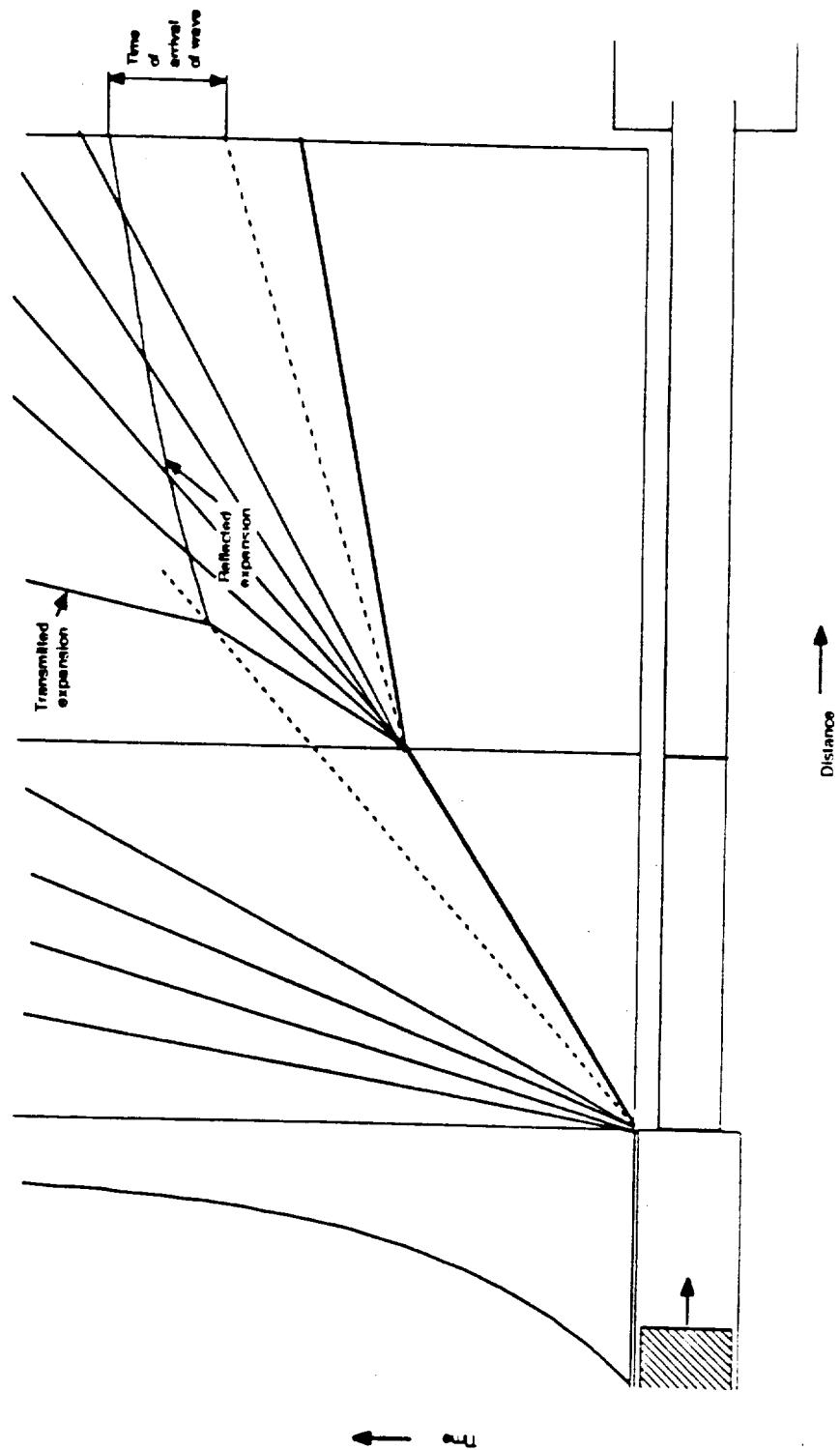


Figure 12: Wave diagram of reflected head of expansion.

OPTIONAL PAGE IS
OF POOR QUALITY

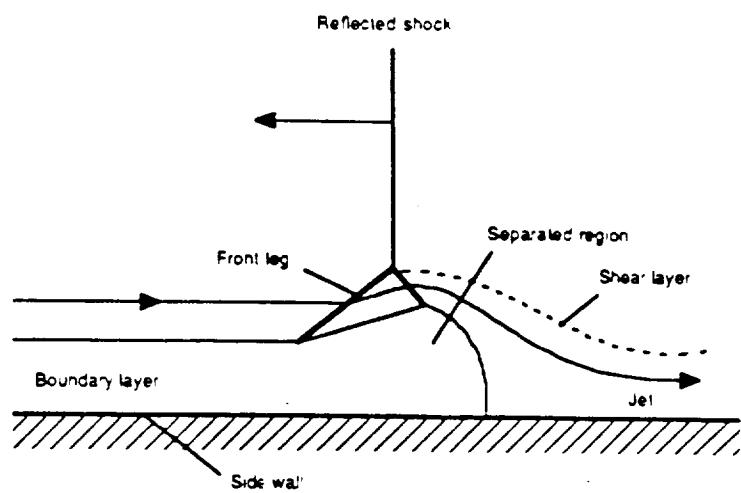


Figure 13: Reflected shock bifurcation.

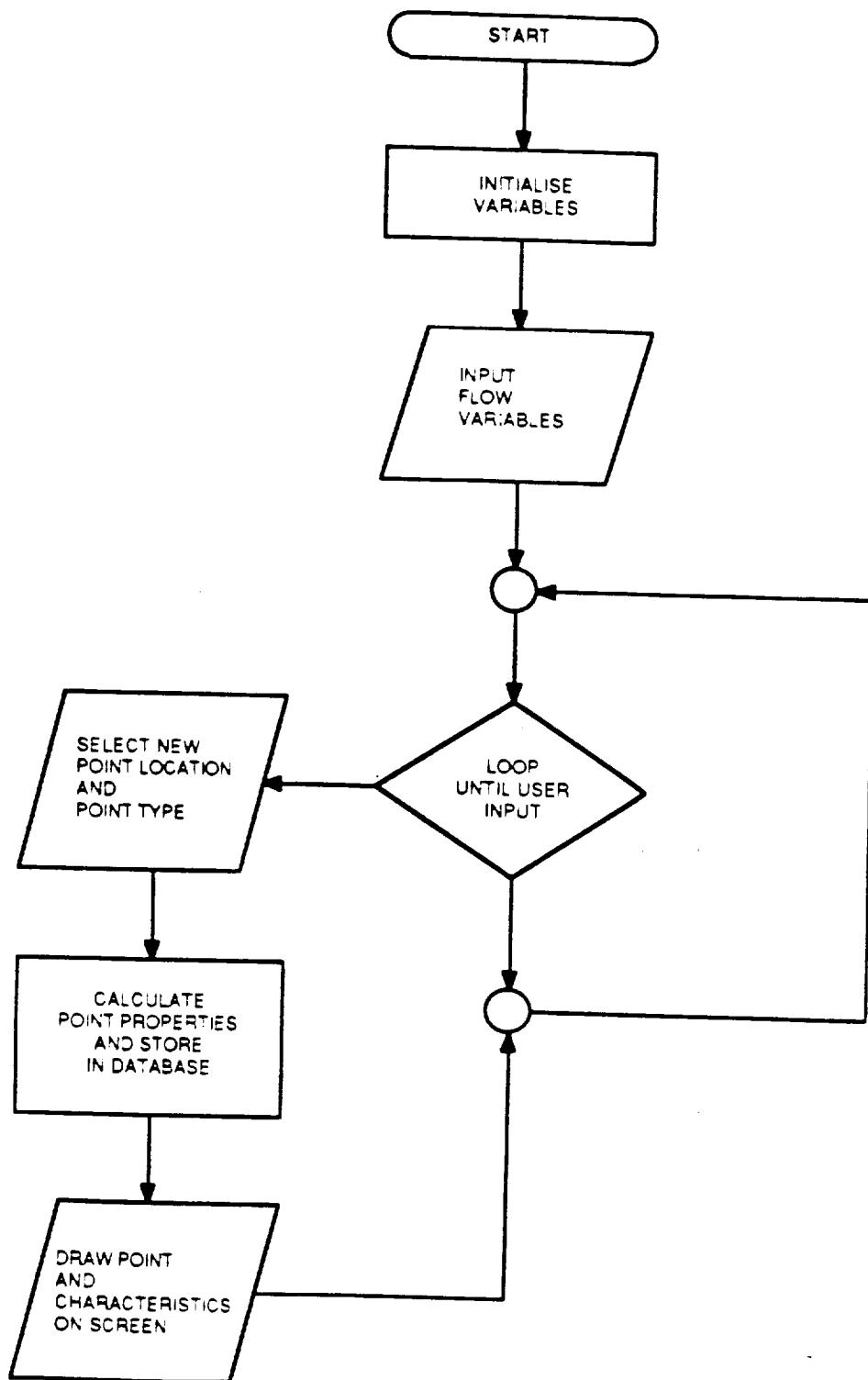


Figure 14: Computer program flow chart.

ORIGINAL PAGE IS
OF POOR QUALITY

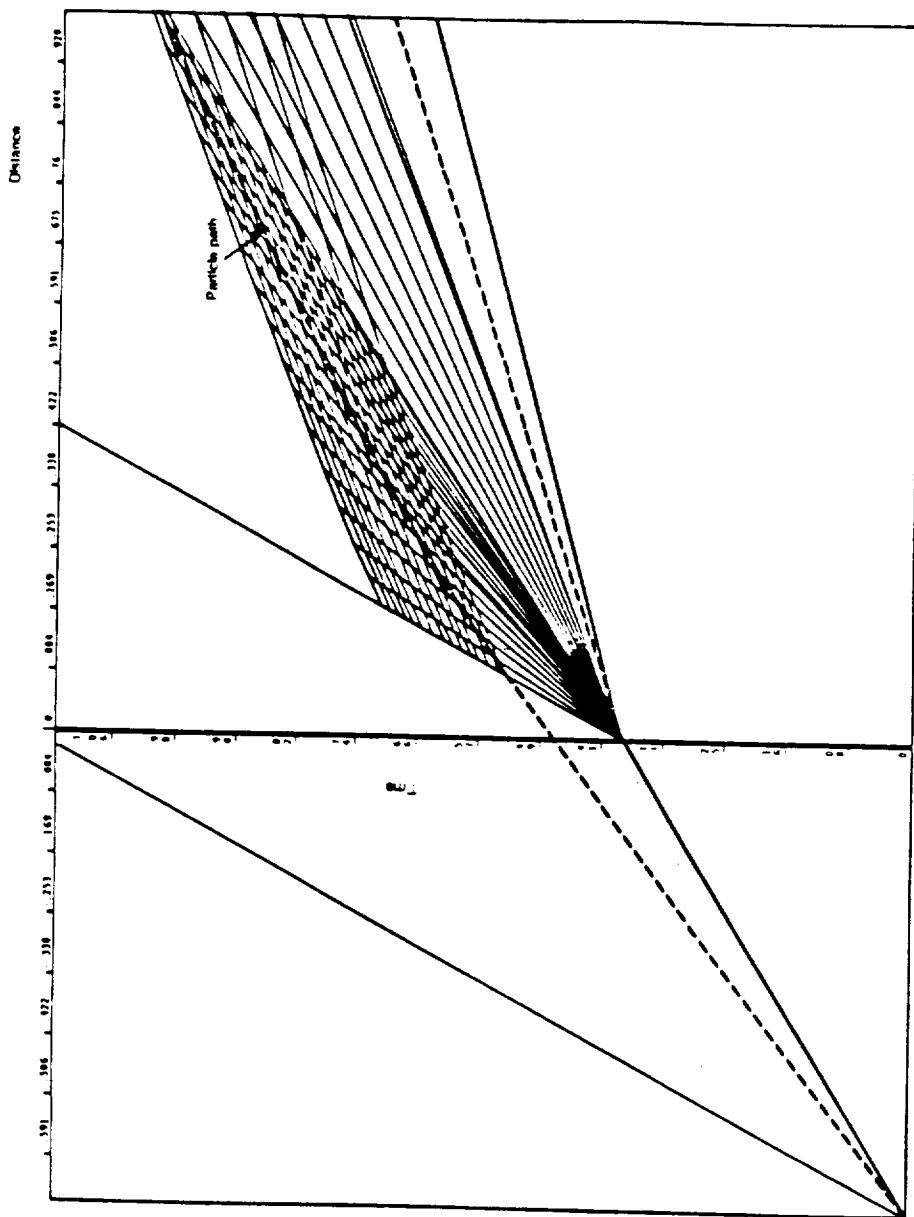
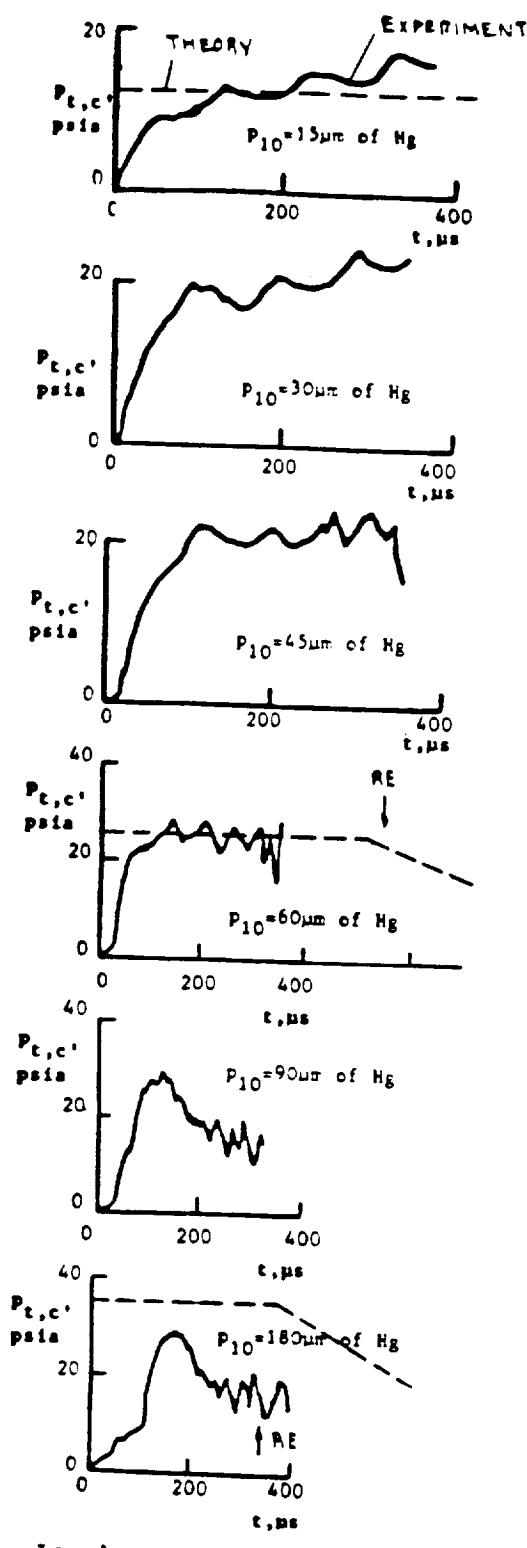


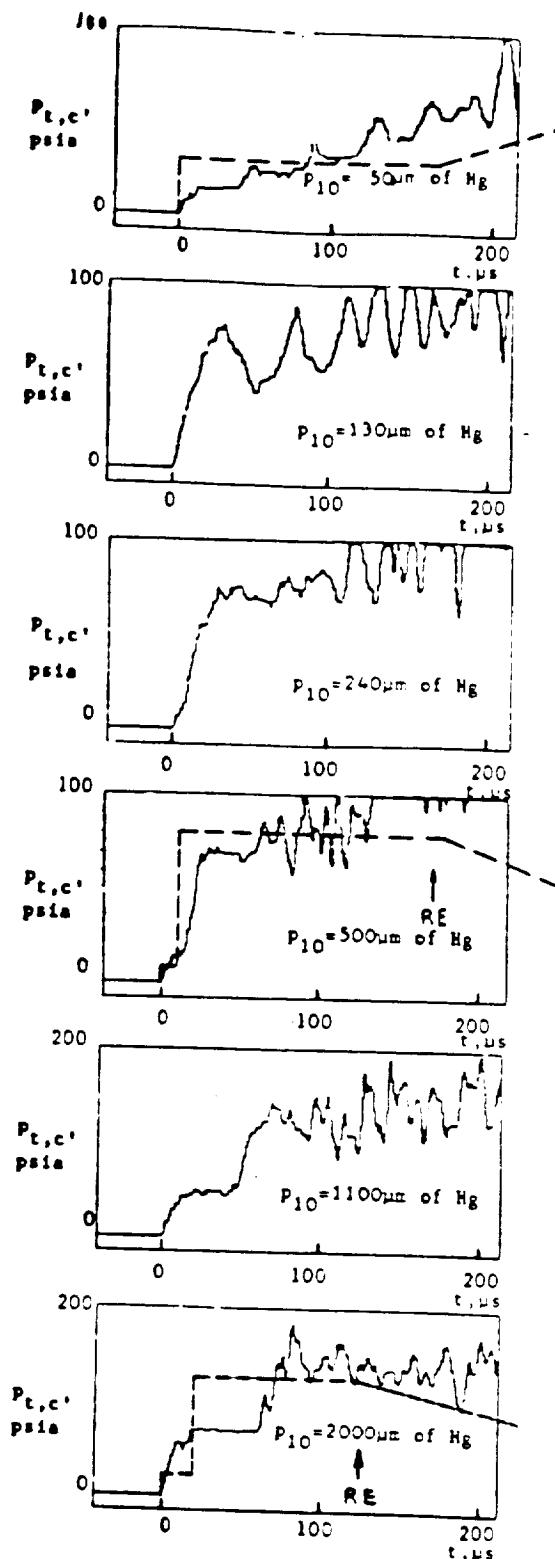
Figure 15: Analytical particle trajectory.



Langley Expansion Tube

$P_1 = 3.4 \text{ kPa}$,

Helium driver.



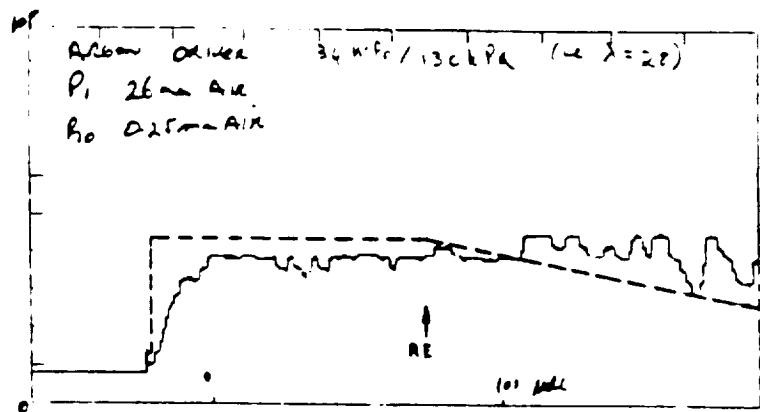
TQ Expansion Tube

$P_1 = 13.7 \text{ kPa}$,

Argon driver.

Figure 16 (a) & 17 (a): Langley (helium) and TQ (argon) Pitot-pressure and predictions. (Note 'RE' = arrival time of reflected expansion).

ORIGINAL PAGE IS
OF POOR QUALITY



'RE' = REFLECTED EXPANSION

Figure 16 (a) & 17 (a): Langley (helium) and TQ (argon)
pitot-pressures and predictions. (Note 'RE' = arrival time
of reflected expansion).

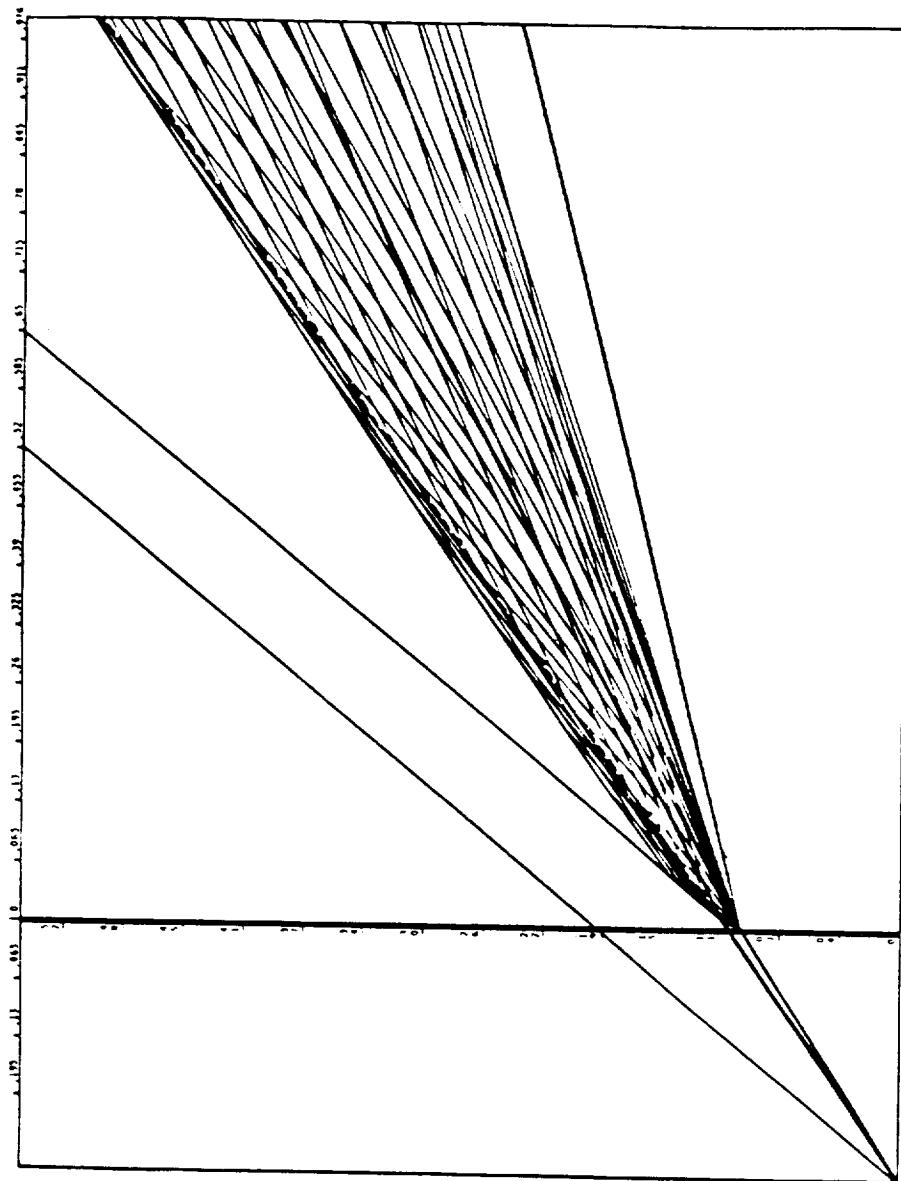


Figure 16 (b): Langley wave diagram, $p_{sc} = 15 \mu\text{m Hg}$.

ORIGINAL DRAWING
OF FIGURE 16(c)

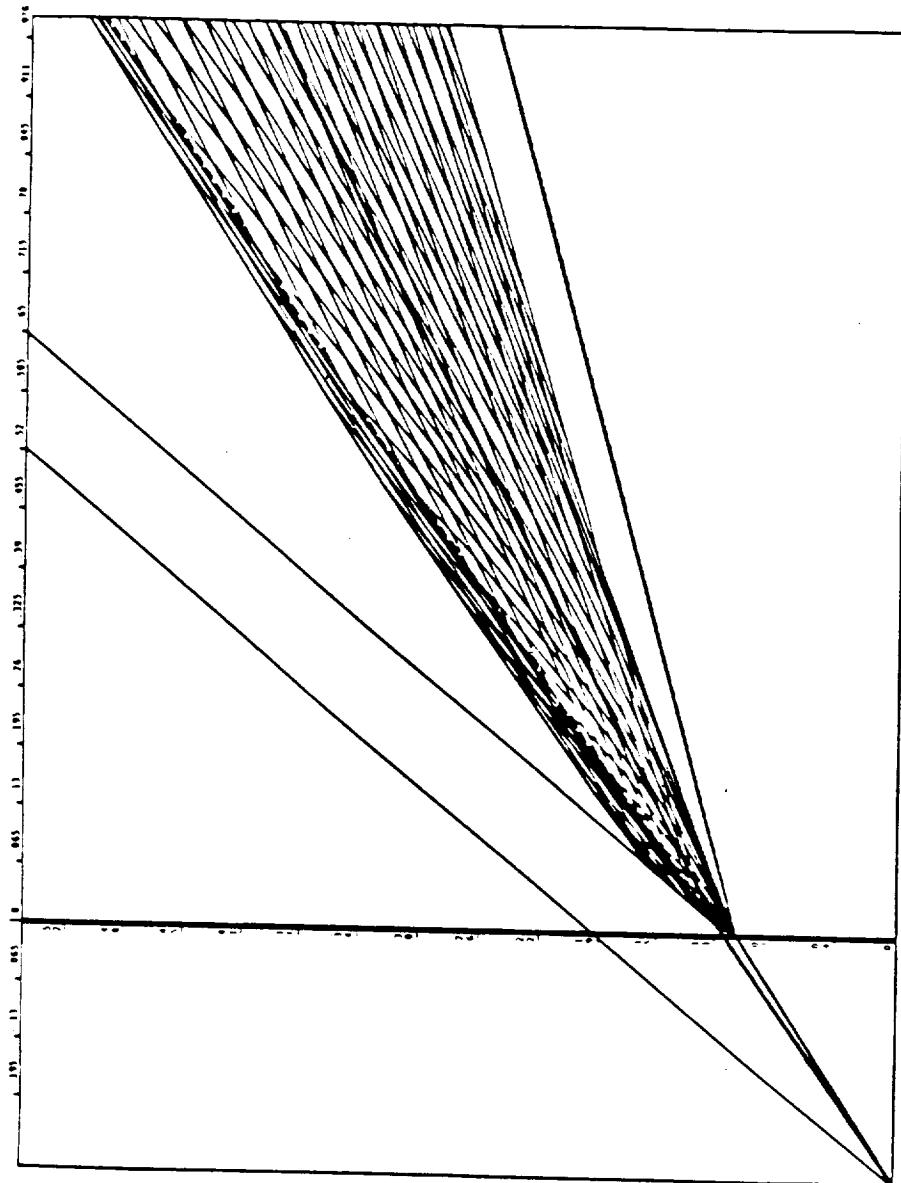


Figure 16 (c): Langley wave diagram, $p_{10} = 60 \mu\text{m Hg}$.

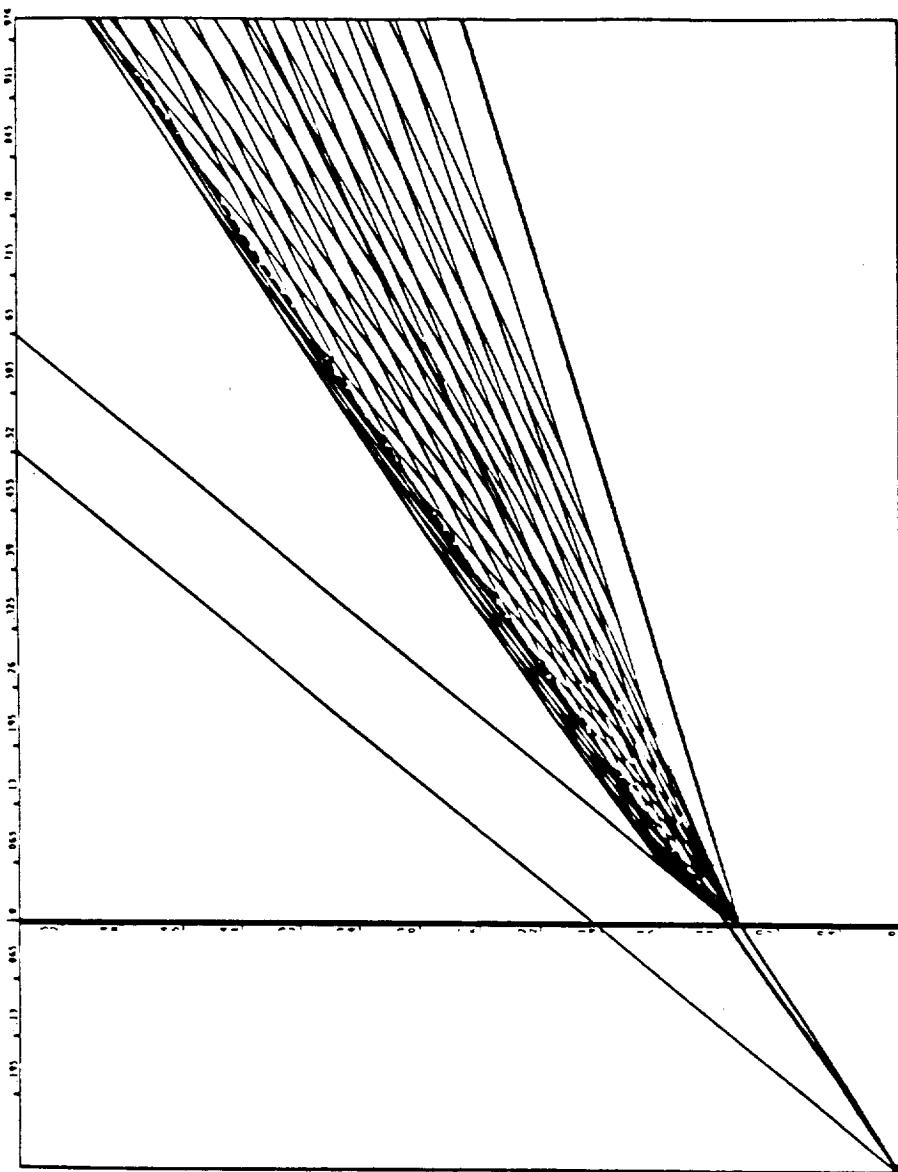


Figure 16 (d): Langley wave diagram, $p_{10} = 180 \mu\text{m Hg}$.

ORIGINAL PAGE IS
OF POOR QUALITY

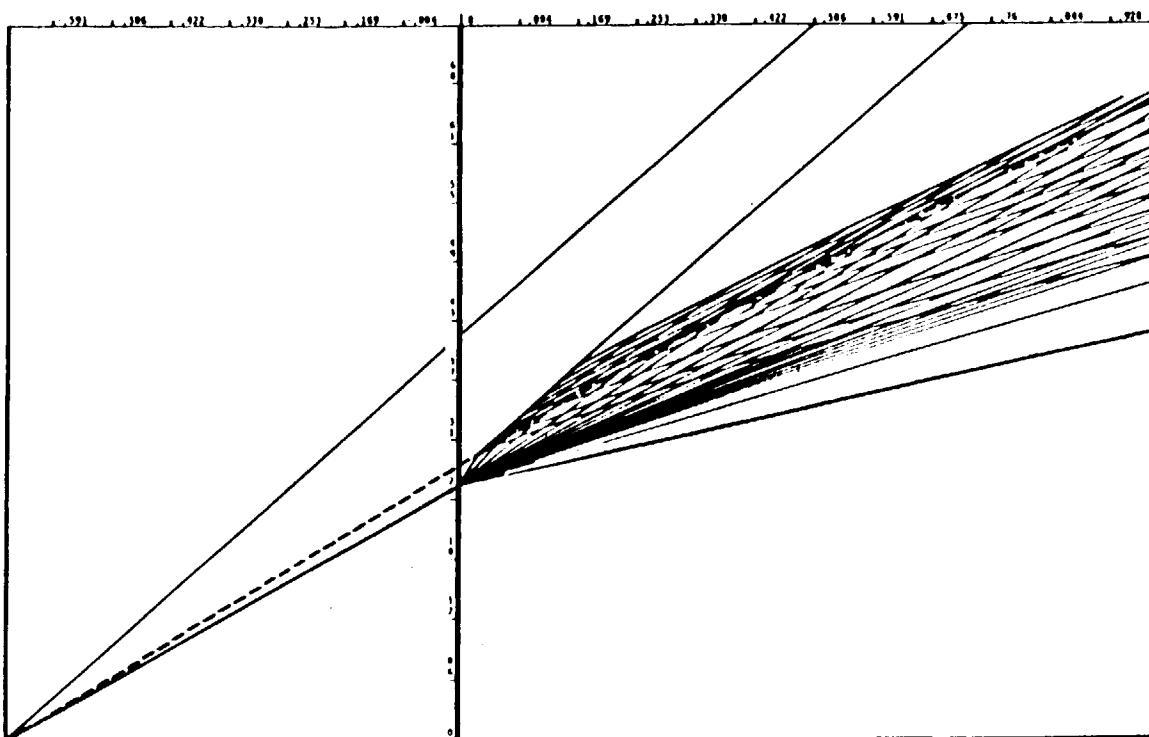


Figure 17 (b): TQ wave diagram, argon, $P_e = 13.7 \text{ kPa}$,

$P_0 = 50 \mu\text{m Hg}$.

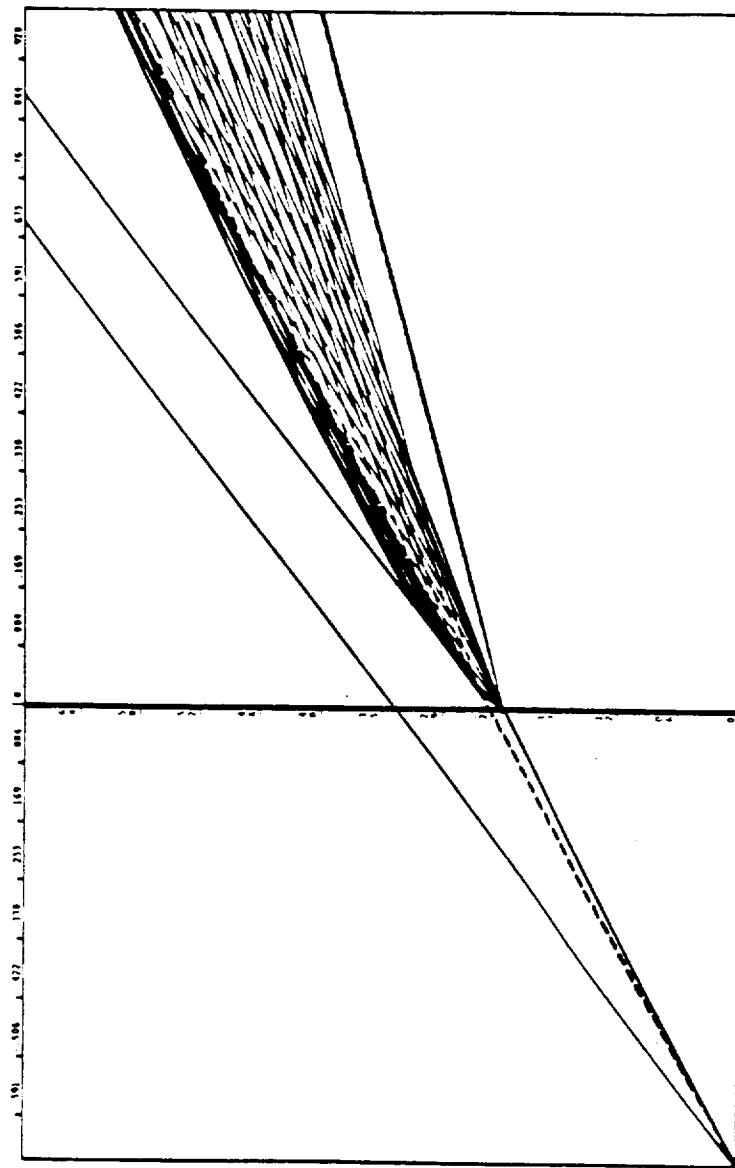


Figure 17 (c): T-Q wave diagram, argon, $p_i = 3.5$ kPa,
 $P_{tot} = 250 \mu\text{m Hg}$.

ORIGINAL PAGE IS
OF POOR QUALITY

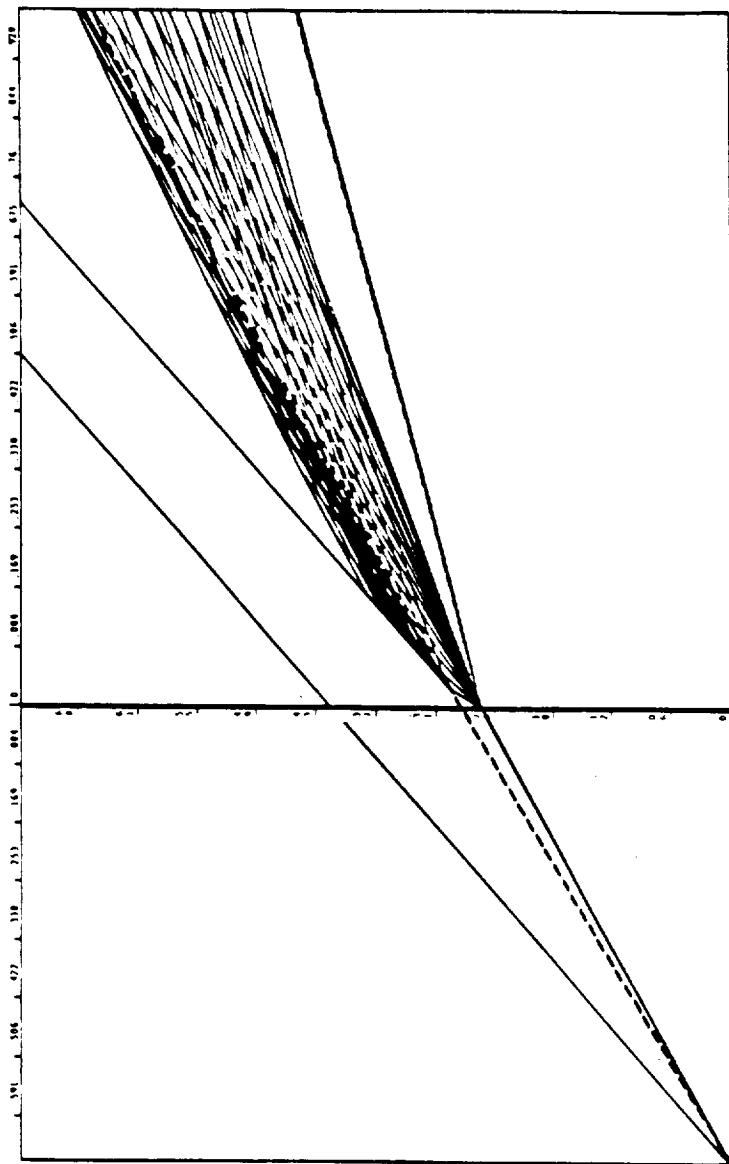


Figure 17 (d) : TQ wave diagram, argon, $p_1 = 13.7$ kPa,
 $p_{1c} = 500 \mu\text{m Hg}$.

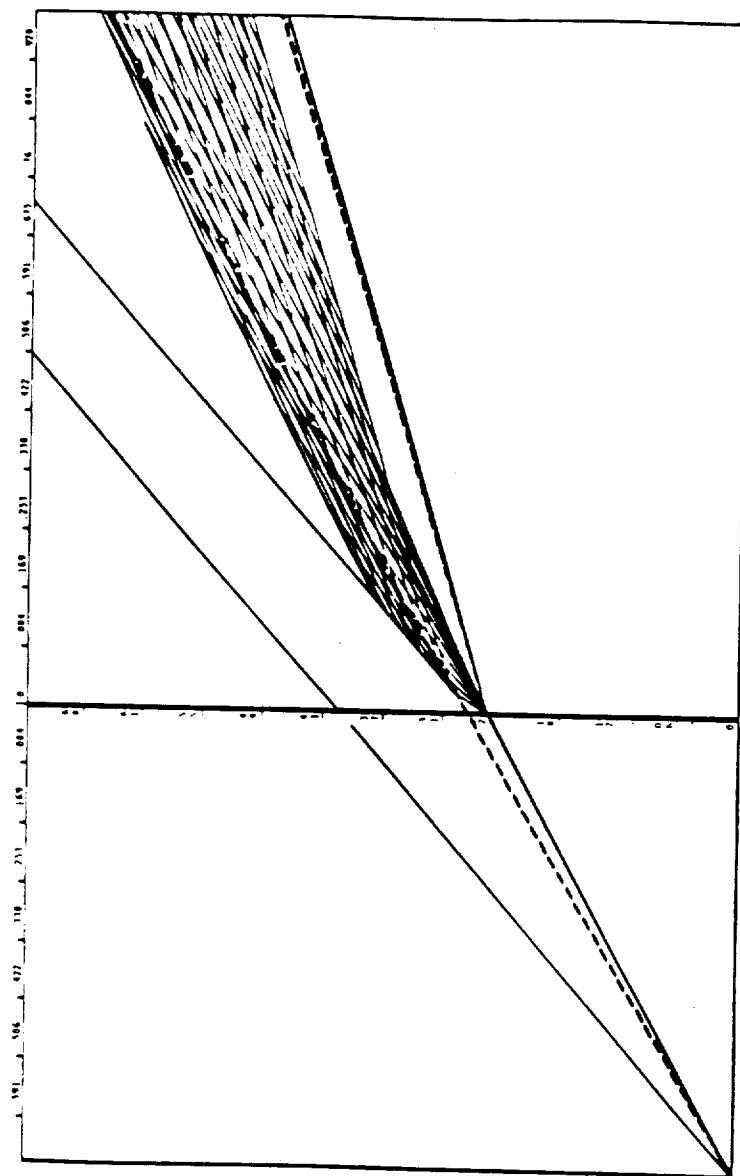
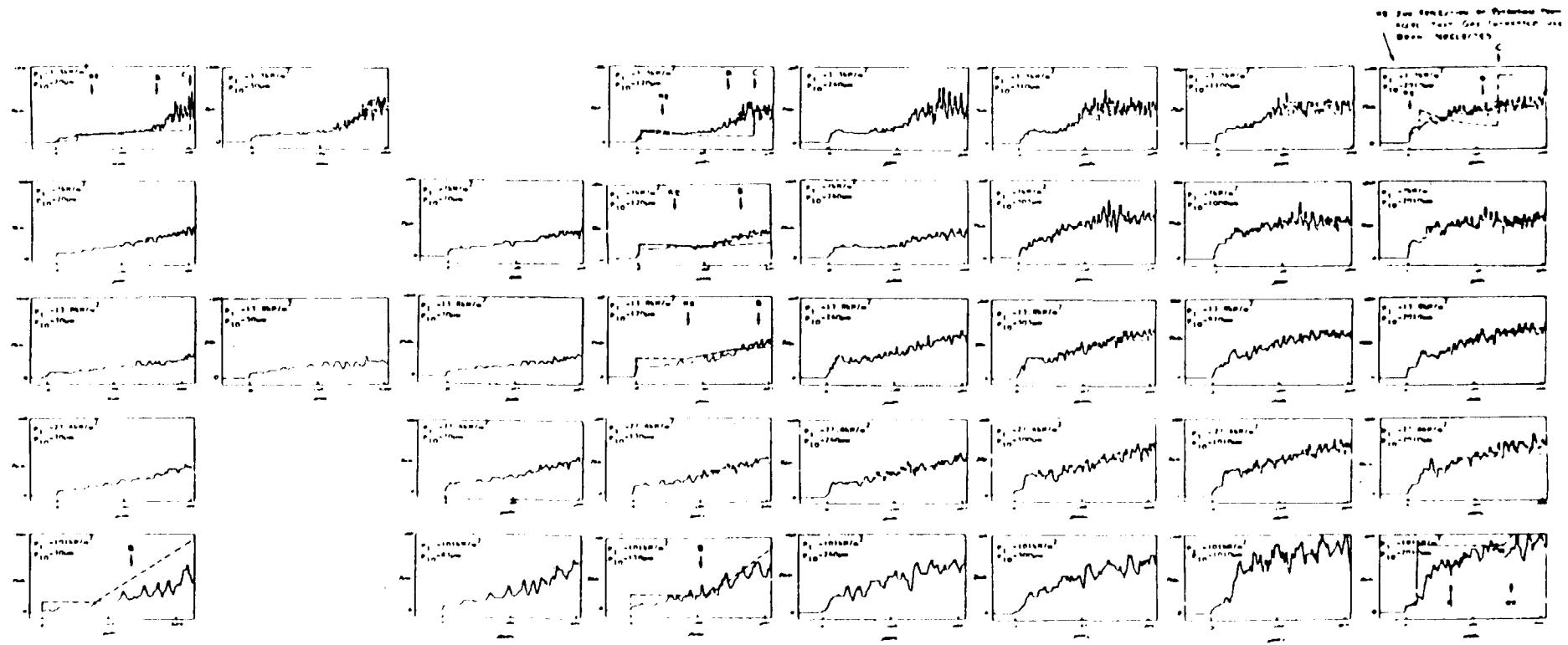


Figure 17 (e): TQ wave diagram, argon, $p_1 = 13.7$ kPa,
 $P_{IC} = 2000 \mu m$ Hg.

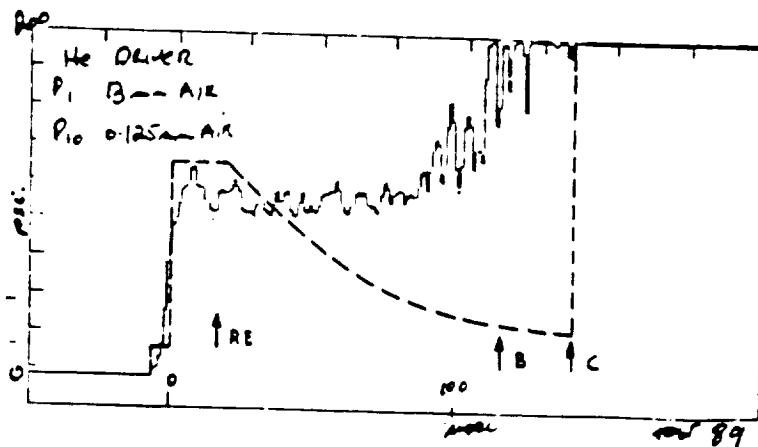


Helium driver, $\lambda = 29$, $P_r = 34.5$ MPa.

RE - REFLECTED EXPANSION
CS - CONTACT SURFACE
LG - BLOB OF LIGHT GAS

Figure 18 (a): TQ pitot pressures and predictions for helium test gas.

ORIGIN OF POINT QUALITY



'RE' = REFLECTED EXPANSION

'C' = CONTACT SURFACE

'B' = BLOB OF LIGHT GAS

**ORIGINAL PAGE IS
OF POOR QUALITY**

Figure 18 (a): TQ pitot-pressures and predictions for helium test gas.

**OPTICAL PROPERTIES
OF FLUORINE**

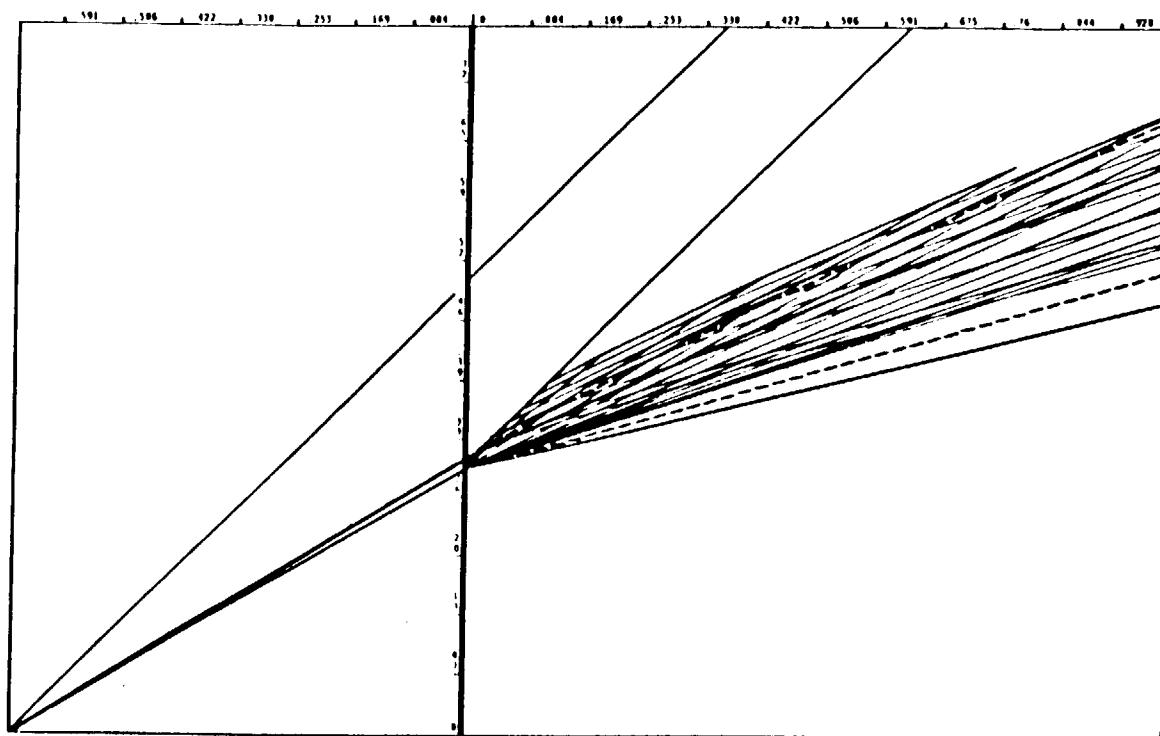


Figure 10 (b): TQ wave diagram, helium, $P_L = 3.5$ kPa,
 $P_{IC} = 20 \mu\text{m Hg}$.

ORIGINAL PAGE IS
OF POOR QUALITY

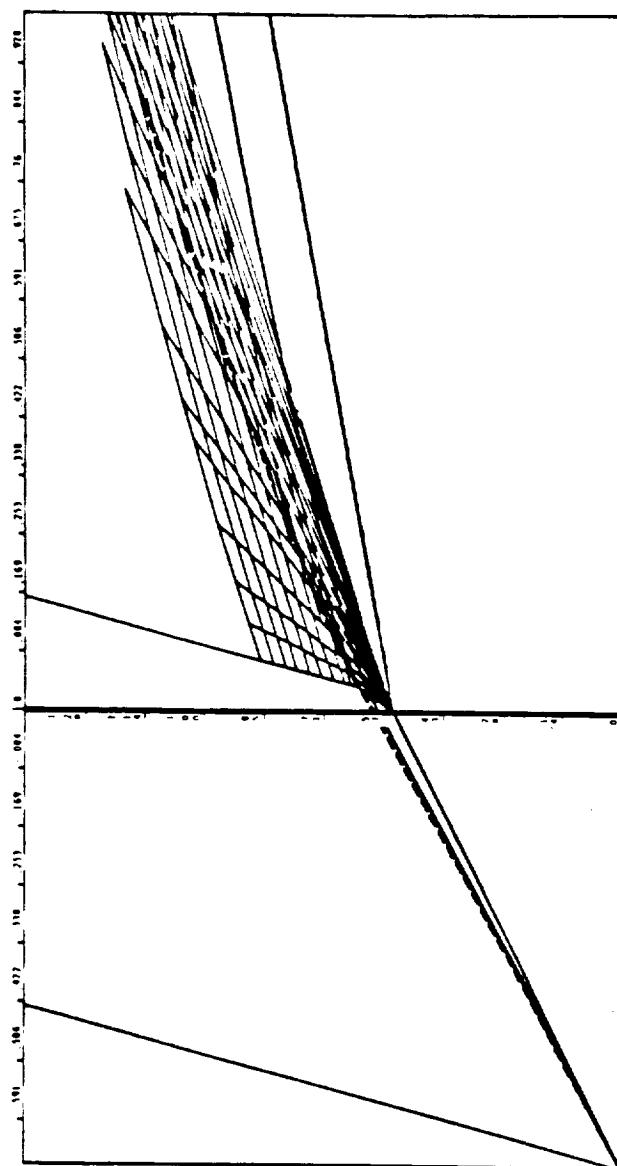


Figure 18 (c): TQ wave diagram, helium, $p_i = 101.0 \text{ kPa}$,

$P_{tc} = 30 \mu\text{m Hg}$.

ORIGINAL PAGE IS
OF POOR QUALITY

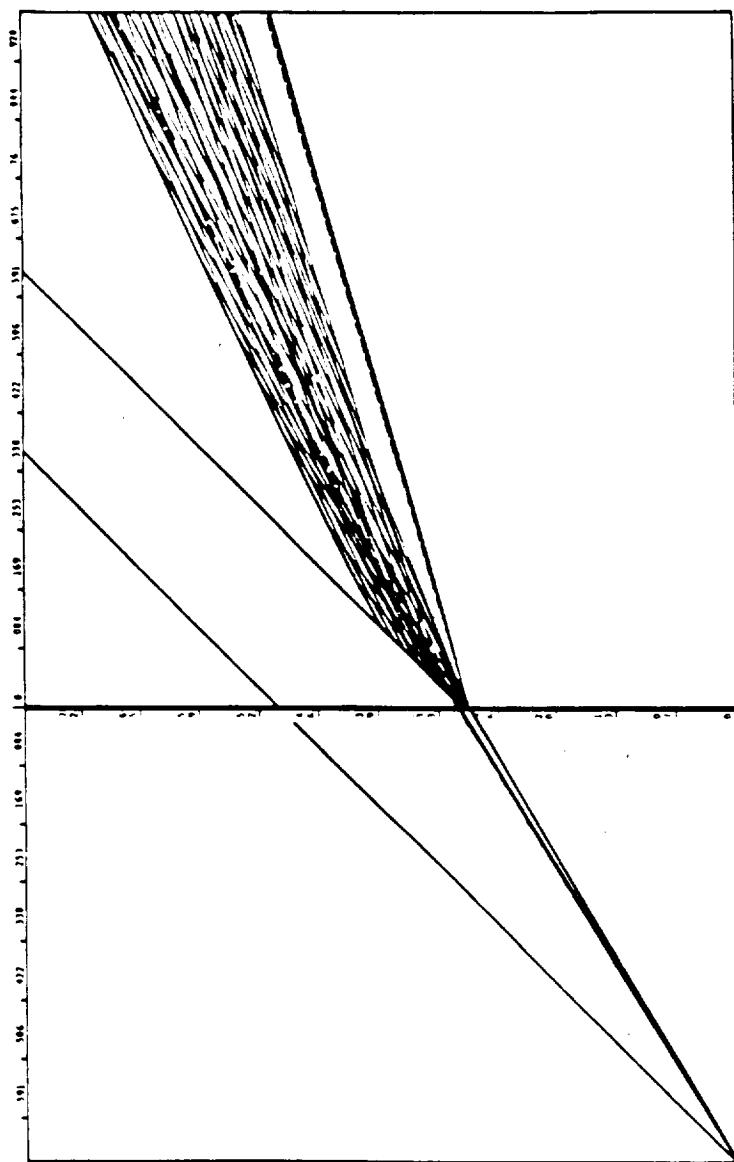


Figure 18 (e): TQ wave diagram, helium, $p_1 = 3.5 \text{ kPa}$,

$P_{dc} = 120 \mu\text{m Hg}$.

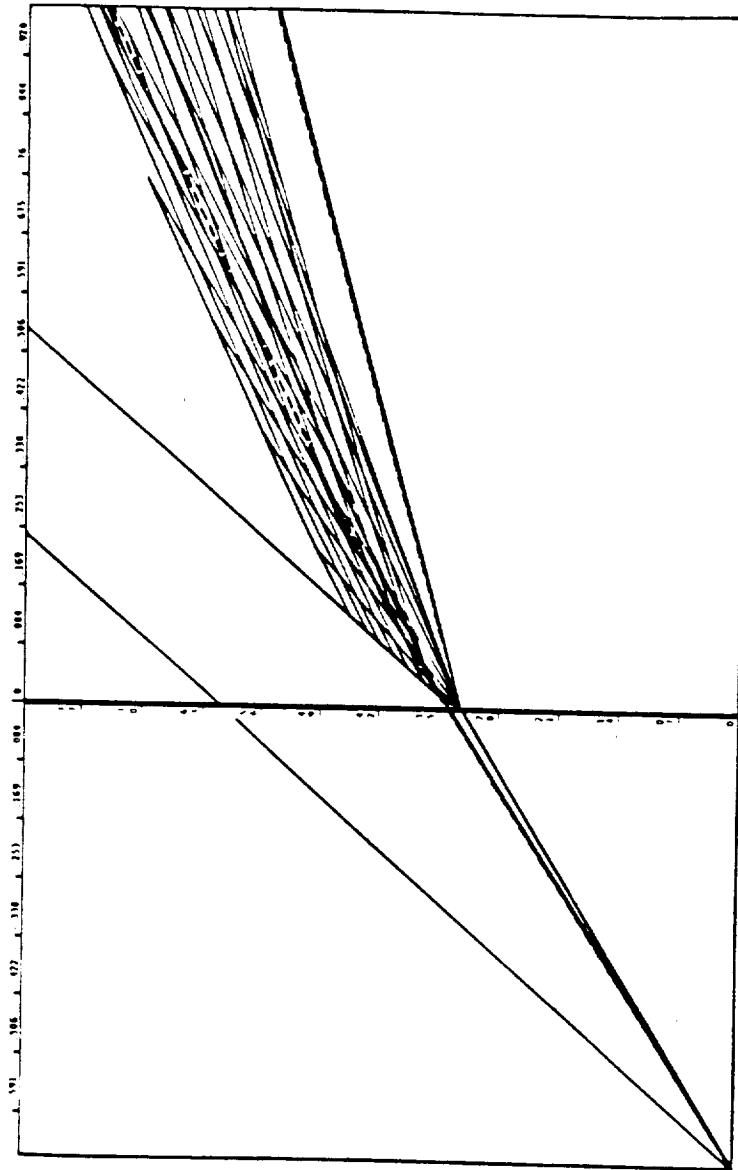


Figure 18 (f): TQ wave diagram, helium, $p_i = 7.0$ kPa,
 $P_{ext} = 120 \mu\pi$ Hg.

ORIGINAL DRAWING
OF PAPER MACHINERY

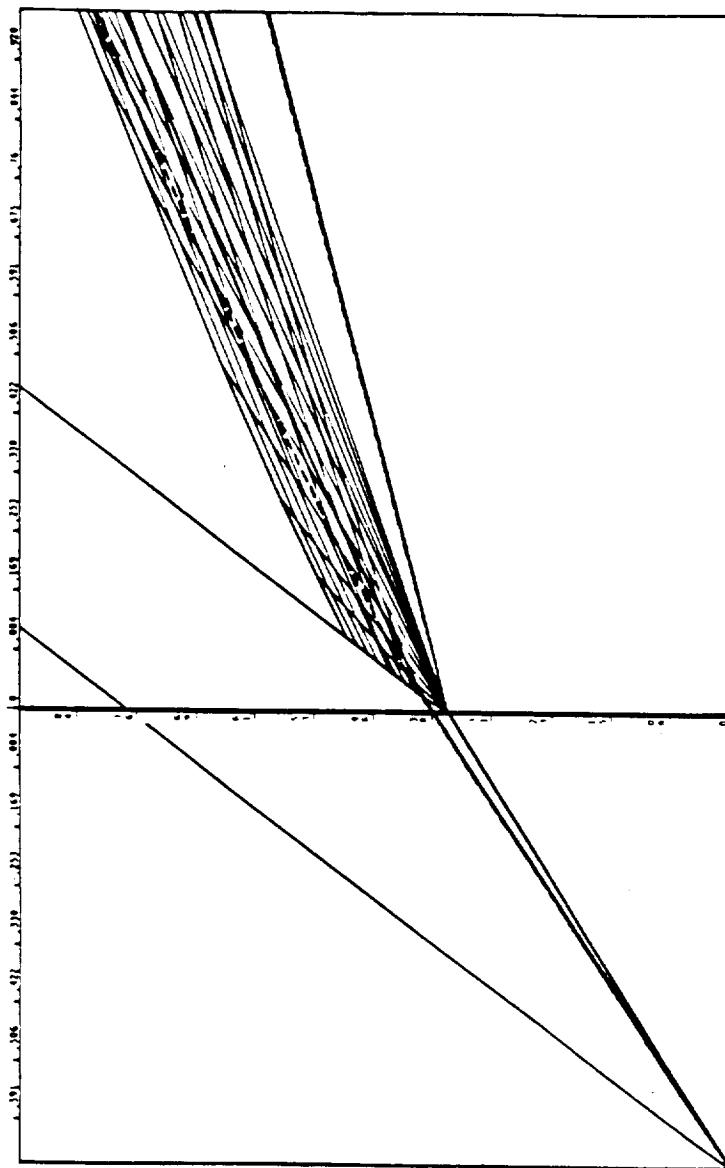


Figure 18 (g): TQ wave diagram, helium, $p_1 = 13.8$ kPa,
 $p_{1c} = 120 \mu\text{m Hg}$.

ORIGINAL PAGE IS
OF POOR QUALITY

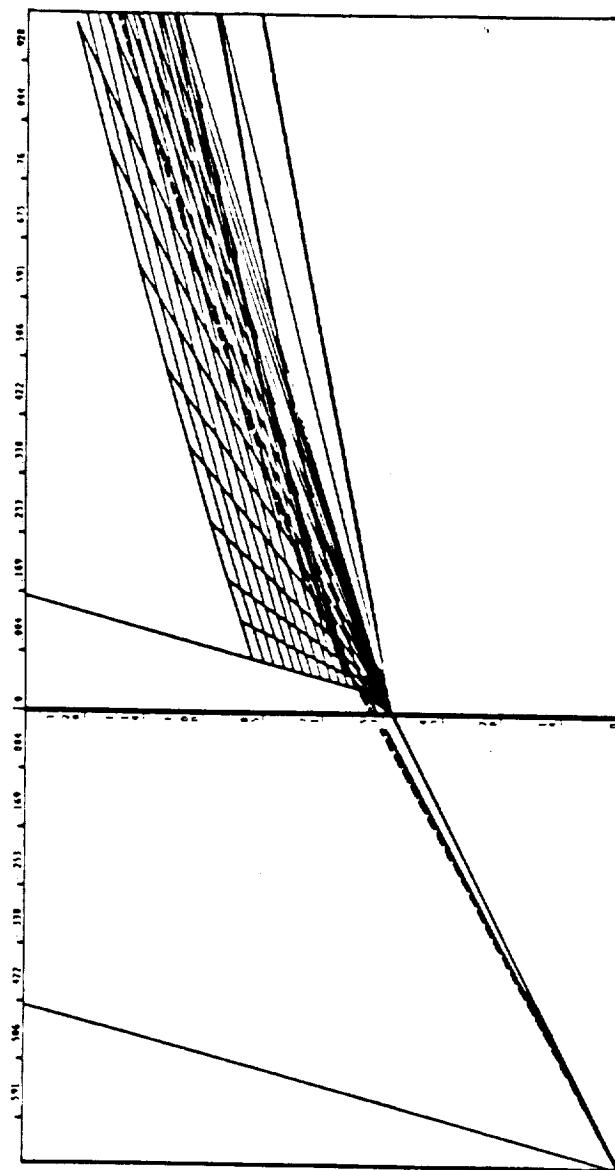


Figure 18 (b) : TQ wave diagram, helium, $p_i = 101.0 \text{ kPa}$,
 $p_{10} = 150 \mu\text{m Hg.}$

ORIGINAL PAGE OF FOON COPY

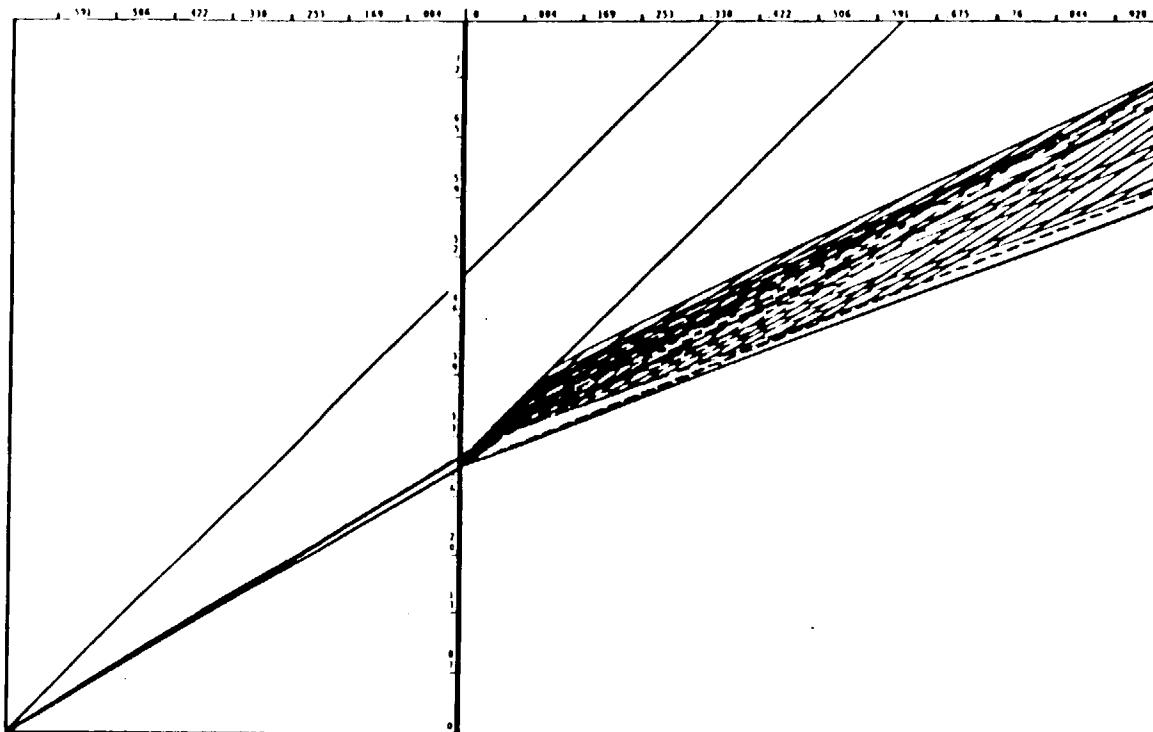


Figure 18 (4): TQ wave diagram, helium, $P_1 = 3.5$ kPa,

$P_{11} = 2010 \mu m Hg.$

ORIGINAL PAGE IS
OF POOR QUALITY

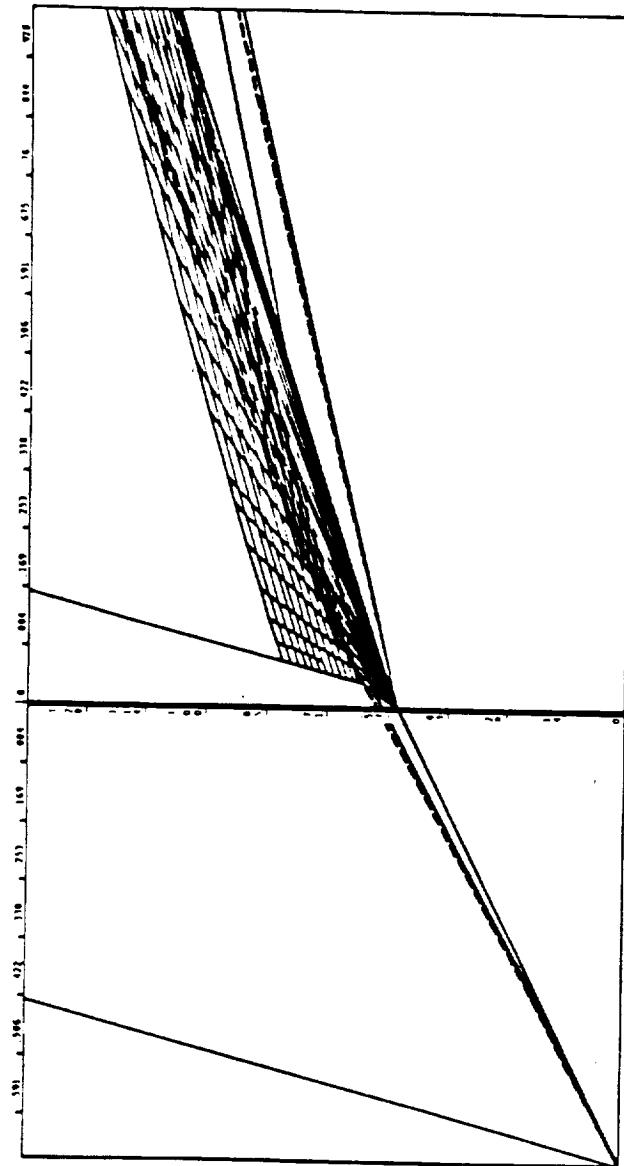
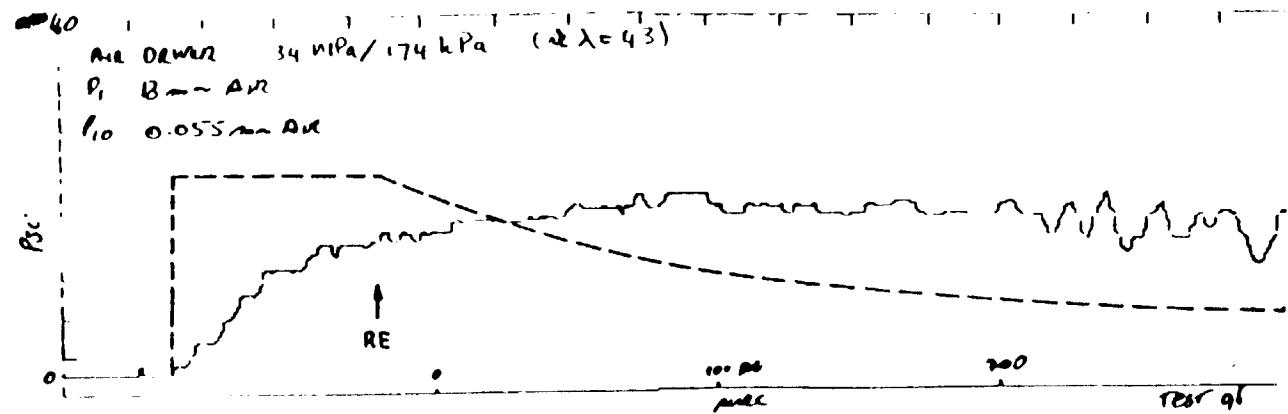


Figure 18 (j): TQ wave diagram, helium, $p_1 = 101.0 \text{ kPa}$,
 $P_{1c} = 2010 \mu\text{m Hg}$.



'RE' = REFLECTED EXPANSION

ORIGINAL PAGES
OF THIS
DOCUMENT

Figure 19 (a): T0 pitot-pressures and predictions for air test gas.

ORIGINAL PAGE IS
OF POOR QUALITY

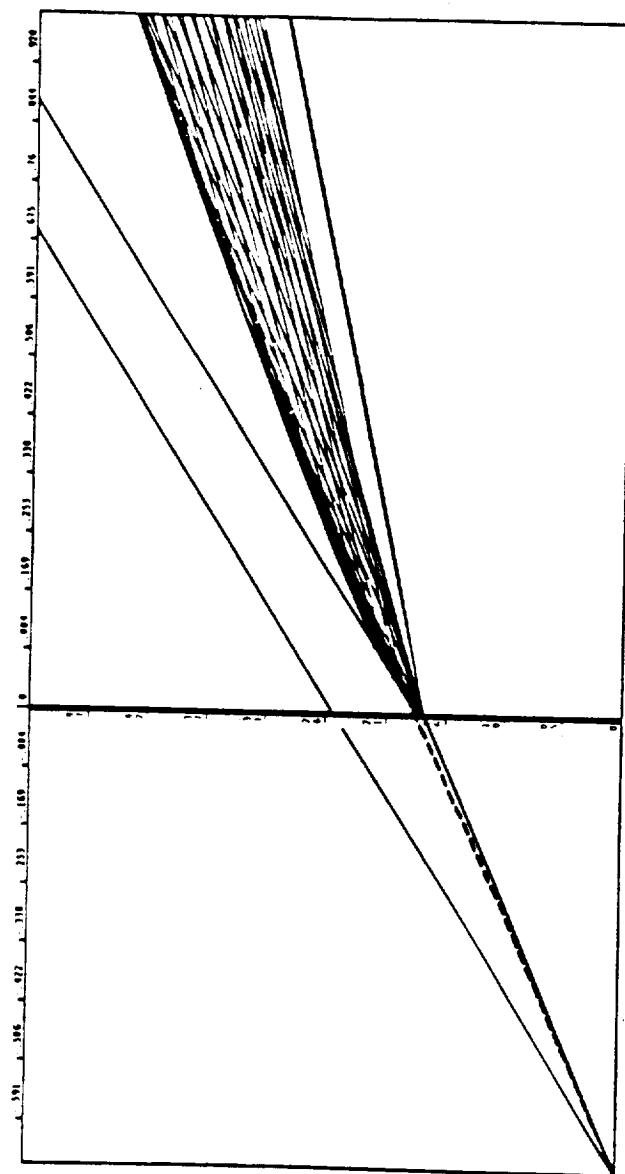


Figure 19 (b): TQ wave diagram, air.

APPENDICES

A. Complete Set of Finite Difference Equations

A.1 Non-Dimensionalisation of Variables

The reference conditions chosen for the wave diagram are the acceleration tube length, the diaphragm rupture pressure and the speed of sound in the driver gas prior to expansion.

A.2 Equations for Ideal Expansion Tube Flow

Shock Tube Section Flow

References: Stalker (1964)

Liepmann and Roskho (1957)

$$\frac{P_4}{P_1} = \frac{P_2}{P_1} \left[\sqrt{\frac{\gamma_4 + 1}{2}} - \frac{(\gamma_4 - 1)(A_1/A_4)(P_2/P_1 - 1)}{\sqrt{2\gamma_1} \sqrt{2\gamma_4 + (\gamma_4 + 1)(P_2/P_1 - 1)}} \right]^{-\frac{2\gamma_4}{\gamma_4 - 1}}$$

$$\frac{P_3}{P_4} = \frac{P_2/P_1}{P_4/P_1}$$

$$\frac{T_3}{T_4} = \left(\frac{P_3}{P_4} \right)^{\frac{\gamma_4 - 1}{\gamma_4}}$$

$$\frac{T_2}{T_1} = \frac{1 + \frac{\gamma_4 - 1}{\gamma_1} \frac{P_2}{P_1}}{1 + \frac{\gamma_4 - 1}{\gamma_1} \frac{P_1}{P_2}}$$

$$M_2 = \frac{1}{\gamma_1} \left(\frac{P_2}{P_1} - 1 \right) \left[\frac{P_2}{P_1} \left(\frac{\gamma_4 + 1}{2\gamma_1} + \frac{\gamma_4 - 1}{2\gamma_1} \frac{P_2}{P_1} \right) \right]^{-\frac{1}{2}}$$

$$M_3 = \frac{2}{\gamma_4 - 1} \left[\left(\frac{P_4/P_1}{P_2/P_1} \right)^{\frac{\gamma_4 - 1}{2\gamma_4}} \sqrt{\frac{\gamma_4 + 1}{2}} - 1 \right]$$

$$A_2 = \sqrt{\gamma_1 R_1 T_2}$$

$$A_3 = \sqrt{\gamma_4 R_4 T_3}$$

$$U_2 = M_2 a_2$$

$$U_3 = M_3 a_3$$

$$\frac{\rho_2}{\rho_1} = \frac{T_1}{T_2} \frac{P_2}{P_1}$$

$$\frac{\rho_3}{\rho_4} = \frac{T_4}{T_3} \frac{P_3}{P_4}$$

ORIGINAL PAGE IS
OF POOR QUALITY

Reference: Liepmann and Roskho (1957)

$$\frac{P_2}{P_{10}} = \frac{P_{20}}{P_{10}} \left[1 + \frac{\gamma - 1}{2} M_2 - \frac{(\gamma - 1)(A_{10}/A_2)(p_{20}/p_{10} - 1)}{\sqrt{2\gamma} \sqrt{2\gamma_1 + (\gamma_1 + 1)(p_{20}/p_{10} - 1)}} \right]^{\frac{-2\gamma}{\gamma - 1}}$$

$$\frac{P_5}{P_2} = \frac{P_{20}/P_{10}}{P_2/P_{10}}$$

$$\frac{T_5}{T_2} = \left(\frac{P_5}{P_2} \right)^{\frac{\gamma-1}{\gamma}}$$

$$\frac{T_{20}}{T_{10}} = \frac{1 + \frac{\gamma - 1}{\gamma_1 + 1} \frac{P_{20}}{P_{10}}}{1 - \frac{\gamma - 1}{\gamma_1 + 1} \frac{P_{20}}{P_{10}}}$$

$$M_{20} = \frac{1}{\gamma} \left(\frac{P_{20}}{P_{10} - 1} \right) \left[\frac{P_{20}}{P_{10}} \left(\frac{\gamma_1 + 1}{2\gamma_1} + \frac{\gamma - 1}{2\gamma_1} \frac{P_{20}}{P_{10}} \right) \right]^{-\frac{1}{2}}$$

$$M_5 = \frac{2}{\gamma_1 - 1} \left[\left(\frac{P_2/P_{10}}{P_{20}/P_{10}} \right)^{\frac{\gamma-1}{2\gamma_1}} \left(1 + \frac{\gamma - 1}{2} M_2 \right) - 1 \right]$$

$$A_{20} = \sqrt{\gamma_1 R_1 T_{20}}$$

$$A_5 = \sqrt{\gamma_1 R_1 T_5}$$

$$U_{20} = M_{20} a_{20}$$

$$U_5 = M_5 a_5$$

$$\frac{\rho_{20}}{\rho_{10}} = \frac{T_{10}}{T_{20}} \frac{P_{20}}{P_{10}}$$

$$\frac{\rho_5}{\rho_2} = \frac{T_2}{T_5} \frac{P_5}{P_2}$$

A.3 Mirels Effect for Laminar or Turbulent Boundary Layers

Laminar

Reference: Mirels (1963)

The acceleration tube flow is laminar for TQ and partly laminar for Langley. Therefore assume that the maximum separation of the shock and the contact surface has been reached. This only has a cosmetic effect on the wave diagram in the acceleration tube region. It does not affect the results. The effect on the test gas, and blobs, is difficult to determine

ORIGINAL PAGE IS
OF POOR QUALITY

due to the expansion wave thickness and the complex nature of the boundary layer (see Mirels and Mullen, 1964).

$$\frac{l_{m2}}{L_2} = \left(\frac{1}{4\beta_1} \right)^2 \frac{P_{10}}{P_{20}} \frac{\rho_{20}/\rho_{10}}{\rho_{20}/\rho_{10} - 1} M_{s20} \frac{\rho_1 a_1}{\mu_1} \left(\frac{d}{L_2} \right)^2 \frac{P_{10}}{P_1} \frac{P_1}{P_4} \frac{P_4}{P_{st}}$$

$$M_{s0} = u_{s20} \sqrt{\frac{\gamma_4 R_4 T_4}{\gamma_1 R_1 T_1}}$$

| M_s | β_1 (Air) |
|-------|-----------------|
| 6 | 0.0283 |
| 8 | 0.0220 |
| 10 | 0.0188 |
| 12 | 0.0157 |
| 14 | 0.0129 |
| 16 | 0.0116 |
| 18 | 0.0104 |
| 20 | 0.0094 |

$$-\frac{x_2}{2} = \ln (1 - T_2^n) + T_2^n, \quad n = \frac{1}{2}$$

$$x_2 = \frac{u_{s20} t}{(\rho_{20}/\rho_{10}) l_{m2}}$$

$$T_2 = \frac{l_2}{l_{m2}}$$

$$\begin{aligned} \ln \left\{ 1 - \left[\frac{u_{s20} \left(t_{G2} - \frac{1}{u_{s2}} \frac{L_1}{L_2} \right) - 1}{l_{m2}} \right]^{1/2} \right\} + \left[\frac{u_{s20} \left(t_{G2} - \frac{1}{u_{s2}} \frac{L_1}{L_2} \right) - 1}{l_{m2}} \right]^{1/2} \\ + \frac{u_{s20} \left(t_{G2} - \frac{1}{u_{s2}} \frac{L_1}{L_2} \right) \rho_{10}}{2 l_{m2} \rho_{20}} = 0 \end{aligned}$$

The limiting separation approximation used in the acceleration tube is given by,

$$t_{G2} = \frac{l_{m2} + 1}{u_{s20}} + \frac{1}{u_{s2}} \frac{L_1}{L_2}$$

Turbulent

Reference: Mirels (1964)

ORIGINAL PAGE IS
OF POOR QUALITY

The shock tube flow is turbulent. The Mirels effect also effects the blob trajectory. The limiting separation is not reached in the shock tube length.

$$\frac{l_m}{L_2} = \left(\frac{1}{4\beta_1} \right)^{5/4} \frac{P_1}{P_2} \frac{\rho_2/\rho_1}{\rho_2/\rho_1 - 1} M_s^{1/4} \left(\frac{\rho_1 A_2}{\mu_1} \right)^{1/4} \left(\frac{d}{L_2} \right)^{5/4} \left(\frac{P_1}{P_4} \frac{P_4}{P_{st}} \right)^{1/4}$$

$$M_s = u_{s2} \sqrt{\frac{\gamma_1 R_1 T_1}{\gamma_2 R_2 T_2}}$$

$$\beta_1 = \beta_0 \left(\frac{(\rho_2/\rho_1)^2 + 1.25(\rho_2/\rho_1) - 0.80}{(\rho_2/\rho_1)((\rho_2/\rho_1) - 1)} \right)$$

| M_s | β_0 (Air |
|-------|---------------------------|
| | $P_1 = 0.5 \text{ cm Hg}$ |
| 6 | 0.0283 |
| 8 | 0.0220 |
| 10 | 0.0188 |
| 12 | 0.0157 |
| 14 | 0.0129 |
| 16 | 0.0116 |
| 18 | 0.0104 |
| 20 | 0.0094 |

$$-\frac{x}{l_m} = \frac{5}{8} \left(\ln \frac{1 - T^n}{1 + T^n} - 2 \arctan T^n + 4T^n \right), \quad n = \frac{1}{5}$$

$$x = \frac{u_{s2} t}{(\rho_2/\rho_1) l_m}$$

$$T = \frac{t}{l_m}$$

$$\begin{aligned} \frac{5}{8} \left(\ln \left\{ \frac{1 - \left[\frac{x_G}{l_m} \left(\frac{u_{s2}}{U_2 - A_2} - 1 \right) \right]^{1/5}}{1 + \left[\frac{x_G}{l_m} \left(\frac{u_{s2}}{U_2 - A_2} - 1 \right) \right]^{1/5}} \right\} - 2 \arctan \left[\frac{x_G}{l_m} \left(\frac{u_{s2}}{U_2 - A_2} - 1 \right) \right]^{1/5} \right. \\ \left. + 4 \left[\frac{x_G}{l_m} \left(\frac{u_{s2}}{U_2 - A_2} - 1 \right) \right]^{1/5} \right) + \left[\frac{\rho_1}{\rho_2} \frac{u_{s2}}{2l_m} \left(\frac{x_G}{U_2 - A_2} + \frac{1}{u_{s2}} \frac{L_1}{L_2} \right) \right] = 0 \end{aligned}$$

$$t_G = \frac{x_G}{U_2 - A_2} + \frac{1}{u_{s2}} \frac{L_1}{L_2}$$

A.4 Blob Trajectories including Mirels Effect

ORIGINAL PAGE IS
OF POOR QUALITY

$$x = \frac{u_s t^*}{(\rho_2/\rho_1) l_m} \left(\frac{3R}{2+R} \right)^{\frac{1}{1-n}}$$

$$t^* = \frac{l^*}{l_m} \left(\frac{3R}{2+R} \right)^{\frac{1}{1-n}}$$

$$R = \frac{\rho}{\rho_{min}}$$

$$v = \left(\frac{3R}{2+R} \right)^{\frac{5}{4}}$$

l^* = mixing front separation from shock wave

$$\begin{aligned} \frac{5}{8} \left(\ln \left\{ \frac{1 - \left[\frac{x_{GB}}{l_m} v \left(\frac{u_{s2}}{U_2 - A_2} - 1 \right) \right]^{1/5}}{1 + \left[\frac{x_{GB}}{l_m} v \left(\frac{u_{s2}}{U_2 - A_2} - 1 \right) \right]^{1/5}} \right\} - 2 \arctan \left[\frac{x_{GB}}{l_m} v \left(\frac{u_{s2}}{U_2 - A_2} - 1 \right) \right]^{1/5} \right. \\ \left. + 4 \left[\frac{x_{GB}}{l_m} v \left(\frac{u_{s2}}{U_2 - A_2} - 1 \right) \right]^{1/5} \right) + \left[\frac{\rho_1}{\rho_2} \frac{u_{s2} v}{2l_m} \left(\frac{x_{GB}}{U_2 - A_2} + \frac{1}{u_{s2}} \frac{L_1}{L_2} \right) \right] = 0 \end{aligned}$$

$$t_{GB} = \frac{x_{GB}}{U_2 - A_2} + \frac{1}{u_{s2}} \frac{L_1}{L_2}$$

A.5 The Unsteady Method of Characteristics

Reference: Ferri (1961)

$$\frac{\delta p}{\delta t} + u \frac{\delta p}{\delta x} + \rho a^2 \frac{\delta u}{\delta x} = 0$$

$$\frac{\delta p}{\delta x} + \rho u \frac{\delta u}{\delta x} + \rho \frac{\delta u}{\delta t} = 0$$

$$\Delta S = 0$$

equation of state

$$p = \rho R T$$

definition of speed of sound for a perfect gas

$$a^2 = \left(\frac{\delta p}{\delta \rho} \right)_S = \gamma R T$$

ORIGINAL PAGE IS
OF POOR QUALITY

physical characteristics

$$\text{along first family, } \frac{dx}{dt} = u + a$$

$$\text{along second family, } \frac{dx}{dt} = u - a$$

state characteristics

$$\text{along first family, } \frac{dp}{dt} + \rho a \frac{du}{dt} = 0$$

$$\text{along second family, } \frac{dp}{dt} - \rho a \frac{du}{dt} = 0$$

Interior Points

$$x_3 = \frac{t_1 - t_2 + \frac{x_2(u_2 - a_2 + u_3 - a_3)}{2(u_2 - a_2)(u_3 - a_3)} - \frac{x_1(u_1 + a_1 + u_3 + a_3)}{2(u_1 + a_1)(u_3 + a_3)}}{\frac{u_2 - a_2 + u_3 - a_3}{2(u_2 - a_2)(u_3 - a_3)} - \frac{u_1 + a_1 + u_3 + a_3}{2(u_1 + a_1)(u_3 + a_3)}}$$

$$t_3 = \frac{x_1 - x_2 + \frac{2t_2(u_2 - a_2)(u_3 - a_3)}{u_2 - a_2 + u_3 - a_3} - \frac{2t_1(u_1 + a_1)(u_3 + a_3)}{u_1 + a_1 + u_3 + a_3}}{\frac{u_2 - a_2 + u_3 - a_3}{u_2 - a_2 + u_3 - a_3} - \frac{2(u_1 + a_1)(u_3 + a_3)}{u_1 + a_1 + u_3 + a_3}}$$

$$u_3 = \frac{u_1 + a_1}{2} + \frac{a_1 - a_2}{\gamma - 1}$$

$$a_3 = \frac{(\gamma - 1)(u_1 - u_2)}{4} + \frac{a_1 + a_2}{2}$$

For driver point:

$$P_3 = P_1 \left(\frac{a_3}{a_1} \right)^{\frac{2\gamma}{\gamma-1}}$$

$$T_3 = a_3^2$$

$$\rho_3 = \frac{P_3}{T_3}$$

For test gas point:

$$P_3 = P_1 \left(\frac{a_3}{a_1} \right)^{\frac{2\gamma}{\gamma-1}}$$

$$T_3 = a_3^2 \frac{\gamma_1 R_1}{\gamma_2 R_2}$$

$$\rho_3 = \frac{P_3 R_4}{T_3 R_1}$$

Expansion Wave Points

$$c_3 = \frac{-(\theta + \mu)}{100} \left(\arctan \left(\frac{1}{U_2 - A_2} \right) - \arctan \left(\frac{1}{U_5 - A_5} \right) \right) + \arctan \left(\frac{1}{U_1 - a_1} \right)$$

$$u_2 = \frac{2}{(\gamma_1 + 1) \tan c_3} + \frac{(\gamma_1 - 1) U_2}{\gamma_1 + 1}$$

$$a_2 = \frac{(\gamma_1 - 1)(U_2 - u_2)}{2} + A_2$$

$$P_2 = P_1 \left(\frac{a_2}{a_1} \right)^{\frac{2\gamma_1}{\gamma_1 - 1}}$$

$$\rho_2 = \rho_1 \left(\frac{a_2}{a_1} \right)^{\frac{2}{\gamma_1 - 1}}$$

$$x_2 = 0$$

$$t_2 = \frac{x_2 - x_1}{u_1 + a_1} + t_1$$

$$x_3 = \frac{t_1 - t_2 + \frac{x_2(u_2 - a_2 + u_3 - a_3)}{2(u_2 - a_2)(u_3 - a_3)} - \frac{x_1(u_1 + a_1 + u_3 + a_3)}{2(u_1 + a_1)(u_3 + a_3)}}{\frac{u_2 - a_2 + u_3 - a_3}{2(u_2 - a_2)(u_3 - a_3)} - \frac{u_1 + a_1 + u_3 + a_3}{2(u_1 + a_1)(u_3 + a_3)}}$$

$$t_3 = \frac{x_1 - x_2 + \frac{2t_2(u_2 - a_2)(u_3 - a_3)}{u_2 - a_2 + u_3 - a_3} - \frac{2t_1(u_1 + a_1)(u_3 + a_3)}{u_1 + a_1 + u_3 + a_3}}{\frac{2(u_2 - a_2)(u_3 - a_3)}{u_2 - a_2 + u_3 - a_3} - \frac{2(u_1 + a_1)(u_3 + a_3)}{u_1 + a_1 + u_3 + a_3}}$$

$$P_3 = P_1 \left(\frac{a_3}{a_1} \right)^{\frac{2\gamma_1}{\gamma_1 - 1}}$$

$$T_3 = a_3^2 \frac{\gamma_4 R_4}{\gamma_1 R_1}$$

$$\rho_3 = \frac{P_3 R_4}{T_3 R_1}$$

Contact Surface Points (velocities and pressures equal)

$$(u_3)_1 = u_4$$

$$(a_{3t})_1 = \frac{(\gamma_1 - 1)(u_4 - u_2)}{2} + a_2$$

$$(a_{3d})_1 = (a_{3t})_1$$

ORIGINAL PAGE IS
OF POOR QUALITY

ORIGINAL PAGE IS
OF POOR QUALITY

$$(u_1)_1 = \frac{(u_3)_1 + u_4}{2} + \frac{(a_{3d})_1 - a_4}{\gamma_4 - 1}$$

$$(a_1)_1 = \frac{(\gamma_4 - 1)((u_3)_1 - u_4)}{4} + \frac{(a_{3d})_1 + a_4}{2}$$

$$(x_3)_I = \frac{t_4 - t_2 + \frac{x_2(u_2 - a_2 + (u_3)_{I-1} - (a_{3t})_{I-1})}{2(u_2 - a_2)((u_3)_{I-1} - (a_{3t})_{I-1})} - \frac{x_4((u_3)_{I-1} + u_4)}{2(u_3)_{I-1}u_4}}{\frac{u_2 - a_2 + (u_3)_{I-1} - (a_{3t})_{I-1}}{2(u_2 - a_2)((u_3)_{I-1} - (a_{3t})_{I-1})} - \frac{(u_3)_{I-1} + u_4}{2(u_3)_{I-1}u_4}}$$

$$(t_3)_I = \frac{x_4 - x_2 + \frac{2t_2(u_2 - a_2)((u_3)_{I-1} - (a_{3t})_{I-1})}{u_2 - a_2 + (u_3)_{I-1} - (a_{3t})_{I-1}} - \frac{2t_4(u_3)_{I-1}u_4}{(u_3)_{I-1} + u_4}}{\frac{2(u_2 - a_2)((u_3)_{I-1} - (a_{3t})_{I-1})}{u_2 - a_2 + (u_3)_{I-1} - (a_{3t})_{I-1}} - \frac{2(u_3)_{I-1}u_4}{(u_3)_{I-1} + u_4}}$$

$$(x_1)_I = \left\{ (t_3)_I - t_4 + \frac{x_4(u_4 - a_{4d} + u_5 - a_5)}{2(u_4 - a_{4d})(u_5 - a_5)} \right. \\ \left. - \frac{(x_3)_I((u_1)_{I-1} + (a_1)_{I-1} + (u_3)_I + (a_{3d})_{I-1})}{2((u_1)_{I-1} + (a_1)_{I-1})((u_3)_{I-1} + (a_{3d})_{I-1})} \right\} \\ + \left\{ \frac{u_4 - a_{4d} + u_5 - a_5}{2(u_4 - a_{4d})(u_5 - a_5)} - \frac{(u_1)_{I-1} + (a_1)_{I-1} + (u_3)_{I-1} + (a_{3d})_{I-1}}{2((u_1)_{I-1} + (a_1)_{I-1})((u_3)_{I-1} + (a_{3d})_{I-1})} \right\}$$

$$(t_1)_I = \left\{ (x_3)_I - x_4 + \frac{2t_4(u_4 - a_{4d})(u_5 - a_5)}{u_4 - a_{4d} + u_5 - a_5} \right. \\ \left. - \frac{2(t_3)_I((u_1)_{I-1} + (a_1)_{I-1})((u_3)_{I-1} + (a_{3d})_{I-1})}{(u_1)_{I-1} + (a_1)_{I-1} + (u_3)_{I-1} + (a_{3d})_{I-1}} \right\} \\ + \left\{ \frac{2(u_4 - a_{4d})(u_5 - a_5)}{u_4 - a_{4d} + u_5 - a_5} - \frac{2((u_1)_{I-1} + (a_1)_{I-1})((u_3)_{I-1} + (a_{3d})_{I-1})}{(u_1)_{I-1} + (a_1)_{I-1} + (u_3)_{I-1} + (a_{3d})_{I-1}} \right\}$$

$$(u_1)_I = \frac{u_4 \sqrt{(t_5 - (t_1)_I)^2 + (x_5 - (x_1)_I)^2} + u_5 \sqrt{(t_4 - (t_1)_I)^2 + (x_4 - (x_1)_I)^2}}{\sqrt{(t_5 - t_4)^2 + (x_5 - x_4)^2}}$$

$$(a_1)_I = \frac{a_{4d} \sqrt{(t_5 - (t_1)_I)^2 + (x_5 - (x_1)_I)^2} + a_5 \sqrt{(t_4 - (t_1)_I)^2 + (x_4 - (x_1)_I)^2}}{\sqrt{(t_5 - t_4)^2 + (x_5 - x_4)^2}}$$

$$(p_1)_I = \frac{p_4 \sqrt{(t_5 - (t_1)_I)^2 + (x_5 - (x_1)_I)^2} + p_5 \sqrt{(t_4 - (t_1)_I)^2 + (x_4 - (x_1)_I)^2}}{\sqrt{(t_5 - t_4)^2 + (x_5 - x_4)^2}}$$

$$(\rho_1)_I = \frac{\rho_{4d} \sqrt{(t_5 - (t_1)_I)^2 + (x_5 - (x_1)_I)^2} + \rho_5 \sqrt{(t_4 - (t_1)_I)^2 + (x_4 - (x_1)_I)^2}}{\sqrt{(t_5 - t_4)^2 + (x_5 - x_4)^2}}$$

$$(p_3)_I = p_4 \left(\frac{(a_{3t})_{I-1}}{a_{4t}} \right)^{\frac{2\gamma}{\gamma-1}}$$

$$(\rho_{3d})_I = \frac{(p_3)_{I-1}}{(a_{3d})_{I-1}^2}$$

$$(p_{3t})_I = \frac{\gamma_1(p_3)_{I-1}}{\gamma_4(a_{3t})_{I-1}}$$

$$(u_3)_I = \frac{p_1 - p_2 + \frac{u_1(p_1 a_1 + (p_{3d})_I (a_{3d})_{I-1})}{2} + \frac{u_2(p_2 a_2 + (p_{3t})_I (a_{3t})_{I-1})}{2}}{\frac{(p_1)_I (a_1)_I + (p_{3d})_I (a_{3d})_{I-1}}{2} + \frac{p_2 a_2 + (p_{3t})_I (a_{3t})_{I-1}}{2}}$$

$$(p_3)_I = \frac{u_1 - u_2 + \frac{2p_1}{p_1 a_1 + (p_{3d})_I (a_{3d})_{I-1}} + \frac{2p_2}{p_2 a_2 + (p_{3t})_I (a_{3t})_{I-1}}}{\frac{p_1 a_1 + (p_{3d})_I (a_{3d})_{I-1}}{2} + \frac{p_2 a_2 + (p_{3t})_I (a_{3t})_{I-1}}{2}}$$

$$(a_{3t})_I = a_{4t} \left(\frac{(p_3)_I}{p_4} \right)^{\frac{\gamma_1-1}{2\gamma_1}}$$

$$(a_{3d})_I = a_{4d} \left(\frac{(p_3)_I}{p_4} \right)^{\frac{\gamma_1-1}{2\gamma_1}}$$

$$T_{3t} = \frac{\gamma_4 R_4 a_{3t}^2}{\gamma_1 R_1}$$

$$T_{3d} = a_{3d}^2$$

Blob Point

$$(x_2)_1 = x_6$$

$$(x_2)_2 = x_3$$

$$(t_2)_I = \frac{(t_6 - t_3)(x_2)_{I-1} - x_6}{x_6 - x_3} + t_6$$

$$(u_2)_I = \frac{u_6 \sqrt{(t_3 - t_2)^2 + (x_3 - (x_2)_{I-1})^2} + u_3 \sqrt{(t_6 - t_2)^2 + (x_6 - (x_2)_{I-1})^2}}{\sqrt{(t_6 - t_3)^2 + (x_6 - x_3)^2}}$$

$$(p_2)_I = \frac{p_6 \sqrt{(t_3 - t_2)^2 + (x_3 - (x_2)_{I-1})^2} + p_3 \sqrt{(t_6 - t_2)^2 + (x_6 - (x_2)_{I-1})^2}}{\sqrt{(t_6 - t_3)^2 + (x_6 - x_3)^2}}$$

$$(W_2)_I = \frac{2((u_2)_I - u_1)}{2R + 1} + W_1$$

$$(x_2)_{I-1} = \frac{2W_1(W_2)_I((t_2)_I - t_1)}{W_1 + (W_2)_I} + x_1$$

Blob Expansion Point

$$c_3 = \frac{-(\theta + \mu)}{100} \left(\arctan \left(\frac{1}{U_2 - A_2} \right) - \arctan \left(\frac{1}{U_5 - A_5} \right) \right) + \arctan \left(\frac{1}{U_1 - a_1} \right)$$

$$u_3 = \frac{2}{(\gamma_1 + 1) \tan c_3} + \frac{(\gamma_1 - 1) U_2}{\gamma_1 + 1}$$

ORIGINAL PAGE IS
OF POOR QUALITY

$$a_3 = \frac{(\gamma - 1)(U_2 - u_3)}{2} + A_2$$

$$T_3 = a_3^2 \frac{\gamma_4 R_4}{\gamma_1 R_1}$$

$$\rho_3 = \rho_1 \left(\frac{T_3}{T_1} \right)^{\frac{1}{\gamma-1}}$$

$$W_3 = \frac{3(u_3 - u_1)}{4R} + W_1$$

$$x_3 = \frac{\frac{1}{u_{s2}} \frac{L_1}{L_2} - t_1 + \frac{x_1(W_1 + W_3)}{2W_1W_3}}{\frac{W_1 + W_3}{2W_1W_3} - \frac{1}{u_3 - a_3}}$$

$$t_3 = \frac{x_3}{u_3 - a_3} \frac{1}{u_{s2}} \frac{L_1}{L_2}$$

Boundary Conditions

1. Moving piston - gas remains in contact with piston.
2. Supersonic outflow through open-ended duct - both families of characteristics travel in same direction and both exit, same as interior points.
3. Strong shock waves - patch solutions together.

A.6 The Pitot Pressure

$$\frac{P_1}{P_{02}} = \frac{\left(\frac{2\gamma}{\gamma+1} M_1^2 - \frac{\gamma-1}{\gamma+1} \right)^{\frac{1}{\gamma-1}}}{\left(\frac{\gamma+1}{2} M_1^2 \right)^{\frac{\gamma}{\gamma-1}}}$$

B Program Listing

**ORIGINAL PAGE IS
OF POOR QUALITY**

The Unsteady Method of Characteristics
By Chris M. Gourlay
University of Queensland
St. Lucia 4067
Queensland, Australia
September, 1983
Microsoft BASIC Version 2.10.00 (Binary Math)

```

INITIALISE PROGRAM AND SET UP EVENT TRAPPING

WINDOW CLOSE :  

CLEAR :  

INITIALISE :  

DEFINT I-N : DEFDBL A-H, O-R : DEFSGN S-U : DEFSTR X-Y : DEFCHR Z-Z :  

MnSelected = 0 : MnOutline = 0 : Activity = 0  

Buttonpressed = 0 : IFSelected = 0 : ISSelected = 0 : WGOAway = 0  

ICirty = 0 : TAUX = 1 : FALSET = 0  

I = 0 :  

K = 1 :  

IXsize = 300 : IXsize = 300 : IXmax = 5 : IXscroll = 0 : IXscroll = 0 : IXpenflag = 0 : IXthumberflag = 0 : IXcircleflag = 1 : IXpend = 0 : IXchasingflag = 0 : IXangleflag = 0 : IXgridflag = 0 : IXselected = 0 : IXGotoaway = 0 : IXdirty = 1 : IXmouseflag = 0 : IXwindowflag = 0 : IXgammaflag = 0 : IXplotpoint = 1 : IXplotflag = 0 :  

PI = 4*ATN(1) :  

TC = .0000001 :  

PRT = 0 : PIPD = 0 : PZC = 0 : L1128 = 0 : MAGFACTR = 1 : THIN = 0 :  

PZFAC = 0 : FIRSTINFO = 0 :  

DIM iwatch(33), icrosshair(33), icircle(33), lbar(33), ihand(33), ihand(33), ipoint(33), perlocation() :  

DIM PointLocs(300), PointLocs(300), PointType(300), lPoint(300), jPoint(300) :  

RESTORE :  

FOR II = 0 TO 31 :  

    READ iwatch(ii) :  

NEXT II :  

SETCURSOR VARPTR (iwatch(0)) :  

RESTORE :  

FOR II = 0 TO 31 :  

    READ icrosshair(ii) :  

NEXT II :  

icrosshair(32) = 7 : icrosshair(33) = 8 :  

FOR II = 0 TO 31 :  

    READ icircle(ii) :  

NEXT II :  

icircle(32) = 7 : icircle(33) = 8 :  

FOR II = 0 TO 3 :  

    igrey(ii) = -21931 :  

NEXT II :  

Draw dashed wall pattern :  

FOR II = 0 TO 3 :  

    idash(ii) = 16191 :  

NEXT II :  

FOR II = 0 TO 31 :  

    READ ihand(ii) :  

NEXT II :  

ihand(32) = 7 : ihand(33) = 8 :  

Set up info scroll bar :  

PICTURE ON :  

Draw grey pattern :  

FOR II = 0 TO 3 :  

    igrey2(ii) = -30886 :  

NEXT II :  

lbar(0) = 14 : lbar(1) = 94 : lbar(2) = 66 : lbar(3) = 110 :  

Frame grey pattern :  

FILLRECT (VARPTR(lbar(0))), (VARPTR(igrey2(0))) :  

FRAGRECT (VARPTR(lbar(0))) :  

LINE (94, 0) - (94, 80) :  

Draw up arrow :  

MOVE TO 102, 2 :  

CALL LINE (6, 6) : CALL LINE (3, 0) : CALL LINE (0, 6) : CALL LINE (6, 0) : CALL LINE (0, -6) : CALL LINE (3, 0) : CALL LINE (-6, -6) :  

Draw down arrow :  

MOVE TO 99, 68 :  

CALL LINE (6, -6) : CALL LINE (-3, 0) : CALL LINE (6, 6) : CALL LINE (3, 0) : CALL LINE (-3, -6) : CALL LINE (0, -6) : CALL LINE (-6, 0) :  

PICTURE OFF :  

scrollBar = PICTURES :  

PICTURE ON :  

Draw scroll bar :  

LINE (95, 15) - (109, 30), 20, BY : LINE (95, 15) - (109, 30), 1, B :  

PICTURE OFF :  

scrollBar = PICTURES :  

WRITE DATA :  

DATA 2016, 2016, 2016, 2016, 2064, 4732, 4732, 4734 :  

DATA 5004, 4104, 4104, 2064, 2016, 2016, 2016, 2016 :  

DATA 2016, 2016, 2016, 2016, 4080, 8184, 8184, 8184 :  

DATA 8184, 8184, 8184, 4080, 2016, 2016, 2016, 2016 :  

CROSSHAIR DATA :  

DATA C, C, 256, 256, 256, 256, 16376 :  

DATA 256, 256, 256, 256, 0, 0, 0 :  

CIRCLE DATA :  

DATA 0, 0, 0, 0, 896, 1088, 2080, 2080 :  

DATA 2080, 1088, 896, 0, 0, 0, 0, 0 :  

DATA C, 0, 0, 0, 896, 1088, 2080, 2080 :  

DATA 2080, 1088, 896, 0, 0, 0, 0, 0 :  

HAND DATA :  

DATA 0, 0, 0, 0, 896, 3200, 4352, 8960 :  

DATA 23590, 17921, 19454, 29192, 17392, 16912, 23168, 16320 :  

DATA 0, 0, 0, 0, 896, 3964, 7936, 14128 :  

DATA 32768, 32767, 32766, 32765, 32752, 32736, 16320 :  

DATA "UNSTEADY CHARACTERISTICS PROGRAM", "By Chris Gourlay" :  

DATA "Dept. of Mechanical Engineering, University of Queensland, St. Lucia" :  

DATA "Queensland 4072, Australia", "Does database file exist?" :  

DATA "Yes" OR "No" To begin? :  

3 DATA "EXPANSION TUBE INITIAL CONDITIONS", "Driver Tube (4)", "Suction Tube (1)", "Accel. Tube (1)", "Driver Gas =", "Test/Accel. Gas =":  

5 DATA "ENTERED SETUP BOX", "Meshscale", "Magnification" :  

6 DATA "New Magnification" :  

200 DATA "PARENT SETUP BOX", "x increment", "y increment", "Magnification", "1" :  

201 DATA "Start", "Finish" :  

300 DATA "PARENT PLOT SETUP" :  

3000 DATA "Select", "1",  

    MENU 1, 0, 1, "File",  

        MENU 1, 1, 1, "Open...",  

        MENU 1, 2, 0, "Close",  

        MENU 1, 3, 0, "Save",  

        MENU 1, 4, 0, "Print...",  

        MENU 1, 5, 0, "Quit",  

        MENU 1, 0, 0, "Display",  

        MENU 1, 1, 2, "Zoom...",  

        MENU 1, 2, 0, "Pan...",  

        MENU 1, 3, 0, "A",  

        MENU 1, 4, 1, "Grid",  

        MENU 1, 5, 0, "C",  

        MENU 1, 6, 1, "Point Numbers"
```

ORIGINAL PAGE IS OF POOR QUALITY

```

MENU 3, 7, 0, 0
MENU 3, 8, 2, "Point Circles"
MENU 3, 9, 0, 0
MENU 3, 10, 1, "Titet Plot..."
MENU 4, 0, 0, "Point"
MENU 4, 1, 0, "Contact..."
MENU 4, 2, 0, "Expansion..."
MENU 4, 3, 0, "Driver..."
MENU 4, 4, 0, "Test..."
MENU 4, 5, 0, "BlaBla..."
MENU 4, 6, 0, "BlaBlaP..."
MENU 4, 7, 0, 0
MENU 4, 8, 1, "Mesh Split"
MENU 4, 9, 0, 0
MENU 4, 10, 0, "Trass..."
MENU 3, 0, 0, "Info"
MENU 3, 1, 1, "Display Info"
MENU 3, 2, 0, "Get Info..."
MENU 6, 0, 0, "Scale"
MENU 6, 1, 1, "Zoom..."
MENU 6, 2, 1, "Scroll..."
MENU 7, 0, 0, "Copy"
MENU 7, 1, 1, "Copyflow"
Activate event handling
ON DIALOG GOSUB DialogEvent
ON MENU GOSUB MenuEvent
ON BREAK GOSUB BreakEvent
ON MOUSE GOSUB MouseEvent
MENU      turn off any highlighted menus
INITCURSOR
MENU ON : DIALOG ON

MAIN PROGRAM LOOP
Idle:
  WHILE TRUE = 1           'Endless loop
  END

HANDLE EVENTS AREA
MenuEvent:
  DIALOG STOP : IF infoflag = 1 THEN MOUSE STOP
  SETCURSOR VAAPTR (iwatch(0))
  Menuselect = MENU(0)
  ON Menuselect GOSUB Filemenu, DisplayMenu, Pointmenu, Infomenu, Scalemenu, Copymenu
  MENU
  IF infoflag = 1 THEN MOUSE ON
  DIALOG ON : INITCURSOR
  RETURN

DialogEvent:
  MENU STOP : IF infoflag = 1 THEN MOUSE STOP
  Activity = DIALOG(0)
  ON Activity GOSUB ButtonEvent, EditEvent, Activate, OnAway, Refresh, ReturnEvent, TabEvent
  Activity = DIALOG(0) : IF infoflag = 1 THEN MOUSE ON
  MENU ON
  RETURN

BreakEvent:
  Break = 1 : iDirty = 0
  IF infoflag = 1 THEN GOSUB Findinfo2
  RETURN

MouseEvent:
  IF mouseflag = 1 THEN RETURN
  MENU STOP : DIALOG STOP
  MouseClick = MOUSE(0) + 4
  ON MouseClick GOSUB MouseReturn, MouseReturn, MousePosition, MouseReturn, MousePosition, MouseReturn
  IF MOUSE(0) = -1 THEN GOTO MouseEvent
  MENU ON : DIALOG ON
  RETURN

HANDLE THE MENU EVENTS AREA
FileMenu:
  Menutree = MENU(1)
  ON Menutree GOSUB Openfile, Closefile, Savefile, Printfile, Quit
  RETURN

Openfile:
  'Setup database interface for storage of information about a particular
  'geometry and solution
  GOSUB DrawDialog
  MENU 1, 1, 0 : MENU 1, 2, 1 : MENU 1, 3, 1 : MENU 1, 4, 1
  RETURN

Closefile:
  MENU 0, CLOSE 3 : WINDOW CLOSE 2 : WINDOW CLOSE 4
  MENU 3, 1, 2 : MENU 3, 2, 0
  MENU 3, 8, 2 : MENU 3, 10, 1
  MENU 4, 1, 1 : MENU 4, 2, 1 : MENU 4, 3, 1 : MENU 4, 4, 1 : MENU 4, 5, 1 : MENU 4, 6, 1 : MENU 4, 8, 1 : MENU 4, 10, 1
  MENU 6, 1, 1 : MENU 6, 2, 1 : MENU 7, 1, 1
  'Save status information
  CLOSE 4
  OPEN FS AS 4: LEN = 76
  FILED #1, 2 AS maxfactors, 2 AS ScrollLX, 2 AS ScrollLY, 8 AS hg, 8 AS tg, 8 AS aglob, 8 AS tglob, 8 AS tg2, 2 AS texpad
  8 AS gammaobj
  LET maxf = MAX(maxf)
  LET maxfactors = MAX(maxfactors)
  LET ScrollLX = MAX(iScrollLX)
  LET ScrollY = MAX(iScrollLY)
  LET hg = MAX(hg)
  LET tg = MAX(tg)
  LET aglob = MAX(aglob)
  LET tglob = MAX(tglob)
  LET tg2 = MAX(tg2)
  LET texpad = MAX(iexpad)
  LET gammaobj = MAX(gammaobj)
  PUT #1, 1
  READ
  MENU 1, 1, 1 : MENU 1, 2, 0 : MENU 1, 3, 0 : MENU 1, 4, 0 : MENU 7, 0, 0 : MENU 4, 1, 0 : MENU 4, 2, 0 : MENU 4, 3, 0 : MENU 4, 8, 1 : MENU 4
  MENU 4, 5, 0 : MENU 5, 1, 0 : MENU 3, 4, 1
  MENU 3, 1, 2 : MENU 3, 2, 0 : MENU 3, 8, 2
  MENU 3, 0, 0 : MENU 4, 6, 0 : MENU 5, 0, 0 : MENU 6, 0, 0 : MENU 4, 4, 0
  1 = 0
  k = 1
  maxf = 5 : iscrollLX = 0 : iscrollLY = 0 : isopenfing = 0 : iscirclefing = 1 : ispend = 0 : itanglefing = 0 : isheetfing = 0

```

ORIGINAL PAGE IS OF POOR QUALITY

```

infoflag = 0 : igniflag = 0 : idirty = 1 : mouseflag = 0 : scrollflag = 0 : lgammaflag = 0 : ipiterflag = 0 : ipiterpoint =
      0 : pip0 = 0 : t471 = 0 : l1124 = 0 : magfactor4 = 11 : rnum = 0
: iflag = 0 : iiratintf = 0
RETURN

SaveFile:
  Save status information
  CLOSE #1
  OPEN #8 AS #1 LEN = 76
  FIELD #1, 2 AS max, 8 AS magfactor8, 2 AS scrollX8, 2 AS scrollY8, 8 AS agf, 8 AS tg1, 8 AS tg2, 8 AS tg3, 8 AS tg4, 2 AS tempers
    AS gamma8
  LSET max8 = MHD8(max)
  LSET magfactor8 = MHD8(magfactor4)
  LSET scrollX8 = MHD8(scrollX4)
  LSET scrollY8 = MHD8(scrollY4)
  LSET agf = MHD8(agf)
  LSET tg1 = MHD8(tg1)
  LSET tg2 = MHD8(tg2)
  LSET tempers = MHD8(tempers)
  LSET gammab8 = MHD8(gamma8)
  PUT #1, 1
Set file up for point data
  CLOSE #1
  OPEN #8 AS #1 LEN = 76
  FIELD #1, 16 AS pgb, 2 AS ts, 2 AS xf, 8 AS yf, 8 AS xl, 8 AS yl, 8 AS pd, 8 AS tt, 8 AS chof
RETURN

Printfile:
  IF infoflag = 1 THEN WINDOW CLOSE 2 : WINDOW 4
  CALL SIDEPIN : LINE (0, 0) - (500, 100), 1
  PICTURE OFF : Images = PICTURES : PICTURE ON : CALL SIDEPIN
  Draw box to input scaling information
  lxa = 30 : ltt = 10 : ls = 1
  WINDOW 4, 77, (116, 80) - (396, 150), -2
  RESTORE 200 : TEXTFACE(1)
  READ axf : MOVETO (224) - LEN(axf)*18, 31, 24, 20 : PRINT axf
  BUTTON 1, 1, THT, (224, 6) - (274, 28), 1
  EDIT FIELD 1, STRE(1max), (5, 40) - (45, 55), 1, 2
  READ axf : MOVETO 50, 52 : PRINT axf
  EDIT FIELD 2, STRE(1tt), (5, 60) - (45, 75), 1, 2
  READ axf : MOVETO 50, 72 : PRINT axf
  READ axf : MOVETO 1404 + (140) - LEN(axf)*17, 40/24, 32 : PRINT axf : EDIT FIELD 3, STRE(axf*100), (190, 50) - (230, 73), 1, 2
  READ axf : MOVETO 240, 72 : PRINT axf
  LINE (5, 34) - (275, 34) : LINE (140, 34) - (140, 104)
  EDIT FIELD 1
  x = DIALOG(0) : INITCURSOR : tabfield = 1
  WHILE x > 0 AND x <> 6
    IF x = 1 THEN IF tabfield < 2 THEN tabfield = tabfield + 1 ELSE tabfield = 1
    IF x = 2 THEN EDIT FIELD tabfield
    x = DIALOG(0)
  MENU
  lxa = VAL(EDITF(1))
  ltt = VAL(EDITF(2))
  ls = VAL(EDITF(3))/100
  WINDOW CLOSE 4 : lbreak = 0
  ON ERROR GOTO Error1
100  IF lbreak = 0 THEN OPEN "LEFT:PRPPRTY FOR OUTPUT AS 2 : SETCURSOR VAFAFE (watch(0)) : WINDOW OUTPUT 62 : PICTURE (0 + lxa, 0 + ltt) - (350 +
  lxa)*ls, (116 + ltt)*ls). Images
  Printfile:
  ON ERROR GOTO 0
  CLOSE #2
  IF infoflag = 1 THEN WINDOW 2 : GOOSB FindInfo
RETURN

Qu11:
  IF igniflag = 0 THEN RESET : MENU RESET : SYSTEM
  Save status information
  CLOSE #1
  OPEN #8 AS #1 LEN = 76
  FIELD #1, 2 AS max, 8 AS magfactor8, 2 AS scrollX8, 2 AS scrollY8, 8 AS agf, 8 AS tg1, 8 AS tg2, 8 AS tg3, 2 AS tempers
    AS gamma8
  LSET max8 = MHD8(max)
  LSET magfactor8 = MHD8(magfactor4)
  LSET scrollX8 = MHD8(scrollX4)
  LSET scrollY8 = MHD8(scrollY4)
  LSET agf = MHD8(agf)
  LSET tg1 = MHD8(tg1)
  LSET tg2 = MHD8(tg2)
  LSET tempers = MHD8(tempers)
  LSET gammab8 = MHD8(gamma8)
  PUT #1, 1
  RESET
  MENU RESET
  SYSTEM

ClipLayermenu:
  MenuItem = MHDG(1)
  On MenuItem GOOSB MeshDisplay, TableDisplay, Grid4Display, NumberDisplay, CircleDisplay, PitoDisplay
RETURN

MeshDisplay:
  MENU 3, 1, 2 : MENU 3, 2, 0 : MENU 4, 0, 1 : MENU 4, 0, 1
  IF igniflag = 1 THEN MENU 3, 4, 2 ELSE MENU 3, 4, 1
  IF igniflag = 1 THEN MENU 3, 5, 2 ELSE MENU 3, 5, 1
  IF icircleflag = 1 THEN MENU 3, 8, 2 ELSE MENU 3, 8, 1
  CLS : GOOSB Reflet
  IF infoflag = 1 THEN IDirty = 0 : II = 1111 : WINDOW 2, "", (400, 260) - (510, 340), 1 : GOOSB FindInfo
RETURN

TabDisplay:
  PICTURE OFF
  MENU 3, 0, 0 : MENU 3, 1, 1 : MENU 3, 2, 2 : MENU 4, 0, 0 : MENU 6, 0, 0
  MENU 3, 4, 0 : MENU 3, 6, 0 : MENU 3, 8, 0 : CLS : II = 1111 - 11 : GOOSB DrawTable
RETURN

Grid4Display:
  IF igniflag = 0 THEN igniflag = 1 : MENU 3, 4, 2 : GOOSB Grid : RETURN
  IF igniflag = 1 THEN igniflag = 0 : MENU 3, 4, 1 : CLS : GOOSB Reflet2 : RETURN

NumberDisplay:
  IF igniflag = 0 THEN igniflag = 1 : MENU 3, 6, 2 : GOOSB ShowNumber : RETURN
  IF igniflag = 1 THEN igniflag = 0 : MENU 3, 6, 1 : CLS : GOOSB Reflet2 : RETURN

CircleDisplay:
  IF icircleflag = 0 THEN icircleflag = 1 : MENU 3, 8, 2 : MENU 4, 0, 1 : GOOSB Reflet2 : RETURN
  IF icircleflag = 1 THEN icircleflag = 0 : MENU 3, 8, 1 : MENU 4, 0, 0 : MENU 3, 0, 0 : CLS : GOOSB Reflet

```

```

    RETURN

PilotDisplay:
MENU 3, 1, 0 : MENU 3, 2, 0 : MENU 3, 4, 0 : MENU 3, 6, 0 : MENU 3, 8, 0 : MENU 3, 10, 0
MENU 4, 1, 0 : MENU 4, 2, 0 : MENU 4, 3, 0 : MENU 4, 4, 0 : MENU 4, 6, 0 : MENU 4, 8, 0 : MENU 4, 10, 0
IF infoflag = 1 THEN MOUSE OFF
mouseflag = 1 : PilotTypePoint = 1 : GOOSB DrawWindow4 : PilotTypeFlag = 1 : WINDOW CLOSE 2
RETURN

PointPlane:
MenuType = MENU(1)
OR MenuType GOOSB ContactPoint, ExpPoint, InteriorPoint, InterPoint, Blob, BlobExpander, MeshSplit, ErasePoint
RETURN

ContactPoint:
InfoFlag = 1
IF infoflag = 1 THEN MOUSE OFF : WINDOW 3
mouseflag = 1 : InterFlag = 0
SETCURSOR VARPTR(crosshair(0)) : GOOSB SelectContact : IF break = 1 THEN GOTO PointEnd
SETCURSOR VARPTR (watch(0))
J = 112
GOOSB FindPoint2 : GOOSB FindPoint3 : GOOSB FindPoint4 : GOOSB FindPoint5
Initial guess at properties
u1 = u4
u2 = (gamma1 - 1)*u4 - u2/20 + a2
u3 = a3t
u4 = u3
u1 = (u3 + u4)/2 + (a3d - a4)/gamma1 - 1)
u1 = (gamma1 - 1)*(u3 - u4)/4 + (a3d + a4)/2
Iterate for position and properties of contact surface point
ContactLoop:
u30 = u3
a30 = a3t
a3d = a3d
GOOSB Contact
IF ABS(u30 - u3)/u30 < tol AND ABS(a30 - a3t)/a30 < tol AND ABS(a3d - a3d)/a3d < tol THEN GOTO ContactCalc ELSE GOTO ContactLoop
ContactCalc:
Calculate contact point remaining properties
T731 = (a3t*2)*(gamma1*14)/(gamma1*11)
T732 = a3d*2
SavePoint:
PointLoc(max) = u3 : PointLoc(max) = t3 : PointType(max) = 2 : iPoint(max) = 1 : jPoint(max) = 3
u3 = a3t : T731 = rhol1 + rho1 : i = max + 2 : j = 112 : Grid1 = "Contact"
GOOSB DrawPoint
PointLoc(max) = u3 : PointLoc(max) = t3 : PointType(max) = 2 : iPoint(max) = 1 : jPoint(max) = 3
u3 = a3t : T731 = rhol1 + rho1 : i = max + 2 : j = max : Grid1 = "Contact"
GOOSB SavePoint
PointLoc(max) = u3 : PointLoc(max) = t3 : PointType(max) = 1 : iPoint(max) = 1 : jPoint(max) = 3
GOOSB DrawPatch
GOOSB DrawPatch
GOOSB Release
IF mouseflag > 0 THEN GET #1, 115 : jj = max + 1 : LSLET jj = MMIS(jj) : PUT #1, 115 : jPoint(115) = max + 1
Grid1 = "Interior"
GOOSB Release
GOOSB DrawPoint
PointLoc(max) = u3 : PointLoc(max) = t3 : PointType(max) = 4 : iPoint(max) = 1 : jPoint(max) = 3
PointEnd:
IF infoflag = 1 THEN IDirty = 0 : GOOSB FindInfo
mouseflag = 0 : ERITCURSOR : infoflag = 0
RETURN

ExpPoint:
IF infoflag = 1 THEN MOUSE OFF : WINDOW 3
mouseflag = 1 : InterFlag = 0 : Expander = 0 : gammaFlag = 0
SETCURSOR VARPTR(crosshair(0)) : GOOSB SelectExpander : IF break = 1 THEN GOTO PointEnd
SETCURSOR VARPTR (watch(0))
J = 112 : GOOSB FindPoint1
IF InterFlag = 1 THEN Expander = -(ATN((4*(u3 - a3))/ - ATN((4*(u3 - a3)))*expangle/1000 + ATN((4*(u1 - a1)))
IF InterFlag = 0 THEN IF expander < ATN((4*(u3 - a3)) THEN Expander = ATN((4*(u3 - a3)) : BEEP : InterFlag = 1
IF InterFlag = 0 THEN Expander = GOOSB Expansion : GOOSB Interior ELSE Grid1 = "Expansion" : u2 = u3 + a2 - a3 : GOOSB Interior
IF InterFlag = 0 THEN u3 = 0 : t2 = 112*expangle/1000 : a2 = u2 + u3 + a2 - a3 : Grid1 = "Expansion"
u3 = (1 - a2 + a2*(u2 - a2 + u3 - a3))/(2*(u1 + a1)*(u3 - a3)) - a1*(u1 + a1 + u3 + a3)/(2*(u1 + a1)*(u3 + a3)) / ((u2 - a2 + u3 - a3)/(2*(u2 - a2 + u3 - a3)) * (u1 + a1 + u3 + a3)/(2*(u1 + a1)*(u3 + a3)))
u3 = a2 - a3 + 2*(u1 + a1)*(u3 + a3)/(2*(u1 + a1 + u3 + a3)) - t1*2*(u1 + a1)*(u3 + a3)/(u1 + a1 + u3 + a3)) / (2*(u2 - a2 + u3 - a3)/(2*(u2 - a2 + u3 - a3)) * (u1 + a1 + u3 + a3))
PointLoc(max) = u3 : PointLoc(max) = t3 : PointType(max) = 1 : iPoint(max) = 1 : jPoint(max) = 1 : IF InterFlag = 0 THEN jPoint(max) = 1 : -1
IF InterFlag = 0 THEN j = -1 ELSE j = -2
GOOSB Calculations
IF InterFlag = 1 THEN InterFlag = 1
PointEnd:
IF infoflag = 1 THEN IDirty = 0 : GOOSB FindInfo
mouseflag = 0 : ERITCURSOR
RETURN

InteriorPoint:
InfoFlag = 1 : GOTO NewInterior
InteriorPoint:
InfoFlag = 0
NewInterior:
IF infoflag = 1 THEN MOUSE OFF : WINDOW 3
mouseflag = 1 : InterFlag = 0
IF mouseflag = 1 THEN GOTO Interior2
InfoFlag = 1
SETCURSOR VARPTR(crosshair(0)) : GOOSB SelectInterior : IF break = 1 THEN PointEnd
SETCURSOR VARPTR (watch(0))
J = 111 : J = 112
GOOSB FindPoint2 : GOOSB FindPoint3
Grid1 = "Interior" : GOOSB Interior
u1 = (1 - a2 + a2*(u2 - a2 + u3 - a3))/(2*(u2 - a2)*(u3 - a3)) - a1*(u1 + a1 + u3 + a3)/(2*(u1 + a1)*(u3 + a3)) / ((u2 - a2 + u3 - a3)/(2*(u2 - a2 + u3 - a3)) * (u1 + a1 + u3 + a3))
u1 = (1 - a2 + a2*(u2 - a2 + u3 - a3))/(u2 - a2 + u3 - a3) - t1*2*(u1 + a1)*(u3 + a3)/(u1 + a1 + u3 + a3)) / (2*(u2 - a2 + u3 - a3)/(2*(u2 - a2 + u3 - a3)) * (u1 + a1 + u3 + a3))
GOOSB Calculations
PointLoc(max) = u1 : PointLoc(max) = t3 : PointType(max) = 0 : iPoint(max) = 1 : jPoint(max) = 3
PointEnd:
IF infoflag = 1 THEN IDirty = 0 : GOOSB FindInfo
mouseflag = 0 : ERITCURSOR : InfoFlag = 0
RETURN

Interior2:
SETCURSOR VARPTR(crosshair(0)) : GOOSB SelectInterior : IF break = 1 THEN GOTO PointEnd
J = 111 : GOOSB FindPoint1
IF PointType(j) = 2 OR PointType(j) = 10 OR PointType(j) = 11 THEN BEEP : BEEP : GOTO PointEnd
u1 = 490*(a1*magfactor + 11124)/(18 + 11124) + 144 + 18*crailx
u1 = 3144 + 18*crailt - 490*(t1*magfactor*t1*magfactor*t1*magfactor)/(18 + 11124)
J = 112 : GOOSB FindPoint2
IF PointType(j) = 2 OR PointType(j) = 10 OR PointType(j) = 11 THEN BEEP : BEEP : GOTO PointEnd
u2 = 490*(a2*magfactor + 11124)/(18 + 11124) + 144 + 18*crailx
u2 = 3144 + 18*crailt - 490*(t1*magfactor*t1*magfactor*t1*magfactor)/(18 + 11124)

```

GRIDS, PART 6

OF POINTS

```

;IMER = 0 : SETCURSOR VARPTR (circle(0)) : MENU OFF : GOSUB SelectSplit : LINE (x1, y1) - (x2, y2), 32 : SETCURSOR VARPTR (circle(0))
    MENU ON : IF lbreak = 1 THEN GOTO MeeshSplit
    GOSUB Average : a1 = xmid : b1 = ymid : GOSUB Remember : GOSUB DrawPoint
    PointLoc(max) = a1 : PointLoc(max) = c1 : iPoint(max) = 1 : jPoint(max) = 1
PointBind:
    IF infing = 1 THEN idirty = 0 : GOSUB FindInfo2
    mouseflag = 0 : INITCURSOR
    GOTO MeeshSplit

;Line:
    IF infing = 1 THEN MODE OFF : WINDOW 3
    mouseflag = 1 : Isotopflag = 0
    SETCURSOR VARPTR (crosshair(0)) : GOSUB SelectSplit : IF lbreak = 1 THEN GOTO BioSplit
    SETCURSOR VARPTR (match(0)) : i = 111
    GOSUB FindPoint : GOSUB FindPoint : GOSUB FindPoint
    imobile = 0
    GET (i, 111) : IF ggi = "Contact" : THEN GOSUB MakeLine ELSE rho = pi : w1 = si = rho/si = 1
    IF imobile = 0 THEN GOTO BioSplit
    siw1 = si * w1 : a1 = iiflag = 2
    t2 = (c6 - c3) * siw1 / (si - a1) : t6
    u2 = (BQR(c3 - c2)^2 + (a6 - siw1)^2)^(1/2) * (a6 - siw1)^(1/2) / BQR(c6 - c3)^2 + (a6 - a3)^2
    rho2 = (BQR(c3 - c2)^2 + (a6 - siw1)^2)^(1/2) * (a6 - siw1)^(1/2) / BQR(c6 - c3)^2 + (a6 - a3)^2
    IF rho > 16 THEN W2 = (u2 + v1)/24 ELSE W2 = (u2 - v1)*(32/(24*rho + 16)) + W1
    siw1 = (c2 - c3)*W2/W1 : W2 = a1 - siw1
    t2 = (t6 - a3)^2 * (a6 - a3) : t6
    u2 = (BQR(c3 - c2)^2 + (a6 - siw1)^2)^(1/2) * (a6 - siw1)^(1/2) / BQR(c6 - c3)^2 + (a6 - a3)^2
    rho2 = (BQR(c3 - c2)^2 + (a6 - siw1)^2)^(1/2) * (a6 - siw1)^(1/2) / BQR(c6 - c3)^2 + (a6 - a3)^2
    IF rho > 16 THEN W2 = (u2 + v1)/24 ELSE W2 = (u2 - v1)*(32/(24*rho + 16)) + W1
    a1upper = (c2 - c3)*W2/W1 : W2 = a1 - siw1
    GOSUB FindInfo2 : GOSUB BioSplit : GOSUB BioSplit
    CALL sencircle(siw1, siw1, iiflag, si1, a2 = 8
    t2 = (t6 - a3)^2 / (a2 - a1) * si - c1
    u2 = (BQR(c3 - c2)^2 + (a6 - a3)^2)^(1/2) / BQR(c6 - c3)^2 + (a6 - a3)^2
    rho2 = (BQR(c3 - c2)^2 + (a6 - a3)^2)^(1/2) * (a6 - a3)^2 / BQR(c6 - c3)^2 + (a6 - a3)^2
    IF rho > 16 THEN W2 = (u2 + v1)/24 ELSE W2 = (u2 - v1)*(32/(24*rho + 16)) + W1
    pi = rho*180/3.14
    aaa = BQR(c3 - c2)^2 + (a6 - a3)^2
    bbb = BQR(c3 - c2)^2 + (a6 - a3)^2
    p1 = (aaa*p2 + bbb*p3)/(aaa + bbb)
    rho = ((rho*pi)/rho2)^(p1/p2)^(1/2/gammablob)
    GOSUB SavePoint : Grids = "blob"
    GOSUB SavePoint
    PointLoc(max) = a2 : PointLoc(max) = t2
    PointType(max) = 6
    iPoint(max) = 111
    jPoint(max) = 111
    GOSUB DrawPoint
    GOSUB DrawPoint
BioSplit:
    IF infing = 1 THEN idirty = 0 : GOSUB FindInfo2
    mouseflag = 0 : INITCURSOR
    RETURN

;Maxblob:
    BEEP : BEEP : BEEP : RETURN
    Find density ellipse
    epsilon = 74
    ii = 11 : GOSUB FindPoint
    alphai = 54*ii - epsilon*ii
    alphai = epsilon*ii
    alphai = 84 - ii
    alphai = 84
    alphai = 54*ii*77 - epsilon*ii*77
    alphai = epsilon*ii*77
    alphai = alphai/alphai
    alphai2 = (alphai/alphai)^2 - alphai*alphai/alphai*alphai - alphai*alphai/(alphai*alphai) + alphai*alphai/(alphai*alphai)
    If alphai < 0# THEN rho = rho : GOTO CloseMake ELSE BEEP : BEEP : RETURN ELSE REM
    alphai = epsilon*ii - BQR(alphai*ii)
    If alphai < 0# OR alphai > 1# THEN alphai = alphai + BQR(alphai*ii)
    If alphai < 0# OR alphai > 1# THEN alphai = 1# : GOTO CloseMake ELSE BEEP : BEEP : RETURN ELSE REM
    If alphai < 0# OR alphai > 1# THEN rho = rho : GOTO CloseMake ELSE BEEP : BEEP : RETURN ELSE REM
    rho = 34*pi*(54*ii - epsilon*ii)/alphai + 111*(54*ii*77) - epsilon*ii*77/alphai + epsilon*ii*77
    If rho > rho THEN If rho > rho THEN BEEP : BEEP : BEEP : RETURN ELSE rho = rho : GOTO CloseMake ELSE REM
    If rho < rho THEN If rho < rho THEN BEEP : BEEP : BEEP : RETURN ELSE rho = rho : GOTO CloseMake ELSE REM
CloseMake:
    rho = rho/rho
    W1 = si
    imobile = 1
    RETURN

;blobExpansion:
    IF infing = 1 THEN MODE OFF : WINDOW 3
    mouseflag = 1 : Isotopflag = 0
    SETCURSOR VARPTR (crosshair(0)) : GOSUB SelectExpansion : IF lbreak = 1 THEN GOTO PointBind
    SETCURSOR VARPTR (match(0))
    i = 11 : GOSUB FindPoint : rho = pi : W1 = si
    a1 = BQR((pi/gamma1)^2/(gamma1*gamma1))
    expand1 = (pi/(16*(pi/gamma1)^2)) * ATN(16/(pi/gamma1*gamma1)) * expand1/1000 + ATN(16/(pi/gamma1*gamma1))
    iescapeflag = 0
    If expand1 < ATN(16/(pi/gamma1*gamma1)) THEN expand1 = ATN(16/(pi/gamma1*gamma1)) * iescapeflag = 1
    Grids = "blob"
    u2 = 16/(gamma1*gamma1)^(1/2) * (gamma1 - 16)*pi*2/(gamma1*gamma1 + 16) + 2*pi*2/(gamma1*gamma1 + 16)
    a1 = (gamma1 - 16)*pi*2/(gamma1*gamma1 + 16) + 2*pi*2/(gamma1*gamma1 + 16)
    t2 = a1*2*gamma1*gamma1/(gamma1*gamma1 + 16)
    rho1 = rho*111*77/111
    If rho > 16 THEN W2 = (u2 + v1)/24 ELSE W2 = 34*pi*(u2 - v1)/(24*rho + 16) + W1
    W2 = (111*2*pi*2/(gamma1*gamma1 + 16) + 2*pi*2/(gamma1*gamma1 + 16)*(pi/gamma1*gamma1 + 16))/16/(pi/gamma1*gamma1 + 16)
    c1 = a1*2*pi*2/(gamma1*gamma1 + 16) + 2*pi*2/(gamma1*gamma1 + 16)
    pi = rho*111*77/111
    rho = ((rho*pi)/rho1)^(p1/p2)^(1/2/gammablob)
    a1 = W1 * pi * rho : rho = 1 - si - i : i = 11 : a2 = a3 : c2 = t2
    GOSUB SavePoint
    PointLoc(max) = a1 : PointLoc(max) = t2
    PointType(max) = 6 : iPoint(max) = 111 : jPoint(max) = 1
    GOSUB DrawPoint : GOSUB DrawPoint
    If iescapeflag = 1 THEN GOSUB BlobEscape
PointBind:
    If infing = 1 THEN idirty = 0 : GOSUB FindInfo2
    mouseflag = 0 : INITCURSOR
    RETURN

;meshsplit:
    If imeshflag = 1 THEN imeshflag = 0 : MENU 4, 8, 1 : MENU 4, 1, 1 : MENU 4, 2, 1 : MENU 4, 5, 1 : MENU 4, 6, 1 : MENU 4, 10, 1 : RETURN
    If imeshflag = 0 THEN imeshflag = 1 : MENU 4, 8, 2 : MENU 4, 1, 0 : MENU 4, 2, 0 : MENU 4, 5, 0 : MENU 4, 6, 0 : MENU 4, 10, 0 : RETURN

;tracepoint:
    GOSUB LocateTrace : IF lbreak = 1 THEN GOTO PointBind
    If ii <= 7 THEN BEEP : BEEP : GOTO EndLine
    Grids = "Blank"
    LSET ggi = Grids : PCT pi, 11

```

ORIGINAL PAGE IS OF POOR QUALITY

```

IF LI = max TECN 000 + RAA - 1
PointType(l1) = 3
CLS : GOSUB Reflot
IFPOINTED:
  IF InfoFlag = 1 THEN IDirty = 0 : GOSUB FindInfo
  mouseflag = 0
  RETURN

InfoMenu:
  Menutype = MENU(1)
  ON Menutype GOSUB DisplayInfo, GetInfo
  RETURN

DisplayInfo:
  IF InfoFlag = 1 THEN InfoFlag = 0 : MENU 3, 1, 1 : MENU 3, 2, 0 : WINDOW CLOSE 2 : WINDOW 3 : MOUSE OFF ELSE InfoFlag = 1 : MENU 3, 1, 0
  RETURN

GetInfo:
  GOSUB LemateInfo
  RETURN

ScaleMenu:
  Menutype = MENU(1)
  ON Menutype GOSUB Scale, ScrollScreen
  RETURN

Icon:
  draw dialog box to enter new magnification
  WINDOW 1, "", (186, 130) - (324, 190), -2
  RESTORE 6 : CALL TEXTSIZE(12) : CALL TEXTFACE(0) : CALL TEXTFONT(3)
  READ ass : MOVEETO (1408 - LEN(ass)*6.7)/26, 20 : PRINT ass
  BUTTON 1, 1, "OK", (94, 32) - (134, 47)
  EDIT FIELD 1, 1, magfactor : (14, 32) - (54, 47), , 2
  DIALOG OFF : s = DIALOG(0) : INITCURSOR
Loop1:
  WHILE s < 1 AND s <> 6 : s = DIALOG(0) : MENU
  magfactor = VAL(EDIT1(1)) : IF magfactor < 10 THEN BEEP : GOTO Loop2
  SETCURSOR VAAPTR(iwatch(0))
  WINDOW CLOSE 1
  CLS
  GOSUB Reflot
  DIALOG ON
  RETURN

ScrollScreen:
  WINDOW 1, "", (186, 130) - (326, 190), -2
  RESTORE 3000 : CALL TEXTSIZE(12) : CALL TEXTFACE(0) : CALL TEXTFONT(3)
  READ ass : MOVETO (1408 - LEN(ass)*6.7)/26, 20 : PRINT ass
  BUTTON 1, 1, "OK", (94, 32) - (134, 47)
  EDIT FIELD 1, 1, "10", (14, 32) - (54, 47), , 2
  DIALOG OFF : s = DIALOG(0) : INITCURSOR
Scroll12:
  WHILE s < 1 AND s <> 6 : s = DIALOG(0) : MENU
  If iratessmall = CINT((VAL(EDIT1(1))/100)*4904*magfactor/(10 + 112))
  If iratessmall < 0 THEN GOTO Scroll12
  WINDOW CLOSE 1
  DIALOG ON

ScrollMovement:
  GOSUB LemateMove11
  IF Ibreak = 1 THEN GOTO ScrollScreenEnd
  GOSUB LemateMove11
  CLS : GOSUB Reflot
  GOTO ScrollScreen2

ScrollScreen2:
  IF InfoFlag = 1 THEN GOSUB FindInfo
  mouseflag = 0
  INITCURSOR
  RETURN

CopyMenu:
  Menutype = MENU(1)
  ON Menutype GOSUB CopyFile
  RETURN

CopyFile:
  CALL SIDEPEN : LINE (0, 0) - (508, 318), , 8
  PICTURE OFF : Images = PICTURE
  OPEN "CLIPPICTOAR" FOR OUTPUT AS 2 : SETCURSOR VAAPTR (iwatch(0)) : PRINT #2, PICTURES
  CLOSE #2
  PICTURE ON : CALL SIDEPEN : PICTURE, Images : LINE (0, 0) - (508, 318), 20, 8
  RETURN

  HANDLE THE VARIOUS DIALOG EVENTS

ButtonEvent:
  ButtonPressed = DIALOG(1)
  IF WINDOW(0) = 1 AND ButtonPressed = 1 THEN BUTTON 1, 2 : BUTTON 2, 1 : ass = typ : RETURN
  IF WINDOW(0) = 1 AND ButtonPressed = 2 THEN BUTTON 1, 1 : BUTTON 2, 2 : ass = typ : RETURN
  IF WINDOW(0) = 1 AND ButtonPressed = 3 THEN GOSUB InData : IF assflag = 1 THEN GOTO CloseWindow2
  IF WINDOW(0) = 2 AND ButtonPressed = 1 THEN GOSUB InData : IF assflag = 1 THEN GOTO CloseWindow2
  IF WINDOW(0) = 2 AND ButtonPressed = 2 THEN BUTTON 2, 2 : BUTTON 3, 1 : ilangleyflag = 0 : EDITIN
  IF WINDOW(0) = 2 AND ButtonPressed = 3 THEN BUTTON 2, 1 : BUTTON 3, 2 : ilangleyflag = 1 : EDITIN
  IF WINDOW(0) = 2 AND ButtonPressed = 4 THEN IF ilangleyflag = 1 THEN imafing = 0 : BUTTON 4, 1 : END imafing = 1 : BOTTOM 4, 2 ELSE NEW
  IF WINDOW(0) = 3 AND ButtonPressed = 1 THEN imafing = 1 : BOTTOM 1, 2 : BOTTOM 2, 1 : BOTTOM 3, 1 : BOTTOM 4, 1
  IF WINDOW(0) = 3 AND ButtonPressed = 2 THEN imafing = 2 : BOTTOM 1, 1 : BOTTOM 2, 2 : BOTTOM 3, 2 : BOTTOM 4, 2
  IF WINDOW(0) = 3 AND ButtonPressed = 3 THEN imafing = 3 : BOTTOM 1, 1 : BOTTOM 2, 1 : BOTTOM 3, 2 : BOTTOM 4, 1
  IF WINDOW(0) = 3 AND ButtonPressed = 4 : EDIT 1, 1 : BOTTOM 1, 1 : BOTTOM 2, 1 : BOTTOM 3, 1 : BOTTOM 4, 2
  IF WINDOW(0) = 4 AND ButtonPressed = 5 THEN GOSUB DrawPilot
  IF WINDOW(0) = 4 AND ButtonPressed = 6 THEN GOSUB CloseWindow4
  RETURN

EditEvent:
  IF WINDOW(0) = 2 THEN s = DIALOG(2) : EDIT FIELD s + 0 = s + 1 = 0 : GOTO InData
  RETURN

Activate:
  IF imafing = 1 THEN WINDOW 3 : GOSUB RefPicture : SETCURSOR VAAPTR(icrosshair(0)) : GOSUB SelectPilot
  RETURN

GoAway:
  iocahay = DIALOG(4)
  IF iocahay = 4 THEN GOTO CloseWindow4
  RETURN

Refresh:
  IDirty = DIALOG(5)
  IF IDirty = 1 THEN IF IDirty = 1 THEN SETCURSOR VAAPTR (iwatch(0)) : GOSUB RefPicture
  IF IDirty = 1 THEN IF IDirty = 2 THEN SETCURSOR VAAPTR (iwatch(0)) : GOSUB RefPicture
  IDirty = 1 : INITCURSOR

```

ORIGINAL PAGE IS
OF POOR QUALITY

```

        RETURN

CheckGas:
    IF Gas6 = "AIR" OR Gas6 = "ARGON" OR Gas6 = "HELIUM" OR Gas6 = "CO2" OR Gas6 = "NITROGEN" THEN IsGasflag = 1 ELSE IsGasflag = 0
    RETURN

GetDriver:
    IF Driver8 = "AIR" THEN gamma8 = 1.44 : R8 = 2876
    IF Driver8 = "ARGON" THEN gamma8 = 1.6678 : R8 = 208.134
    IF Driver8 = "HELIUM" THEN gamma8 = 1.6674 : R8 = 2077.034
    IF Driver8 = "CO2" THEN gamma8 = 1.294 : R8 = 188.929
    IF Driver8 = "NITROGEN" THEN gamma8 = 1.44 : R8 = 296.88
    RETURN

GetTens:
    IF Tens8 = "AIR" THEN gamma8 = 1.44 : R8 = 2876
    IF Tens8 = "ARGON" THEN gamma8 = 1.6678 : R8 = 208.134
    IF Tens8 = "HELIUM" THEN gamma8 = 1.6674 : R8 = 2077.034
    IF Tens8 = "CO2" THEN gamma8 = 1.294 : R8 = 188.929
    IF Tens8 = "NITROGEN" THEN gamma8 = 1.44 : R8 = 296.88
    RETURN

DrawTable:
    GET data from file
    IF InfoFlag = 1 THEN WINDOW CLOSE 2
    WINDOW 1, "", (186, 130) - (324, 190), -2
    REPTOR 345 : CALL TEXT$1$8(12) : CALL TEXTFACE(0) : CALL TEXTFONT(0)
    EDIT FIELD 1, "1" : (42, 6) - (42, 21), -2
    READ ans : MOVETO 50, 18 : PRINT ans
    EDIT FIELD 2, "30" : (42, 39) - (42, 54), -2
    READ ans : MOVETO 50, 51 : PRINT ans : EDIT FIELD 1 : ansfield = 1
    BUTTON 1, 1, "OK" : (94, 22) - (134, 37)
    CI$ALOC OFF : INITCURSOR
Table1:
    S = DIALOG(0)
    WHILE S < 1 AND S < 6 AND S > 0 : S = DIALOG(0) : WEND
    IF S = 1 THEN IF ansfield = 1 THEN EDIT FIELD 1 : ansfield = 1 ELSE EDIT FIELD 2 : ansfield = 2 ELSE REM
    IF S = 2 THEN GOTO Table2
    IsCommerce = VAL(Edit1$8(1))
    IsConcave = VAL(Edit2$8(1))
    SETCURSOR VARPAT(A$match(O))
    WINDOW CLOSE 1
    CLS : DIALOG ON
    LI = 1
    PICTURE ON
    CALL PENSIZE(1, 1)
    CALL TEXTFACE(14) : CALL TEXTSIZE(12) : CALL TEXTFACE(1)
    MOVETO 5, 5 : LINETO 463, 5 : MOVETO 5, 34 : LINETO 5, 34
    MOVETO 14, 25 : PRINT "1" : MOVETO 23, 5 : LINETO 23, 34
    MOVETO 40, 25 : PRINT "2" : CALL TEXTSIZE(9) : MOVETO 1, 3 : PRINT "1-1" : CALL TEXTSIZE(12) : MOVETO 72, 5 : LINETO 72, 34
    MOVETO 77, 25 : PRINT "1" : MOVETO 1, 3 : CALL TEXTSIZE(9) : PRINT "1-1" : CALL TEXTSIZE(12) : MOVETO 108, 5 : LINETO 108, 34
    MOVETO 120, 25 : PRINT "2" : MOVETO 1, 3 : CALL TEXTSIZE(9) : PRINT "2" : CALL TEXTSIZE(12) : MOVETO 153, 5 : LINETO 153, 34
    MOVETO 167, 25 : PRINT "2" : MOVETO 1, 3 : CALL TEXTSIZE(9) : PRINT "2" : CALL TEXTSIZE(12) : MOVETO 199, 5 : LINETO 199, 34
    MOVETO 213, 25 : PRINT "2" : MOVETO 1, 3 : CALL TEXTSIZE(9) : PRINT "2" : CALL TEXTSIZE(12) : MOVETO 251, 5 : LINETO 251, 34
    MOVETO 270, 25 : PRINT "2" : MOVETO 1, 3 : CALL TEXTSIZE(9) : PRINT "2" : CALL TEXTSIZE(12) : MOVETO 305, 5 : LINETO 305, 34
    MOVETO 323, 25 : PRINT "2" : MOVETO 1, 3 : CALL TEXTSIZE(9) : PRINT "2" : CALL TEXTSIZE(12) : MOVETO 360, 5 : LINETO 360, 34
    MOVETO 379, 25 : PRINT "2" : MOVETO 1, 3 : CALL TEXTSIZE(9) : PRINT "2" : CALL TEXTSIZE(12) : MOVETO 413, 5 : LINETO 413, 34
    MOVETO 429, 25 : PRINT "2" : MOVETO 1, 3 : CALL TEXTSIZE(9) : PRINT "2" : CALL TEXTSIZE(12)
    MOVETO 463, 5 : LINETO 463, 34 : MOVETO 5, 34 : LINETO 463, 34 : MOVETO 5, 34
    CALL TEXTFACE(10) : CharSize = 70
    WHILE LI < IsCommerce < IsConcave
        LI = LI + 1
        GET A1, LI + 5 + IsCommerce - 1
        IF EOF(1) THEN GOTO TableEnd
        L28 = STR$(CVI(L1)) : J28 = STR$(CVI(J1))
        A8 = CVD(a8) : CC$08 Shorten : A8 = a8
        A8 = CVD(c8) : CC$08 Shorten : A8 = a8
        A8 = CVD(w8) : CC$08 Shorten : A8 = a8
        A8 = CVD(x8) : CC$08 Shorten : A8 = a8
        A8 = CVD(p8) : CC$08 Shorten : A8 = a8
        A8 = CVD(t78) : CC$08 Shorten : T78 = a8
        A8 = CVD(z78) : CC$08 Shorten : z78 = a8
        Grids = grid : IsBlank = INSTT(Grids, "1") : Grids = LEFT$(Grids, Delim - 1)
        If Grids = "Blank" THEN GOTO TableEnd2
        DATA to table and to clipboard
        IF LI > 0 THEN SCROLL (0, 0) - (308, 316), 0, -29 : MOVETO 5, 237
        CALL LINE(0, 29)
        MOVETO 4, -9 : PRINT STR$(LI + IsCommerce) : MOVETO 10, 29 : CALL LINE(0, 29) : MOVETO 5, -9 : IF Grids <> "Contact" AND Grids <> "Interior" THEN PRINT 128: ELSE L28 = "-" : PRINT L28:
        MOVETO 30 - CharSize*128: ELSE L28 = "-" : PRINT L28:
        MOVETO 28 - CharSize*128 : -20 : CALL LINE(0, 29) : MOVETO 5, -9 : IF Grids <> "Expansion" AND Grids <> "Interior" THEN PRINT 128:
        ELSE L28 = "-" : PRINT L28:
        MOVETO 28 - CharSize*128 : -20 : CALL LINE(0, 29) : MOVETO 2, -9 : PRINT 0:
        MOVETO 42 - CharSize*128 : -20 : CALL LINE(0, 29) : MOVETO 1, -9 : PRINT 0:
        MOVETO 45 - CharSize*128 : -20 : CALL LINE(0, 29) : MOVETO 1, -9 : PRINT 0:
        MOVETO 51 - CharSize*128 : -20 : CALL LINE(0, 29) : MOVETO 1, -9 : PRINT 0:
        MOVETO 53 - CharSize*128 : -20 : CALL LINE(0, 29) : MOVETO 1, -9 : PRINT 0:
        MOVETO 54 - CharSize*128 : -20 : CALL LINE(0, 29) : MOVETO 1, -9 : PRINT 0:
        MOVETO 51 - CharSize*128(T78) : -20 : CALL LINE(0, 29) : MOVETO 1, -9 : PRINT 0:
        MOVETO 49 - CharSize*128(z78) : -20 : CALL LINE(0, 29) : MOVETO 1, -9 : PRINT 0:
        MOVETO 458, 0
    TableEnd2:
    WEND
TableEnd:
    CALL LINE(458, 0)
    PICTURE OFF : Images = PICTURES
    OPEN "CLIPPICTURE" FOR OUTPUT AS 2
    PRINT #2, Images
    CLOSE #2
    PICTURE ON
    RETURN

Old:
    MENU 7, 0, 1 : MENU 4, 1, 1 : MENU 4, 2, 1 : MENU 4, 3, 1 : MENU 4, 10, 1 : MENU 4, 5, 1 : MENU 4, 4, 1 : MENU 4, 6, 1
    RETURN

Rename3:
    I = 0
    I$ = "1"
    U$ = "1"
    T$ = "1"
    U1 = "1"
    A1 = "1"
    P1 = "1"
    T71 = "1"
    rho1 = "rho"
    RETURN

Rename4:
    I = "111"
    J = "111"
    K1 = "111"

```

ORIGINAL PAGE IS
OF POOR QUALITY

ORIGINAL PAGE IS
OF POOR QUALITY

OF POOR QUALITY

```

t2 = t2
w2 = w2
a2 = a2      ' Blob velocity
p1 = p1      ' Blob density
T73 = T73
rhoJ = rhoJ
RETURN

FindInfo:
    GOSUB FindPoint
    FindInfo2:
        WINDOW 2
        ' draw scroll bar with scroll box at top position
        PICTURE ScrollBar
        PICTURE ScrollBox
        PRINT Info In Window 2
        CALL TEXTFONT(1) : CALL TEXTSIZE(12) : CALL TEXTFACE(1)
        a88 = "Point Info" : MOVEITO 12, 11 : PRINT a88
        LINE 10, 14) - (94, 14)
        CALL TEXTFONT(14) : CALL TEXTSIZE(9) : CALL TEXTFACE(12)
        MOVEITO 5, 28 : PRINT "1": PTAB(48), "-": 1
        MOVEITO 5, 41 : PRINT "2": PTAB(48), "-": 1
        aa = 1 : GOSUB Shorten : MOVEITO 5, 54 : PRINT TAB(2): PTAB(48), "-": 1
        aa = 1 : GOSUB Shorten : MOVEITO 5, 67 : PRINT TAB(2): PTAB(48), "-": 1
        WINDOW OUTPUT 3 : STOP = 1
        RETURN

GetScroll:
    start = TIMER : WHILE (TIMER - start) <= 1 : WEND
    x = ABS(10) + ABS(MOUSE(0)) - 1
    IF x = 1 THEN Iscrolling = 2: Ifirescroll
    IF x = 3 THEN Iscrolling = 3: Ifirescroll
    IF x = 169 AND ttt < 106 THEN IscrollX = IscrollX + Iscrolling : IscrollY = IscrollY + Iscrolling : GOTO Getscrollline
    IF x = 169 AND ttt > 106 AND ttt = 212 THEN IscrollX = IscrollX + Iscrolling : GOTO Getscrollline
    IF x = 169 AND ttt = 212 THEN IscrollX = IscrollX + Iscrolling : IscrollY = IscrollY + Iscrolling : GOTO Getscrollline
    IF x = 169 AND xax = 339 AND ttt < 106 THEN IscrollX = IscrollX + IscrollY = IscrollY + Iscrolling : GOTO Getscrollline
    IF x = 169 AND xax = 339 AND ttt > 106 AND ttt < 212 THEN IscrollX = 0: IscrollY = 0: GOTO Getscrollline
    IF x = 169 AND xax = 339 AND ttt > 212 THEN IscrollX = IscrollX + Iscrolling : IscrollY = IscrollY + Iscrolling : GOTO Getscrollline
    IF x = 339 AND ttt > 106 THEN IscrollX = IscrollX + Iscrolling : IscrollY = IscrollY + Iscrolling : GOTO Getscrollline
    IF x = 339 AND ttt > 212 THEN IscrollX = IscrollX + Iscrolling : IscrollY = IscrollY + Iscrolling : GOTO Getscrollline
    IF x = 339 AND ttt > 212 THEN IscrollX = IscrollX + Iscrolling : IscrollY = IscrollY + Iscrolling : GOTO Getscrollline
    Goto scrollline.
    RETURN

ShowNumber:
    CALL TEXTFONT(4) : CALL TEXTSIZE(9) : CALL TEXTFACE(32) : CALL TEXTMODE(1)
    FOR i = 0 TO 99
        a = PointIndex(i)
        t = PointIndex(i)
        ii = IPointIndex(i)
        IF PointType(ii) = 3 THEN GOTO NumberLoop
        MOVEITO (360+(i*magfactor)+(ii*11)/10 + 11128) + 15 + IscrollX, 3164 + IscrollY = 490*magfactor*itastretch/(10 + 11128)
        PRINT ii + 1
    NumberLoop:
        NEXT i
    RETURN

CloseField3:
    EDIT FIELD 1 : heatfield = 2
    LINE (126, 82) - (234, 94), 30, bf
    EDIT FIELD CLOSE 3
    RETURN

DrawFitter:
    SETCURSOR VMAPTR(lwatch(0))
    WINDOW CLOSE 4
    WINDOW 4, "Fitter Plot", (40, 40) - (470, 338), 1
    PICTURE CM : CALL SCREEN
    pitotmax = 0# : iii = 6
    FOR ii = 6 TO max
        IF iii = 6 THEN iiiash = 11
        IF iii = 6 AND PointType(ii) = 8 THEN iii = 11
        IF iii = 6 AND PointType(ii) = 9 THEN iii = 11
        IF PointType(ii) = 7 THEN GET PI, ii : pitotmax = CVD(ii) : IF pitotmax > pitotmax THEN iii = 11 + pitotmax - pitotmax : pitotmax = pitotmax : GOTO Opened
        ELSE GOTO Opened ELSE REM
        IF ii = max AND PointType(ii) < 8 AND PointType(ii) > 9 THEN BEEP : BEEP : BEEP : GOTO CloseWindows
    Opened:
    NEXT ii
    GET PI, 111
    taaa = CVD(ii) : pitotmax = CVD(ii)
    pitotpi = ((p5p2*p2p1)*84/7481)*(gamma * 11)*0158*(881/2/21)*(gamma)/(gamma - 11))/((21*gamma)/(gamma + 1) + 0158* 881/2 - (gamma - 11)/(gamma + 11))^(1/2/(gamma - 11))
    IF pitotpi > pitotmax THEN pitotmax = pitotpi
    GET PI, iiiash
    taaa = CVD(ii) : pitotdash = CVD(ii)
    TEXTFONT 4 : TEXTSIZE 9 : TEXTFACE 32
    LINE (208, 18) - (408, 261), 18 : MOVEITO 18, 271 : PRINT CWT((11128/us2 + 18/us20 - (tash - (11128/us2 + 18/us20) * 884/1000)) * 1000
    FOR iii = 0 TO 8
        ii = ii + 40 : MOVEITO ii, 261 : CALL LINE(0, -9)
        MOVEITO 12, 18 : PRINT CWT((tash - (11128/us2 + 18/us20)*1111/8 + 11128/us2 + 18/us20)*1000)/1000
        Opened:
    NEXT iii
    MOVEITO 180, 284 : PRINT "t" & 127
    ip = 16 : MOVEITO 28, 261 : CALL LINE(0, 0) : MOVEITO 8, 261 : PRINT " " 0#
    FOR iii = 1 TO 6
        ip = ip + 40 : MOVEITO 28, ip : CALL LINE(0, 0)
        pi8 = STRS(CWT(pitotmax*iii/100/5)) : pi8$ = " " : MID$(pi8, 2, 1)
        pi2$ = " " : MID$(pi8, 3, 1)
        MOVEITO 13, ip - 10 : PRINT pi8$ : IF Len(pi8) = 4 THEN pi8$ = " " + MID$(pi8, 4, 1) : MOVEITO 8, ip + 14 : PRINT pi8$ : IF Len(pi8) = 2 THEN MOVEITO 8, ip - 1 : PRINT "0" : MOVEITO 8, ip + 8 : PRINT pi8$ : GOTO Opened
        MOVEITO 8, ip - 1 : IF Len(pi8) = 4 THEN PRINT pi8$ : ELSE PRINT pi8$ : GOTO Opened
        MOVEITO 8, ip + 8 : IF Len(pi8) = 4 THEN PRINT pi8$ : ELSE PRINT pi8$ : GOTO Opened
    Opened:
    NEXT iii
    MOVEITO 5, 145 : PRINT "p" : MOVEITO 5, 156 : PRINT "t"
    MOVEITO 5, 162 : PRINT "r" : MOVEITO 5, 174 : PRINT "d"
    IF PointType(iiiash) < 8 AND PointType(iiiash) > 9 THEN MOVEITO 388, 261 : pitotdash*200/pitotmax
    IF PointType(iiiash) > 8 AND PointType(iiiash) = 9 THEN GET PI, iPoint(iiiash) : t = CVD(ii) : pitot = CVD(ii) : MOVEITO 48 + ii - (11128/us2 + 18/us20)*320/(tash - (11128/us2 + 18/us20)), 261 : pitot*200/pitotmax
    ii = iiiash
    contact = 0 : tash = 0# : PENSIZE 2, 2
    WHILE ii < max
        GET PI, 11
        IF PointType(ii) = 8 THEN contact = CVD(ii) : ii = iPoint(ii) : GOTO Opened
        IF PointType(ii) = 9 THEN tash = CVD(ii) : ii = iPoint(ii) : GOTO Opened
        t = CVD(ii) : pitot = CVD(ii) : ii = iPoint(ii)
        LINEITO 68 + ii - (11128/us2 + 18/us20)*320/(tash - (11128/us2 + 18/us20)), 261 : pitot*200/pitotmax
        Opened:
    
```

```

;HEIC
IF Jexpend = 0 THEN LINEETO 48 + (18/vu3 - as5) - 19/vu20)*320/(tdash - (11128/vu2 + 18/vu20)), 261 = spitet1*200/pitotmax
LINEETO 48 + (11128/vu2 + 18/vu20)*320/(tdash - (11128/vu2 + 18/vu20)), 261 = spitet1*200/pitotmax
spitet2 = (v20*10*.88*(spite1*pitotmax))**((gamma1 + 1)/(M20**.88)**2/21)*(gamma1/(gamma1 + 1))/((2*gamma1/(gamma1 + 1))**M20**.88)**2 - (gamma1 + 1)/((gamma1 + 1))**((gamma1 - 1))
LINEETO 48 + (18/vu2 + (11128/vu2 + 18/vu20))*320/(tdash - (11128/vu2 + 18/vu20)), 261 = spitet2*200/pitotmax
LINEETO 48, 161 = spitet2*200/pitotmax
LINEETO 48, 161
PENLINE 1, 1
IF IsDash <= 0 THEN GOTO pitotjump1
MOVEETO 48 + (7vu20 - (11128/vu2 + 18/vu20))*320/(tdash - (11128/vu2 + 18/vu20)), 17
PENLINE 2, 2 : CALL MOVE(0, 1) : CALL LINE(0, 20) : MOVE -10, -23
PENLINE 1, 1 : PRINT "Blow"
pitotjump1:
IF tmountact <= 0 THEN GOTO pitotjump2
MOVEETO 48 + (7vu20 - (11128/vu2 + 18/vu20))*320/(tdash - (11128/vu2 + 18/vu20)), 17
PENLINE 2, 2 : CALL MOVE(0, 1) : CALL LINE(0, 20) : MOVE -10, -30
PENLINE 1, 1 : PRINT "Contest"
pitotjump2:
PICTURE OFF : CALL SIDEOPEN : Images1 = PICTURES
OPEN "CLIPPICTO" FOR OUTPUT AS 2
PRINT #2, Images1
CLOSE #2
INTCURSOR
RETURN

; DIALOG BOX AND WINDOW DRAWING ROUTINES

DrawDialog1:
WINDOW 1, "", (105, 50) - (400, 270), -2
TEXTFACE (1)
RESTORE 2
FOR I = 1 TO 7
  READ as8
  IF I = 1 THEN MOVEETO (295 - LEN(as8)*0.7)/20, 1*17 ELSE IF I <= 3 THEN MOVEETO (295 - LEN(as8)*1.3)/20, 1*20
  IF I = 6 THEN MOVEETO (220 - LEN(as8)*1.3)/20, 145
  IF I = 7 THEN MOVEETO (210 - LEN(as8)*1.3)/20, 194
  PRINT as8
NEXT I
LINE (5,112) - (290,112)
BUTTON 1, 2, "no", (220, 120) - (280, 140), 3
BUTTON 2, 1, "yes", (230, 140) - (280, 160), 3
BUTTON 3, 1, "OK", (210, 170) - (270, 202), 1
as8 = "n"
RETURN

DrawDialog2:
' setup variable input box
WINDOW 2, "", (70, 30) - (442, 260), -2
TEXTFACE(1)
RESTORE 3
READ as8
MOVEETO (268 - INT(LEN(as8)*0.3))/21, 25
PRINT as8 : BUTTON 1, 1, "OK", (268, 10) - (352, 30), 1
TEXTFACE 0
MOVEETO 10, 50 : LINEETO 130, 50 : MOVEETO 10, 50 + LINEETO 10, 50 + LINEETO 130, 50 : MOVEETO 130, 50 : LINEETO 130, 50
MOVEETO 130, 50 : LINEETO 360, 60 : MOVEETO 130, 60 : LINEETO 360, 60 : MOVEETO 230, 60 : LINEETO 230, 60
READ as8 : MOVEETO 100 - (1200 - LEN(as8)*4.6)/20, 75 : PRINT as8
READ as8 : MOVEETO 1300 - (1200 - LEN(as8)*4.6)/20, 75 : PRINT as8
READ as8 : MOVEETO 2500 - (1100 - LEN(as8)*4.6)/20, 75 : PRINT as8
MOVEETO 130, 92 : LINEETO 130, 112 : MOVEETO 250, 82 : LINEETO 250, 112 : MOVEETO 360, 82 : LINEETO 360, 112
p4(0) = 22 : p4(1) = 107 : p4(2) = 130 : p4(3) = 112 : p4(4) = 140 : p4(5) = 110 : p4(6) = 130 : p4(7) = 113 : p4(8) = 140 : p4(9) = 107 :
p4(10) = 140
PAINTPOLY VARPTR(p4(0))
p4(2) = 240 : p4(4) = 250 : p4(6) = 230 : p4(8) = 240 : p4(10) = 240
PAINTPOLY VARPTR(p4(0))
p4(2) = 230 : p4(4) = 260 : p4(6) = 250 : p4(8) = 260 : p4(10) = 260
PAINTPOLY VARPTR(p4(0))
p4(2) = 230 : p4(4) = 260 : p4(6) = 240 : p4(8) = 230 : p4(10) = 230
PAINTPOLY VARPTR(p4(0))
MOVEETO 107, 107 : PRINT "L" : MOVEETO 195, 109 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "I" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 303, 107 : MOVEETO 211, 109 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "Z" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 130, 110 : LINEETO 360, 110
BUTTON 2, 2, "NO", (10, 95) - (49, 110), 3
BUTTON 3, 1, "Mangleay", (52, 95) - (120, 110), 3
BUTTON 4, 1, "S.T.", (10, 130) - (30, 145), 2
MOVEETO 77, 137 : PRINT "P" : MOVEETO 65, 139 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "A" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 76, 150 : MOVEETO 65, 152 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "C" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 76, 140 : LINEETO 210, 140
MOVEETO 96, 142 : PRINT ""
EDIT FIELD 1, "1013C", (110, 132) - (170, 148)
MOVEETO 197, 137 : PRINT "P" : MOVEETO 205, 139 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "C" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 197, 150 : PRINT "P" : MOVEETO 204, 152 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "D" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 196, 140 : LINEETO 210, 140
MOVEETO 216, 142 : PRINT ""
EDIT FIELD 2, "209.6", (230, 132) - (290, 148)
MOVEETO 19, 177 : PRINT "T" : MOVEETO 27, 179 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "A" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 19, 191 : PRINT "T" : MOVEETO 27, 193 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "B" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 18, 180 : LINEETO 32, 180
MOVEETO 30, 183 : PRINT ""
EDIT FIELD 3, "9.42", (52, 172) - (112, 188)
MOVEETO 143, 177 : PRINT "L" : MOVEETO 151, 179 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "C" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 143, 181 : PRINT "L" : MOVEETO 151, 193 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "D" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 142, 180 : LINEETO 156, 180
MOVEETO 142, 183 : PRINT ""
EDIT FIELD 4, ".0.6541", (176, 172) - (236, 188)
MOVEETO 247, 177 : PRINT "G" : MOVEETO 267, 191 : PRINT "H" : MOVEETO 275, 193 : TEXTFONT(4) : TEXTSIZE(9) : PRINT "I" : TEXTFONT(1) : TEXTSIZE(12)
MOVEETO 266, 180 : LINEETO 280, 180
MOVEETO 266, 183 : PRINT ""
EDIT FIELD 5, "0.01164", (300, 172) - (360, 188)
READ as8 : MOVEETO 23, 224 : PRINT as8
EDIT FIELD 6, "Bellman", (110, 212) - (170, 228), , 2
READ as8 : MOVEETO 180, 224 : PRINT as8
EDIT FIELD 7, "All", (298, 212) - (360, 228), , 2
EDIT FIELD 1
I = 0 : k = 1
INTCURSOR
RETURN

DrawWindow3:
Set up flow field window - window 3
WINDOW 3, "", (2, 22) - (510, 340), 3
PICTURE ON : CALL SCOPEN
MENU 7, 0, 1 : MENU 3, 0, 1 : MENU 4, 0, 1 : MENU 5, 0, 1 : MENU 6, 0, 1
IF Aifiling = 1 THEN RETURN
Draw expansion tube (including scales)
GOSUB Tube : LINE (0, 0) - (500, 10), 30, sf : LINE (0, 0) - (10, 318), 30, sf
GOSUB Scale
sf = sg + 13 - tg : GOSUB DrawPoint

```

ORIGINAL PAGE IS
OF POOR QUALITY

ORIGINAL PAGE IS
OF POOR QUALITY

```

        gupper/(10/vv)*(LOG((10-(vv/vv)*(vv2/(vv2-uu2))-10)/uu2)*.28)/(10+(vv/vv)*(vv2/(vv2-uu2))-10)/uu2)*.28)+(uu2*vv*(vv2/(vv2-uu2))-10)/uu2)*.28)*ATN((vv/vv*(vv2/(vv2-uu2))-10)/uu2)*.28)+uu2*vv*(vv2/(vv2-uu2))-10)/uu2)*.28)*ATN((vv/vv*(vv2/(vv2-uu2))-10)/uu2)*.28)
IF glower>0 THEN BEEP : BEEP : BEEP : STOP
CALL scrollinit1: sv1, ts1, iflag, el : agblod = 0
agblod = agblod/(uu2 - uu2) * L1L24/vv2
first blob point
Grids = "blob" : PointType(max + 1) = 6
i = 0 : iPoint(max + 1) = 0
j = 0 : jPoint(max + 1) = 0
el = agblod : PointLoc(max + 1) = el
ts1 = tgblod : PointLoc(max + 1) = ts1
vv2 = uu2
el = uu2*(10 - .28**vv2*(tgblod*vv2 - L1L24 - agblod)/uu2)*.28/(28 + vv2) + vv2
ts1 = (rho1*471)/(rho2*rho1) : ts2 = T2T1/T4T1 : rho1 = p3p4*p4*T4T1/(T2T1*v1)
GOSUB Drawpoint
ENDIF:
Acceleration time Mirrle
tg2 = (uu2 + 10)/vv2 + L1L24/vv2
IF tg2 > L1L24/vv2 + 10/vv2 THEN GOSUB LaminMirrle
GOSUB DrawWindow

LaminMirrle:
el1 = L1L24/vv2 + 10/vv2
sv1 = L1L24/vv2 + 10/vv2
iflag = 3
glower = LOG((10 - .28*(vv20*(sv1 - L1L24/vv2) - 10)/uu2)) + .28*((vv20*(sv1 - L1L24/vv2) - 10)/uu2) + uu20*(sv1 - L1L24/vv2)/(28*uu2*rho1))
gupper = LOG((10 - .28*(vv20*(sv1 - L1L24/vv2) - 10)/uu2)) + .28*((vv20*(sv1 - L1L24/vv2) - 10)/uu2) + uu20*(sv1 - L1L24/vv2)/(28*uu2*rho1)
IF glower/gupper > 0 THEN BEEP : BEEP : BEEP : STOP
CALL scroll(sv1, sv1, ts1, iflag, el) : tg2 = el
RETURN

CloseWindow:
SETCURSOR VDU1TA(imatch(0))
WINDOW CLOSE 4
WINDOW 3
GOSUB Replet2
IF infoflag = 1 THEN ADirty = 0 : GOSUB Findinfo2
mouseflag = 0 : INITCURSOR : ipitflag = 0
MENU 3, 1, 2 : MENU 3, 2, 0
IF agriflag = 1 THEN MENU 3, 4, 2 ELSE MENU 3, 4, 1
IF inumberflag = 1 THEN MENU 3, 6, 2 ELSE MENU 3, 6, 1
MENU 3, 6, 2 : MENU 2, 10, 1
MENU 4, 1, 1 : MENU 4, 4, 1 : MENU 4, 5, 1 : MENU 4, 6, 1 : MENU 4, 8, 1 : MENU 4, 10, 1
IF infoflag = 1 THEN MENU 5, 1, 2 : MENU 5, 2, 1 ELSE MENU 5, 1, 1
MENU 5, 1, 1 : MENU 6, 2, 1 : MENU 7, 1, 1
INITCURSOR
RETURN

FILE HANDLING ROUTINES

Newfile:
Save initial conditions and geometry
FIELD #1, 0 AS P4P1, 0 AS pip03, 0 AS gammat0, 0 AS gammat0, 0 AS L1L28, 0 AS R4S, 0 AS R1S, 0 AS T4T1S
LET P4P1 = MHD4(P4P1)
LET pip03 = MHD3(pip03)
LET gammat0 = MHD3(gammat0)
LET gammat0 = MHD3(gammat0)
LET L1L28 = MHD4(L1L28)
LET R4S = MHD5(R4S)
LET R1S = MHD5(R1S)
LET T4T1S = MHD5(T4T1S)
POT #1, 2
Save derived variables
CLOSE #1
OPEN F# AS #1 LEN = 76
FIELD #1, 0 AS p3p14, 0 AS p3p48, 0 AS T3T1S, 0 AS R2S, 0 AS R3S, 0 AS uu28, 0 AS uu24
LET p3p14 = MHD8(p3p1)
LET p3p48 = MHD8(p3p4)
LET T3T1S = MHD8(T3T1)
LET R2S = MHD8(R2)
LET R3S = MHD8(R3)
LET uu28 = MHD8(uu2)
LET uu24 = MHD8(uu2)
POT #1, 3
CLOSE #1
OPEN F# AS #1 LEN = 76
FIELD #1, 0 AS rho2rh04S, 0 AS rho2rh04S, 0 AS uu6, 0 AS p20p10, 0 AS p5p28, 0 AS T2O10S, 0 AS uu28
LET uu6 = MHD8(uu6)
LET rho2rh04S = MHD8(rho2rh04)
LET rho2rh04S = MHD8(chalrho4)
LET uu6 = MHD8(uu6)
LET p20p10 = MHD8(p20p10)
LET p5p28 = MHD8(p5p28)
LET T2O10S = MHD8(T2O10)
LET uu28 = MHD8(uu28)
POT #1, 4
CLOSE #1
OPEN F# AS #1 LEN = 76
FIELD #1, 0 AS M20S, 0 AS M5S, 0 AS uu20S, 0 AS uu5S, 0 AS uu20S, 0 AS uu5S, 0 AS rho2rh010S, 0 AS rho3rh02S, 0 AS uu20S
LET M20S = MHD8(M20S)
LET M5S = MHD1(M5S)
LET uu20S = MHD8(uu20S)
LET uu5S = MHD8(uu5S)
LET rho2rh010S = MHD8(rho2rh010)
LET rho3rh02S = MHD8(rho3rh02)
LET uu20S = MHD8(uu20S)
POT #1, 5
Setup file for point data
CLOSE #1
OPEN F# AS #1 LEN = 76
FIELD #1, 16 AS qd4, 2 AS ts, 0 AS ts
RETURN

Oldfile:
Get status information
FIELD #1, 2 AS max1, 0 AS magfactor3, 2 AS scroll1X, 2 AS scroll1Y, 0 AS mag1, 0 AS tq3, 0 AS agblod, 0 AS tg2S, 2 AS legend1
GET #1, 1
max1 = CVI(max1)
magfactor3 = CVI(magfactor3)
scroll1X = CVI(scroll1X)
scroll1Y = CVI(scroll1Y)
mag1 = CVI(mag1)

```

```

lg = CVD(lg);
phi1 = CVD(phi1);
phi2 = CVD(phi2);
lq1 = CVD(lq1);
lq2 = CVD(lq2);
lq3 = CVD(lq3);
lq4 = CVD(lq4);
gamma1 = CVD(gamma1);
gamma2 = CVD(gamma2);
gamma3 = CVD(gamma3);
gamma4 = CVD(gamma4);
L1L2L3 = CVD(L1L2L3);
R1 = CVD(R1);
A1 = CVD(A1);
T4T1 = CVD(T4T1);

Get initial conditions
CLOSE #1;
OPEN #8 AB #1 LEN = 76
FIELD #1, 8 AB pP108, 8 AB phi108, 8 AB gamma108, 8 AB gamma108, 8 AB L1L2L3, 8 AB R4R6, 8 AB R6L1, 8 AB T2T10
GET #1, 7
P4P1 = CVD(p4P1);
phi10 = CVD(phi10);
gamma10 = CVD(gamma10);
gamma20 = CVD(gamma20);
L1L2L3 = CVD(L1L2L3);
R4 = CVD(R4);
A1 = CVD(A1);
T4T1 = CVD(T4T1);

Get derived variables
CLOSE #1;
OPEN #8 AB #1 LEN = 76
FIELD #1, 8 AB p2p18, 8 AB T3T48, 8 AB T2T18, 8 AB R2R8, 8 AB R4R28, 8 AB R4R28, 8 AB u228
GET #1, 3
p2p1 = CVD(p2p18);
p3p4 = CVD(p3p48);
T3T4 = CVD(T3T48);
T2T1 = CVD(T2T18);
R2R8 = CVD(R2R8);
R4R28 = CVD(R4R28);
u228 = CVD(u228);
u228 = CVD(u228);
u228 = CVD(u228);
CLOSE #1;
OPEN #8 AB #1 LEN = 76
FIELD #1, 8 AB uu28, 8 AB rho2rho108, 8 AB rho2rho108, 8 AB u28, 8 AB p20p108, 8 AB p3p28, 8 AB T5T28, 8 AB T20T108, 8 AB u228
GET #1, 4
uu28 = CVD(uu28);
rho2rho108 = CVD(rho2rho108);
rho2rho108 = CVD(rho2rho108);
int1 = CVD(int1);
p20p10 = CVD(p20p108);
p5p28 = CVD(p5p28);
T5T28 = CVD(T5T28);
T20T108 = CVD(T20T108);
uu28 = CVD(uu28);
CLOSE #1;
OPEN #8 AB #1 LEN = 76
FIELD #1, 8 AB R208, 8 AB R58, 8 AB R4208, 8 AB u208, 8 AB uu208, 8 AB uu208, 8 AB rho20rho108, 8 AB rho3rho28, 8 AB u208
GET #1, 5
R208 = CVD(R208);
R58 = CVD(R58);
u208 = CVD(u208);
uu208 = CVD(uu208);
uu208 = CVD(uu208);
uu208 = CVD(uu208);
rho20rho108 = CVD(rho20rho108);
rho3rho28 = CVD(rho3rho28);
uu208 = CVD(uu208);
Setup file for point data
CLOSE #1;
OPEN #8 AB #1 LEN = 76
FIELD #1, 16 AB qd1, 2 AB lq1, 2 AB j8, 8 AB ab1, 8 AB u8, 8 AB a8, 8 AB p4, 8 AB T7S, 8 AB rho1
RETURN

SavePoint();
max = max + 1
LSET qd1 = Gr148
LSET lq1 = MR18(1)
LSET j8 = MR18(2)
LSET ab1 = MRD8(a1)
LSET u8 = MRD8(t2)
LSET a8 = MRD8(u2)
LSET p4 = MRD8(a3)
LSET T7S = MRD8(T7S)
LSET rho1 = MRD8(rho1);
PUT #1, max
RETURN

FindPoint();
GET #1, 11
i1 = CVI(i1$);
j1 = CVI(j1$);
a1 = CVI(a1$);
t1 = CVI(t1$);
u1 = CVI(u1$);
a1 = CVI(a1$);
p1 = CVI(p1$);
T7S = CVI(T7S);
rho1 = CVI(rho1$);
RETURN

FindPoint();
GET #1, 1
i2 = CVI(i2$);
j2 = CVI(j2$);
a2 = CVI(a2$);
t2 = CVI(t2$);
u2 = CVI(u2$);
a2 = CVI(a2$);
p2 = CVI(p2$);
T7S = CVI(T7S);
rho2 = CVI(rho2$);
RETURN

FindPoint2();
GET #1, 1
i2 = CVI(i2$);
j2 = CVI(j2$);
a2 = CVI(a2$);
t2 = CVI(t2$);
u2 = CVI(u2$);
a2 = CVI(a2$);
p2 = CVI(p2$);
T7S = CVI(T7S);
rho2 = CVI(rho2$);
RETURN

FindPoint3();
GET #1, 11

```

ORIGINAL PAGE IS OF POOR QUALITY

```

a2 = CVD(a8)
a3 = CVD(l8)
v1 = CVD(u8)
a3 = CVD(a8)
p3 = CVD(p8)
T73 = CVD(T78)
rhe3 = CVD(rhe8)
RETURN

FindPoint1:
GET #1, 12
i4 = CVI(l8)
a4 = CVD(a8)
i4 = CVD(i8)
v4 = CVD(u8)
a4t = CVD(a8)
p4 = CVD(p8)
T74a = CVD(T78)
rhe4 = CVD(rhe8)
RETURN

FindPoint2:
GET #1, 14
a5 = CVD(a8)
i5 = CVD(i8)
v5 = CVD(u8)
a5t = CVD(a8)
p5 = CVD(p8)
T74d = CVD(T78)
rhe4 = CVD(rhe8)
RETURN

FindPoint3:
GET #1, 115
i5 = CVI(l8)
j5 = CVI(j8)
a5 = CVD(a8)
i5 = CVD(i8)
v5 = CVD(u8)
a5 = CVD(a8)
p5 = CVD(p8)
T75 = CVD(T78)
rhe3 = CVD(rhe8)
RETURN

FindPoint4:
GET #1, 116
a6 = CVD(a8)
i6 = CVD(i8)
v6 = CVD(u8)
a6t = CVD(a8)
p6 = CVD(p8)
T76 = CVD(T78)
rhe6 = CVD(rhe8)
RETURN

FindPoint5:
GET #1, 115
i5 = CVI(l8)
j5 = CVI(j8)
a5 = CVD(a8)
i5 = CVD(i8)
v5 = CVD(u8)
a5 = CVD(a8)
p5 = CVD(p8)
T75 = CVD(T78)
rhe3 = CVD(rhe8)
RETURN

FindPoint6:
GET #1, 116
a6 = CVD(a8)
i6 = CVD(i8)
v6 = CVD(u8)
a6t = CVD(a8)
p6 = CVD(p8)
T76 = CVD(T78)
rhe6 = CVD(rhe8)
RETURN

Renumber:
IF i1 = 112 OR i2 = 111 THEN GOTO Renumber1
Renumber1:
IF j1 = 112 THEN GET#1, 111 : j = max + 1 : LSET j0 = MKIS(j) : PUT #1, 111 : j = 112 : iPoint(111) = max + 1 ELSE GET #1, 112 : j = max + 1 : LSET j0 = MKIS(j) : PUT #1, 112 : j = 111 : iPoint(112) = max + 1
Grid4 = "Interior" : i = 0
GOSUB SavePoint
PointType(max) = 4
RETURN
Renumber2:
IF i1 = 112 THEN GET#1, 111 : i = max + 1 : LSET i0 = MKIS(i) : PUT #1, 111 : i = 112 : iPoint(111) = max + 1 ELSE GET #1, 112 : i = max + 1 : LSET i0 = MKIS(i) : PUT #1, 112 : i = 111 : iPoint(112) = max + 1
Grid4 = "Interior" : j = 0
GOSUB SavePoint
PointType(max) = 4
RETURN

CALCULATIONS

NewCalc:
Calculate shock tube and acceleration tube properties
slower = 11
IF langleleyflag = 0 THEN upper1 = 9*(SQR(gamma1)*(gamma1 + 1)*(gamma4 + 1)*gamma4*84*7471/(gamma4 + 1))**2 ELSE upper1 = 9*(SQR(gamma1)*(gamma1 + 1)**2*gamma4**84*7471/(gamma1**3))**2
iflag = 0
IF langleleyflag = 0 THEN yy1 = slower*(SQR((gamma4 + 1)/2)) - ((gamma4 + 1)*SQR((gamma1**3)/(gamma4*84*7471)))*(slower) - 1/(2*(SQR(gamma1))**2*(gamma1 + 1)**2*(slower - 1))**2 ELSE yy1 = 1/(2*(SQR(gamma1))**2*(gamma1 + 1)**2*(slower - 1))
IF langleleyflag = 1 THEN yy1 = slower*(1 - ((gamma4 + 1)*SQR((gamma1**3)/(gamma4*84*7471)))*(slower) - 1/(2*(SQR((2*(gamma1))**2*(gamma1 + 1))))**2 ELSE yy1 = 1/(2*(SQR((2*(gamma1))**2*(gamma1 + 1))))**2
IF langleleyflag = 1 THEN yy2 = upper1*(SQR((gamma4 + 1)/2)) - ((gamma4 + 1)*SQR((gamma1**3)/(gamma4*84*7471)))*(upper1) - 1/(2*(SQR((2*(gamma1))**2*(gamma1 + 1))))**2 ELSE yy2 = 1/(2*(SQR((2*(gamma1))**2*(gamma1 + 1))))**2
IF yy1*yy2 > 0 THEN BEEP : STOP
CALL serin(slower, upper1, tol, iflag, s) : p2p1 = s
p2p4 = p2p1/P4P1
T274 = (p2p4**((gamma4 + 1)/gamma4))
T271 = (18 + (gamma1 + 10)*p2p1/(gamma1 + 10))/(18 + (gamma1 + 10)*(p2p1)*(gamma1 + 10))
M2 = (18 + (gamma1 + 10)*p2p1/(gamma1 + 10))/SQR(p2p1*(gamma1 + 10)/(2*(gamma1 + 10)*(p2p1)))
IF langleleyflag = 0 THEN M3 = (27/(gamma1 + 10))**((18 + p2p1)/(gamma4 + 18))/((18 + (gamma1 + 10)*(p2p1))/28) + 18
M2 = SQR(T271*(gamma1**3)/(T471*(gamma4**3)))
M3 = M2**2
M4 = SQR(T274)
M5 = M4**2
M6 = M2/M4
M7 = M5/M6
rhob1 = p2p1/T271
rhob4 = p2p4/T274
u2 = SQR((1/(gamma1 + 10)/(2*(gamma1)) + ((gamma1 + 10)/(2*(gamma1))**2*gamma1**3)/(7471*gamma4**3)))
slower2 = 11
upper2 = 9*(SQR(2*(gamma1)*(gamma1 + 10)*T271)**((1 + (gamma1 + 10)*P2P1/20)/(gamma1 + 10))**2
iflag = 1
yy1 = slower2*(16 + (gamma1 + 10)*M2**2/2) - ((gamma1 + 10)*SQR(18/T271)*(slower2 - 18))/((SQR((2*(gamma1))**2*(gamma1 + 10)*(p2p1)))**2*(gamma1 + 10))
yy2 = upper2*(16 + (gamma1 + 10)*M2**2/2) - ((gamma1 + 10)*SQR(18/T271)*(upper2 - 18))/((SQR((2*(gamma1))**2*(gamma1 + 10)*(p2p1)))**2*(gamma1 + 10))
IF yy1*yy2 > 0 THEN BEEP : STOP
CALL serin(slower2, upper2, tol, iflag, s) : p2p10 = s
p2p2 = p2p10/(p10*p2p1)
T272 = (p2p2**((gamma1 + 10)/gamma1))
T270 = (18 + (gamma1 + 10)*p2p10/(gamma1 + 10))/(18 + (gamma1 + 10)/(p2p10*(gamma1 + 10)))
M20 = (18 + (gamma1 + 10)*p2p10/(gamma1 + 10))/SQR(p2p10*(gamma1 + 10)/(2*(gamma1 + 10)*(p2p10)))
M30 = (28/(gamma1 + 10))**((18 + p2p10)/(gamma1 + 10)/(2*(gamma1 + 10)*M20/28) + 18)
M40 = SQR(T270*(gamma1**3)/(T471*(gamma4**3)))
M50 = M40**2

```

ORIGINAL PROGRAMS OF PLUG QUALITY

```

aa3 = P08/T572*T271*(gamma1*81/(T471)*gamma4*84)
uu1 = RS4*uu3
rho2*rho10 = p20p10/T20710
rho12*rho2 = p3p2/T372
uu20 = 80*((gamma1 - 1)/(2*gamma1)) * ((gamma1 + 1)/(2*gamma1)) * p20p10*(gamma1*81)/(T471)*(gamma4*84)
RETURN

Interior:
IF igammaflag = 1 THEN gamma = gamma1 + 8 + 14 ELSE gamma = gamma1 + 8 + 11
L2 = .55*(el1 + el2) + (el1 + el2)/gamma - 19
el3 = (gamma - 19)*(uu1 - uu2)/40 + (el1 + el2)/20
RETURN

Expansion:
u2 = 24/((gamma1 + 1)*TAR(expander)) + (gamma1 + 1)*uu2/(gamma1 + 1) + 2*uu2/((gamma1 + 1)*
el2 = (gamma1 - 14)*uu2 - uu2/27 + ee2
p2 = p1*(el1*el1)*(24*gamma1)/(gamma1 - 14)
rho2 = rho1*(el1*el1)*(24*(gamma1 - 14))
igammaflag = 0
RETURN

Contact:
Calculate contact surface point position
el1 = (el1 - L2 + ee2*(el1 - el2)*(el2 - el3)/(28*(el2 - el3)*(el3 - el4)) + ee1*el3 + ee4)/(28*(el2 - el3)*(el3 - el4))
el2 = (el2 - L2 + ee2*(el2 - el3)*(el3 - el4)/(28*(el2 - el3)*(el3 - el4)) + ee1*el3 + ee4)/(28*(el2 - el3)*(el3 - el4))
el3 = (el3 - L2 + ee2*(el3 - el4)/(28*(el3 - el4)) + ee1*el4)/(28*(el3 - el4))
el4 = (el4 - L2 + ee2*(el4 - el3)/(28*(el4 - el3)) + ee1*el3)/(28*(el4 - el3))
Calculate driver gas point position
el1 = (el1 - el2 + ee2*(el1 - el2)*(el2 - el3)/(28*(el2 - el3)*(el3 - el4)) + ee1*el3 + ee4)/(28*(el1 - el2 + el3)*(el2 - el3 + el4))
el2 = (el2 - el3 + ee2*(el2 - el3)*(el3 - el4)/(28*(el2 - el3)*(el3 - el4)) + ee1*el3 + ee4)/(28*(el2 - el3 + el4)*(el3 - el4))
el3 = (el3 - el4 + ee2*(el3 - el4)/(28*(el3 - el4)) + ee1*el4)/(28*(el3 - el4))
el4 = (el4 - el3 + ee2*(el4 - el3)/(28*(el4 - el3)) + ee1*el3)/(28*(el4 - el3))
Calculate driver gas point properties
e = SQRT((el1 - el2)^2 + (el2 - el3)^2)
b = SQRT((el3 - el4)^2 + (el4 - el1)^2)
m = SQRT((el1 - el4)^2 + (el3 - el2)^2)
v1 = (b^uu1 + e*uu3)/el1 + el1 + el2 + el3 + el4)/el1
p1 = (b*ee2 + e*ee3)/el1
rho1 = (b*rho2 + e*rho3)/el1
p2 = p1*(el1*el1)*(24*gamma1)/(gamma1 - 14)
rho10 = p2/el1*el1
Calculate contact surface point properties
uu2 = ((rho1*el1 + rho3*el3)*el1/24 + (rho2*el2 + rho4*el4)*el2/24 + p1 - p2)/((rho1*el1 + rho3*el3)/24 + (rho2*el2 + rho4*el4)/24)
p3 = (2*p1/(rho1*el1 + rho3*el3) + 2*p2/(rho2*el2 + rho4*el4) + el1 - el2)/24/(rho1*el1 + rho3*el3) + 24/(rho2*el2 + rho4*el4))
el4 = el4*(p3/p4)*(gamma1 - 14)/(24*gamma1)
el3 = el3*(p3/p4)*(gamma1 - 14)/(24*gamma1)
el2 = el2*(p3/p4)*(gamma1 - 14)/(24*gamma1)
el1 = el1*(p3/p4)*(gamma1 - 14)/(24*gamma1)
RETURN

Calculations:
IF igammaflag = 1 THEN temp = T1 : dens = 11 ELSE temp = (gamma4*84)/(gamma1*81) : dens = 34/81
IF igammaflag = 1 THEN p3 = p1*(el1*el1)*(24*gamma1)/(gamma1 - 14) ELSE p3 = p1*(el2*el1)*(24*gamma1)/(gamma1 - 14)
T23 = (p3/T23)*dens
rho3 = (p3/T23)*dens
Store results of calculations and store point type
GOSUB SavePoint
Draw output mesh
GOSUB DrawPoint
Draw characteristic lines
GOSUB DrawMech
RETURN

Average:
aaa = SQRT((t2 - t1)^2 + (el2 - el3)^2)
bbb = SQRT((t2 - t1)^2 + (el3 - el4)^2)
uu1 = (aaa*el1 + bbb*el2)/dens + bbb
el3 = (aaa*el1 + bbb*el2)/dens + bbb
el4 = (aaa*el1 + bbb*el2)/dens + bbb
p1 = (aaa*p1 + bbb*p2)/dens + bbb : rho1 = -.001*uu1/dens
el2 = (aaa*t21 + bbb*t22)/(dens + bbb)
rho10 = (aaa*rho1 + bbb*rho2)/(dens + bbb)
RETURN

PitotCalc:
I = 111 : GOSUB FindPoint1
J = 112 : GOSUB FindPoint2
K = 110
L2 = (el2 - el1)*(el1 - el2) + el1
el3 = (el3 - el1)*(el1 - el3) + el1
IF ipitotpoint = 2 OR ipitotpoint = 4 THEN GOSUB PitotCalc2
aaa = SQRT((t2 - t1)^2 + (el2 - el3)^2)
bbb = SQRT((t3 - t1)^2 + (el3 - el1)^2)
uu1 = (aaa*el1 + bbb*el2)/dens + bbb
el3 = (aaa*el1 + bbb*el2)/dens + bbb
el4 = (aaa*el1 + bbb*el2)/dens + bbb
p1 = (aaa*p1 + bbb*p2)/dens + bbb : rho1 = -.001*uu1/dens
IF ipitotpoint = 1 THEN gamma = gamma1
IF ipitotpoint = 3 THEN gamma = gamma4
piter = .04*p1*(gamma + 1)*(T044*2/11)*(gamma/(gamma + 1)) + (gamma - 1.17)*(gamma + 1.17)*(gamma - 1.17)*(gamma + 1.17)
Grid8 = "Pitot" : T23 = piter
PitotCalc2:
I = aaa + 2 : J = aaa + 2
IF ipitotpoint = 2 THEN Grid8 = "ContactTime"
IF ipitotpoint = 4 THEN Grid8 = "Blowtime"
GOSUB SavePoint
IPoint(max) = max + 1 : JPoint(max) = max + 1
IF ipitotpoint < 2 AND ipitotpoint > 4 THEN PointExcess(max) = 1 : PointLoc(max) = I3 : PointType(max) = 7
IF ipitotpoint = 2 THEN PointType(max) = 9
IF ipitotpoint = 4 THEN PointType(max) = 5
WINDOW 4 : BUTTON 3, 1
RETURN

RhoCalc:
uu2 = uu2*SQRT(gamma4*84*T471/(gamma1*81))
uu20 = uu2*SQRT(gamma4*84*T471/(gamma1*81))
GOSUB GetBeta
GOSUB GetBeta1
GOSUB GetBeta2
lnf = (4L2/(4*beta2))^((59/49)*(msf*20610000*354554/(4P1*1011))^((19/44)*(rho2*rho1)/(rho2*rho1 - 14)*p2p1))
lnf2 = (4L2/(4*beta2))^2*uu2*20610000*354554*rho2*rho10/(P4P1*1011*p20p10*(rho2*rho10 - 14)*p1p10)
RETURN

GetBeta:
IF msf < 90 THEN beta = -.003156*(msf - 60) + .02838 : GOTO BetaEnd
IF msf < 104 THEN beta = -.003166*(msf - 80) + .02216 : GOTO BetaEnd
IF msf < 128 THEN beta = -.003357*(msf - 100) + .01984 : GOTO BetaEnd
IF msf < 140 THEN beta = -.001446*(msf - 120) + .01578 : GOTO BetaEnd
IF msf < 160 THEN beta = -.000453*(msf - 140) + .01236 : GOTO BetaEnd
IF msf < 180 THEN beta = -.00039999999999990-04*(msf - 160) + .01169 : GOTO BetaEnd
beta = -.00056*(msf - 180) + .01044
BetaEnd:
beta = beta*((rho2*rho1)^2 + (.234*rho2*rho1 - .88)/(rho2*rho1 - 14))^(49/50)
RETURN


```

ORIGINAL PAGE IS
OF POOR QUALITY

```

GetBeta2:
IF us2 < 60 THEN Beta2 = -.0938*(us2 - 40) + 1.166 : GOTO BetaEnd
IF us2 < 60 THEN Beta2 = -.050000000000001D-02*(us2 - 60) + 1.474 : GOTO BetaEnd
IF us2 < 106 THEN Beta2 = -.0538*(us2 - 60) + 1.38 : GOTO BetaEnd
IF us2 < 126 THEN Beta2 = -.0659*(us2 - 60) + 1.199 : GOTO BetaEnd
Beta2 = -.0347*(us2 - 126) + 1.19
BetaEnd:
RETURN

BicubicSlope:
    A1 = u3 + t1 + t2
    A2 = t1 + A1 + A2
    t3 = (t1 - u3)/W3 + t1 + t2 + t3
    u3 = u3
    A3 = u3
    p1 = zmax
    T112 = T112*TT21/7471
    rho1 = p1*p2*p3*84/(P471*T112*t1)
    I = max(1, 3 - max)
    GOSUB DrawPoint
    PointLocX(max) = A3 : PointLocY(max) = t3
    PointType(max) = 6 : IfPoint(max) = 1 : IfPoint(max) = 0
    GOSUB DrawPoint
    GOSUB DrawLine
    GOSUB DrawLine
    RETURN

GRAPHICS ROUTINES

Scales:
PENSIZE 1, 1 : TEXTFONT 4 : TEXTFACE 9 : TEXTFACE 32
MOVE TO L1L28*4908/(10 + L1L28) + 14 + 18*scrollX, 10 : LINETO L1L28*4908/(10 + L1L28) + 14 + 18*scrollX, 0
u3 = 4908*L1L28/(10 + L1L28) + 14 + 18*scrollX
MOVE TO u3 + 1, 0 : PRINT "0"
WHILE u3 < 4908*(magfactor* + L1L28)/(10 + L1L28) - 40 + 18*scrollX
    u3 = u3 + 30
        IF u3 > 308 THEN GOTO ScaleEnd1
    MOVE TO u3, 10 : LINETO u3, 5
    MOVE TO u3, 5 : PRINT "."
    u3 = CINT((u3 - 14 - 18*scrollX)*(10 + L1L28)/4908 - L1L28)*1000/magfactor
    PRINT CINT(u3)/1000
    WEND
ScaleEnd1:
u3 = 4908*L1L28/(10 + L1L28) + 14 + 18*scrollX
WHILE u3 > 4908*L1L28/(10 + magfactor*)/(10 + L1L28) + 78 + 18*scrollX
    u3 = u3 - 30
        IF u3 < 0 THEN GOTO ScaleEnd2
    MOVE TO u3, 10 : LINETO u3, 5
    MOVE TO u3, 5 : PRINT "."
    u3 = CINT((u3 - 14 - 18*scrollX)*(10 + L1L28)/4908 - L1L28)*1000/magfactor
    PRINT CINT(u3)/1000
    WEND
ScaleEnd2:
u3 = 314 + 18*scrollX
MOVE TO 10, u3 : LINETO 0, u3 : MOVE TO -2, u3 - 3 : PRINT "0"
WHILE u3 > 33
    u3 = u3 - 30
        IF u3 > 318 THEN GOTO ScaleEnd3
    MOVE TO 10, u3 : LINETO 5, u3
    t1 = CINT((314 + 18*scrollX - u3)*(10 + L1L28)/(4908*magfactor*tstretch))
    T112 = STR(t1*1000)
    a1 = " " + MID(T112, 2, 1)
    b1 = " " + MID(T112, 3, 1)
    MOVE TO 5, u3 - 21 : PRINT a1
    IF LEN(T112) = 4 THEN a1 = " " + MID(T112, 4, 1) : MOVE TO -2, u3 - 25 : PRINT a1
    IF LEN(T112) = 2 THEN MOVE TO -2, u3 - 12 : PRINT "0" : MOVE TO -2, u3 - 3 : PRINT a1 : GOTO ScaleEnd3
    IF LEN(T112) = 3 THEN MOVE TO -2, u3 - 12 : PRINT "0" : MOVE TO -2, u3 - 3 : PRINT a1 : GOTO ScaleEnd3
    MOVE TO -2, u3 - 3 : IF LEN(T112) = 4 THEN PRINT a1 : ELSE PRINT b1
    WEND
ScaleEnd3:
    WEND
MOVE 4908*L1L28/(10 + magfactor*)/(10 + L1L28) + 14 + 18*scrollX, 10 : LINETO 4908*(magfactor* + L1L28)/(10 + L1L28) + 14 + 18*scrollX, 10
MOVE TO 10, 10 : LINETO 10, 314 + 18*scrollX
TEXTFACE 1 : TEXTFONT 1 : TEXTFACE 12
RETURN

Tubes:
PENSIZE 2, 2
tstretch = (314 - L1L28*4908*(u3/u2 - u3)) * (10 - u3/u2)/u2 + 18 / (u2*(10 + L1L28*u2)) / 1004
MOVE TO (10 - magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
LINETO (10 - magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
MOVE TO (10 - magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
LINETO (10 - magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
MOVE TO L1L28*4908/(10 + L1L28) + 14 + 18*scrollX, 3144 + 18*scrollX
MOVE TO (11128 + magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
LINETO (11128 + magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
MOVE TO (11128 + magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
LINETO (11128 + magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
LINETO (11128 + magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
u3 = L1L28*4908/(10 + L1L28) + 14 + 18*scrollX
t1 = 314 + 18*scrollX - L1L28*4908*magfactor*tstretch/(10 + L1L28*u2)
u3 = 18 / ((t1*2 - L1L28*u2)*tstretch)
u3d = (L1L28 + magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX
tend = 314 + 18*scrollX - L1L28*4908*magfactor*tstretch/(10 + L1L28)
GOSUB Dashline
MOVE TO (10 - magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
CALL PEPAT(VARPTR(Idash(0)))
IF tstretch > 0 AND tstretch < 04 THEN LINETO 4908*(magfactor* * L1L28)/(10 + L1L28) + 144 + 18*scrollX, 3144 + 18*scrollX
    t1 = 18 / (tstretch*magfactor* * L1L28)
    CALL PEPAT
PENSIZE 1, 1
MOVE TO L1L28*4908/(10 + L1L28) + 14 + 18*scrollX, 314 + 18*scrollX - L1L28*4908*magfactor*tstretch/(10 + L1L28*u2)
LINETO u3d, tend
t1 = (314 + 18*scrollX - 10)*(10 + L1L28)/(4908*magfactor*tstretch)
u3d = 18
tend = 18
LINETO 4908*((t1*u3d - u3) + u3d*magfactor* * L1L28)/(10 + L1L28) + 14 + 18*scrollX, 10
MOVE TO (10 - magfactor* * L1L28*4908/(10 + L1L28)) + 144 + 18*scrollX, 3144 + 18*scrollX
LINETO 4908*((t1*u3d - u3) - L1L28*magfactor* * L1L28)/(10 + L1L28) + 14 + 18*scrollX, 10
RETURN

DrawPoint:
PENSIZE 1, 1
CIRCLE (4908*(u3*magfactor* * L1L28)/(10 + L1L28) + 14 + 18*scrollX, 314 + 18*scrollX - 18*magfactor*tstretch*4908/(10 + L1L28)), 1

```

CHAPTER 10 OF POKA QUALITY

```

        RETURN

DrawContact:
PENSIZE 2, 2
ai = 490*(magfactor* + LIL28)/(14 + LIL28) + 14 + 18scrollX
ti = 314 + 18scrollY - t3*magfactor*tstretch*490/(14 + LIL28)
mond = 490*(m3*magfactor* + LIL28)/(14 + LIL28) + 14 + 18scrollX
tend = 314 + 18scrollY - t3*magfactor*tstretch*490/(14 + LIL28)
udash = -(mond - ai)/(tend - ti)
GOSUB DashLine
PENSIZE 1, 1
RETURN

DrawMech:
PENSIZE 1, 1
MOVETO 490*(m3*magfactor* + LIL28)/(14 + LIL28) + 14 + 18scrollX, 314 + 18scrollY - t3*490*magfactor*tstretch/(14 + LIL28)
IF Grid <> "Interior" THEN LINETO 490*(ai*magfactor* + LIL28)/(14 + LIL28) + 14 + 18scrollX, 314 + 18scrollY - t3*490*magfactor*tstretch/(14 + LIL28)
IF Grid = "Interior" THEN GOTO DrawMechEnd
MOVETO 490*(m3*magfactor* + LIL28)/(14 + LIL28) + 14 + 18scrollX, 314 + 18scrollY - t3*490*magfactor*tstretch/(14 + LIL28)
IF Grid <> "Expansion" THEN LINETO 490*(m3*magfactor* + LIL28)/(14 + LIL28) + 14 + 18scrollX, 314 + 18scrollY - t3*490*magfactor*tstretch/(14 + LIL28)
IF Grid = "Expansion" AND j <> -7 AND j <> -7 THEN LINETO LIL28*490/(14 + LIL28) + 14 + 18scrollX, 314 + 18scrollY - LIL28*490*magfactor*tstretch/(14 + LIL28)*ns2
DrawMechEnd:
RETURN

Grid:
CALL PENTAP(VARPTR(lgrey(0))) : CALL PENSIZE(1, 1) : CALL PERIOD(9)
aa = 490*LIL28/(14 + LIL28) + 14 + 18scrollX
WHILE aa < 494
    aa = aa + 30
    MOVETO aa, 10 : LINETO aa, 318
WEND
aa = 490*LIL28/(14 + LIL28) + 14 + 18scrollX
WHILE aa > 44
    aa = aa - 30
    MOVETO aa, 10 : LINETO aa, 318
WEND
ts = 314 + 18scrollY
WHILE ts > 85
    ts = ts - 30
    MOVETO 10, ts : LINETO 300, ts
WEND
CALL PERNORMAL
RETURN

DashLine:
IF ai < 14 AND ti <= 314 THEN ti = -(14 - ai)/udash + ti : ai = 14 : GOTO DashStart
IF ti > 314 AND ai >= 14 THEN ai = -udash*(314 - ti) + ai : ti = ti : IF ti2 <= 314 THEN ai = 14 - ti + ti2 ELSE ai = -udash*(314 - ti) + ai : ti = ti - 34
ELSE RDN
    DashStart:
        WHILE ai < mond AND ti > tend AND ai < 304 AND ti > 10
            MOVETO ai, ti
            ai = 10*udash/PQR(udash*2 + 16) + ai
            ti = -(ai - ai)/udash + ti
            IF ai >= mond OR ti <= tend THEN ai = mond : ti = tend
            LINETO ai, ti
            ai = 10*udash/PQR(udash*2 + 16) + ai
            ti = -(ai - ai)/udash + ti
        WEND
    RETURN

Redraw:
PICTURE OFF : CALL SIDEOPEN : PICTURE ON : CALL SIDEOPEN
Redraw2:
IF igridding = 1 AND inumberflag = 0 THEN GOSUB Grid
IF inumberflag = 1 AND igridding = 0 THEN GOSUB ShowNumber
IF inumberflag = 1 AND igridding = 1 THEN GOSUB Grid : GOSUB ShowNumber
GOSUB Tube
ii = -1
WHILE TRUE = 1
    ii = ii + 1
    GET PI, II, 4
    IF PI < 0 OR ii > max - 6 THEN GOTO Redraw5
    i = CVI(18) : j = CVI(54) : 0 = 0
    ai = CVD(i8)
    ti = CVD(t8)
    Grid8 = #88
    blank = INTR(Grid8, " ") : Grid8 = LEFTS(Grid8, blank - 1)
    GOSUB GetLocations
    IF Grid <> "Interior" AND Grid <> "Expansion" AND Grid <> "Contact" AND Grid <> "Contact2" AND Grid <> "Interior" AND Grid <> "Interior"
        AND Grid <> "Blank" AND Grid <> "FirstPoint" THEN GOTO Redraw
    IF Grid = "Interior" AND i < 0 THEN GOSUB FindPoint1 : GOSUB FindPoint2 : GOTO Redraw
    IF Grid = "Interior": THEN GOSUB FindPoint1 : GOTO Redraw
    IF Grid = "Interior": THEN GOSUB FindPoint2 : GOTO Redraw
    IF Grid = "Expansion": THEN GOSUB FindPoint1 : GOTO Redraw
    IF Grid = "Expansion": THEN GOSUB FindPoint2 : GOSUB FindPoint3 : i = ii : GOSUB FindPoint4 : GOTO Redraw
    IF Grid = "Blank": AND i <> 0 THEN GOSUB FindPoint1 : GOTO Redraw
    IF Grid = "Blank": AND i > 0 THEN GOSUB FindPoint2 : GOTO Redraw
    IF Grid <> "Blank" AND inumberflag = 1 THEN GOSUB DrawPoint : GOTO Redraw4
    IF Grid = "FirstPoint" AND inumberflag = 1 THEN GOSUB DrawPoint : GOTO Redraw4

    Redraw4:
        IF icerleflag = 1 THEN GOSUB DrawPoint
        IF Grid = "Contact": THEN GOSUB DrawContact
        IF Grid = "Blank": AND i < 0 THEN A2 = ai : i2 = ti : GOSUB DrawBlank
        IF i < 0 AND j = 0 THEN GOTO Redraw
        IF Grid <> "Blank": THEN GOSUB DrawPoint : GOSUB DrawPoint
        Redraw:
    WEND
Redraw5:
LINE (0, 0) - (500, 10) : 30, 0F
LINE (0, 10) - (10, 318) : 30, 0F
GOSUB Scales
RETURN

GetLocations:
IF DCASE8(Grid8) = "INTERIOR": THEN PointType(ii + 6) = 0
IF DCASE8(Grid8) = "EXPANSION": THEN PointType(ii + 6) = 1
IF DCASE8(Grid8) = "CONTACT": THEN PointType(ii + 6) = 2
IF DCASE8(Grid8) = "CONTACT2": THEN PointType(ii + 6) = 11
IF DCASE8(Grid8) = "INTERIOR": THEN PointType(ii + 6) = 3
IF DCASE8(Grid8) = "INTERIOR": THEN PointType(ii + 6) = 4
IF DCASE8(Grid8) = "BLANK": THEN PointType(ii + 6) = 5
IF DCASE8(Grid8) = "BLANK": THEN PointType(ii + 6) = 6
IF DCASE8(Grid8) = "FIRSTPOINT": THEN PointType(ii + 6) = 10
IF DCASE8(Grid8) = "FIRST": THEN PointType(ii + 6) = 7
IF DCASE8(Grid8) = "CONTACTDNE": THEN PointType(ii + 6) = 8
IF DCASE8(Grid8) = "BLDGTIME": THEN PointType(ii + 6) = 9
PointLoc(ii + 6) = ai
PointLoc(ii + 6) = ti
PointLoc(ii + 6) = 1 : jPoint(ii + 6) = j

```

```

        RETURN

Reflect:
PICTURE OFF : CALL SIDEOPEN : PICTURE ON : CALL SIDEOPEN
Reflect2:
IF lgridflag = 1 AND inumberflag = 0 THEN GOSUB Grid
IF inumberflag = 1 AND lgridflag = 0 THEN GOSUB ShowNumber
IF inumberflag = 1 AND lgridflag = 1 THEN GOSUB Grid : GOSUB ShowNumber
GOSUB Tube
FOR i = 6 TO nnn
    a1 = PointLoc(i)
    t1 = PointLoc(i)
    t2 = PointLoc(i)
    t3 = PointLoc(i) : j = j+1
    IF PointType(i) = 0 THEN Grid = "Interior" : IF i1 < 0 THEN a1 = PointLoc((Point(i)) + t1) : t1 = PointLoc((Point(i)) - t2) =
        PointLoc((Point(i)) + t2) : GOTO Reflect ELSE GOTO Reflect2 ELSE ADM
    IF PointType(i) = 1 THEN Grid = "Expansion" : a1 = PointLoc((Point(i)) + t1) : t1 = PointLoc((Point(i)) - t2) =
        PointLoc((Point(i)) + t2) : t2 = PointLoc((Point(i)) + t3) : t3 = PointLoc((Point(i)) - t1) : GOTO Reflect
    IF PointType(i) = 2 THEN Grid = "Contact" : a1 = PointLoc((Point(i)) + t1) : t2 = PointLoc((Point(i)) + t3) : t3 = PointLoc((Point(i)) - t1) : t1 = PointLoc((Point(i)) + t2) : GOTO Reflect
    IF PointType(i) = 3 THEN Grid = "Interior" : a1 = PointLoc((Point(i)) + t1) : t1 = PointLoc((Point(i)) - t2) : GOTO Reflect
    IF PointType(i) = 4 THEN Grid = "Interior" : a1 = PointLoc((Point(i)) + t2) : t2 = PointLoc((Point(i)) - t1) : GOTO Reflect
    IF PointType(i) = 5 THEN Grid = "Bleb" : IF i1 < 0 THEN a1 = PointLoc((Point(i)) + t1) : t1 = PointLoc((Point(i)) - t2) : GOTO Reflect
    IF PointType(i) = 6 THEN Grid = "Bleb" : IF i1 < 0 THEN a1 = PointLoc((Point(i)) + t1) : t1 = PointLoc((Point(i)) - t2) : GOTO Reflect
    IF PointType(i) = 7 THEN Grid = "Bleb" : IF i1 < 0 THEN a1 = PointLoc((Point(i)) + t1) : t1 = PointLoc((Point(i)) - t2) : GOTO Reflect
    IF PointType(i) = 8 THEN Grid = "Bleb" : IF i1 < 0 THEN a1 = PointLoc((Point(i)) + t1) : t1 = PointLoc((Point(i)) - t2) : GOTO Reflect
    IF PointType(i) = 9 THEN Grid = "Bleb" : IF i1 < 0 THEN a1 = PointLoc((Point(i)) + t1) : t1 = PointLoc((Point(i)) - t2) : GOTO Reflect
    IF PointType(i) = 10 AND lgridflag = 1 THEN GOSUB DrawPoint
    GOTO Reflect
Reflect3:
IF lgridflag = 1 THEN GOSUB DrawPoint
IF Grids = "Contact" THEN GOSUB DrawContact
IF Grids = "Bleb" AND i1 < 0 THEN a1 = a1 : t2 = t3 : t3 = t1 : GOSUB DrawBleb
IF i1 = 0 AND j = 0 THEN GOSUB Reflect4
IF Grids <> "Bleb" THEN GOSUB DrawMech
GOSUB Scales
RETURN

Reflect4:
NEXT i
LINE (0, 0) - (500, 10), 30, w1
LINE (0, 10) - (10, 318) : 30, w2
GOSUB Scales
RETURN

FlashLine:
PENSIZE 1, 1
IF timer = 1 THEN timer = 0 : LINE (x1, y1) - (x2, y2), 33 : RETURN
IF timer = 0 THEN timer = 1 : LINE (x1, y1) - (x2, y2), 30
CIRCLE (x1, y1), 3
CIRCLE (x2, y2), 3
RETURN

Reficture:
PICTURE OFF : Images = PICTURES : PICTURE ON : PICTURE, Images
RETURN

DrawBleb:
CALL PFPAT(VARPAT(lidash(0))) : PENSIZE 2, 2
MOVE TO 490*(x1*magfactor1 + L1L2)/10 + L1L2) + 14 + 18*x1LX, 314 + 18*x1LT - 490*(x1*magfactor2*tstretch/(10 + L1L2))
MOVE TO 490*(x2*magfactor1 + L1L2)/10 + L1L2) + 14 + 18*x2LX, 314 + 18*x2LT - 490*(x2*magfactor2*tstretch/(10 + L1L2))
PENNORMAL : PENSIZE 1, 1
RETURN

MOUSE INPUT ROUTINES

SelectContact:
BREAK ON : lbreak = 0
SelectContact1:
t = MOUSE(0)
WHILE MOUSE(0) <> 1
    IF lbreak = 1 THEN GOTO SelectContactEnd
    WEND
    xaa = MOUSE(5) : ttt = MOUSE(6)
    lcheckflag = 0
    GOSUB CheckPoint
    IF lcheckflag < 1 THEN BEEP : BEEP : GOTO SelectContact1
    l11 = 11
    BEEP
SelectContact2:
t = MOUSE(0)
WHILE MOUSE(0) <> 1
    IF lbreak = 1 THEN GOTO SelectContactEnd
    WEND
    xaa = MOUSE(5) : ttt = MOUSE(6)
    lcheckflag = 0
    GOSUB CheckPoint
    IF lcheckflag < 1 THEN BEEP : BEEP : GOTO SelectContact2
    l12 = 11
SelectContactEnd:
BREAK OFF
RETURN

SelectExpansion:
BREAK ON : lbreak = 0
lmpflag = 0
SelectExpansion1:
t = MOUSE(0)
WHILE MOUSE(0) <> 1
    IF lbreak = 1 THEN GOTO StopEnd
    IF lmpflag = 0 THEN Test1 = INPUT(2)
    IF lmpflag = 0 THEN expand1 = VAL(Test1)
    IF lmpflag = 0 THEN IF Test1 = "1" THEN lmpflag = 1 ELSE lmpflag = 0
    WEND
    xaa = MOUSE(5) : ttt = MOUSE(6)
    lcheckflag = 0 : lmpflag = 1
    GOSUB CheckPoint : lmpflag = 0
    IF lcheckflag < 1 OR lmpflag = 0 THEN BEEP : BEEP : GOTO SelectExpansion1
StopEnd:
BREAK OFF
RETURN

SelectInterior:
BREAK ON : lbreak = 0
SelectInterior1:
t = MOUSE(0)
WHILE MOUSE(0) <> 1
    IF lbreak = 1 THEN GOTO SInteriorEnd
    WEND
    xaa = MOUSE(5) : ttt = MOUSE(6)
    lcheckflag = 0 : ldriverflag = 1
    GOSUB CheckPoint : ldriverflag = 0
    IF lcheckflag < 1 THEN BEEP : BEEP : GOTO SelectInterior1
    a1 = x1 : t1 = t1 : l11 = 11
    BEEP
SelectInterior2:
t = MOUSE(0)

```

ORIGINAL PAGE IS
OF POOR QUALITY

ORIGINAL PAGE IS OF POOR QUALITY

```

WHILE MOUSE(0) <> 1
    IF lbreak = 1 THEN GOTO SelectInfoEnd
    HEND
    xax = MOUSE(5) : ttt = MOUSE(6)
    iscrollflag = 0
    GOSUB CheckPoint
    IF icheckflag <> 1 THEN BEEP : BEEP : GOTO SelectInfoEnd
    xz = xx + tz : st = xl + xl2 - 11
    SelectInfoEnd:
    BREAK OFF
    RETURN

CheckPoint:
    IF ineflag = 0 AND ieflag = 0 THEN GOTO CheckPoint1
    xeq = 490*tmagfactor*(1128)/(18 + L1L28) + 144 + iscrollX
    stq = 314 + iscrollY - 490*tmgfactor*tstretch/(18 + L1L28)
    xai = 490*((((314 + iscrollY - 108)*(18 + L1L28))/(490*tmgfactor*tstretch) + Lq1*(xz) - xz) + tmgfactor*(1128)/(18 + L1L28)) + 144 + iscrollX
    iscrollX
    st = 10
    st = (tmg - stq)/(seq - xai)
    xx = (ttt - stq + st)*(seq + xax/wf)/(st + 18/wf)
    st = 0/(seq - xai) + stq
    IF ABS((xx - xz)*2 + (ttt - st)*2) < 20 THEN iscrollflag = 1 ELSE GOTO CheckPoint1
    Grids = "Interior"
    l = 0 : j = 0
    xl = (xx + 14 - iscrollX)*(11 + L1L28)/490 - L1L28/tmgfactor
    xl = (314 + iscrollY - st)*(11 + L1L28)/(490*tmgfactor*tstretch)
    xl = xl3
    xl3 = xl
    xl = xl3*p3d
    xl3 = xl3*p3d
    xl = xl3/P3
    xl3 = xl3/P3
    GOSUB SavePoint
    IF ineflag = 1 THEN GOSUB CheckPoint
    ineflag = 0
    PointLoc(max) = xl : PointLoc(max) = t3 : Point(max) = 0 : Point(max) = 0 : PointType(max) = 0
    xl = max
    GOTO CheckEnd
CheckPoint1:
    FOR xl = max TO 6 STEP -1
        IF ldriverflag = 1 AND PointType(xl) = 11 THEN GOTO CheckPoint1
        IF ldriverflag = 1 AND PointType(xl) = 10 THEN ldfudgeflag = 0 : GOTO CheckPoint1
        IF PointType(xl) = 0 OR PointType(xl) = 1 OR PointType(xl) = 2 OR PointType(xl) = 3 OR PointType(xl) = 4 OR PointType(xl) = 5 OR PointType(xl) = 10 OR PointType(xl) = 11 THEN GOTO CheckPoint1
        GOTO CheckPoint2
CheckPoint2:
    xl = PointLoc(xl) : t = PointLoc(xl)
    xl = 490*tmgfactor*(1128)/(18 + L1L28) + 14 + iscrollX
    st = 314 + iscrollY - 490*tmgfactor*tstretch/(18 + L1L28)
    IF ABS(xl - xax) <= 20 AND ABS(st - ttt) <= 20 THEN iscrollflag = 1 : GOTO CheckEnd
    CheckPoint3:
    NEXT xl
    CheckEnd:
    RETURN

SelectSplit:
    BREAK ON : lbreak = 0
    SelectSplit:
    i = MOUSE(0)
    WHILE MOUSE(0) <> 1
        GOSUB FlashLine
        IF lbreak = 1 THEN GOTO $splitEnd
    HEND
    xax = MOUSE(5) : ttt = MOUSE(6)
    st = (ttt - stl)/(xax - xl)
    IF ABS(st) <= (xax/wf/2 * (ttt - st))/wf + xai)/(18 + L1L28)*2 ELSE xl = (xax/wf/2 * (ttt - st))/wf + xai)/(18 + L1L28)
    IF ABS(st) > 18 THEN ttd = (xax - xax)/st + ttt ELSE ttd = (xax - xai)/st + stl
    IF ABS(xax - ttd) * 2 + (xax - xl)*2 > 36 THEN iscrollflag = 0 ELSE iscrollflag = 1
    IF icheckflag <> 1 THEN BEEP : BEEP : GOTO SelectSplit
    xax = (xax - 14 - iscrollY - 490*(L1L28/(18 + L1L28)))*(18 + L1L28)/(490*tmgfactor)
    ttd = (314 + iscrollY - ttd)*(18 + L1L28)/(490*tmgfactor*tstretch)
$splitEnd:
    BREAK OFF
    RETURN

LocateInfo:
    WINDOW 3 : mouseflag = 1
    SETCURSOR VARPTR(lcrosshair(0))
    SelectInfo:
    i = MOUSE(0)
    WHILE MOUSE(0) <> 1
    HEND
    xax = MOUSE(5) : ttt = MOUSE(6)
    iscrollflag = 0
    GOSUB CheckPoint
    IF icheckflag <> 1 THEN BEEP : BEEP : GOTO SelectInfo
    SETCURSOR VARPTR(lwatch(0))
    ldirty = 0
    IF firstinfo <> 1 THEN GOSUB FindInfo
    mouseflag = 0
    RETURN

LocateErase:
    IF ineflag = 1 THEN WINDOW 3
    mouseflag = 1
    SETCURSOR VARPTR(lcrosshair(0))
    BREAK ON : lbreak = 0
    SelectErase:
    i = MOUSE(0)
    WHILE MOUSE(0) <> 1 THEN GOTO SelectErase
    HEND
    xax = MOUSE(5) : ttt = MOUSE(6)
    iscrollflag = 0
    GOSUB CheckPoint
    IF PointType(i) = 2 OR PointType(i) = 3 OR PointType(i) = 4, OR PointType(i) = 7, OR PointType(i) = 8 OR PointType(i) = 11 THEN icheckflag = 0
    IF icheckflag <> 1 THEN BEEP : BEEP : GOTO SelectErase
    EraseEnd:
    BREAK OFF : IF lbreak = 1 THEN RETURN
    SETCURSOR VARPTR(lwatch(0))
    RETURN

LocateScroll:
    IF ineflag = 1 THEN WINDOW 3
    mouseflag = 1
    BREAK ON : lbreak = 0
    SETCURSOR VARPTR(lhard(0))
    SelectScroll:
    i = MOUSE(0)
    WHILE i = 0

```

```

        IF lbreak = 1 THEN GOTO ScrollEnd
        t = MOUSE(0)
        END
        ax = MOUSE(5) : ttt = MOUSE(6)
        IF ax < 0 OR ax > 601 OR ttt < 0 OR ttt > 317 THEN BEEP : SLEEP : GOTO SelectScroll
        ScrollEnd:
        BREAK OFF : IF lbreak = 1 THEN RETURN
        lDirt = 0
        RETURN

SelectB1:
        BREAK ON : lbreak = 0
        SelectB1();
        t = MOUSE(0)
        WHILE MOUSE(0) <> 1
        IF lbreak = 1 THEN GOTO B1End
        END
        ax = MOUSE(5) : ttt = MOUSE(6)
        iCheckFlag = 0 : iDiverging = 1
        GDOS Checkpoint : iDiverging = 0 : iDiverging = 0
        IF iCheckFlag < 1 THEN BEEP : SLEEP : GOTO SelectB1
        al = ax : t1 = st : il1 = ii1
        BEEP
        SelectB1();
        t = MOUSE(0)
        WHILE MOUSE(0) <> 1
        IF lbreak = 1 THEN GOTO B1End
        END
        ax = MOUSE(5) : ttt = MOUSE(6)
        iCheckFlag = 0 : iDiverging = 1
        GDOS Checkpoint : iDiverging = 0
        IF iCheckFlag < 1 THEN BEEP : SLEEP : GOTO SelectB1
        al = ax : t1 = st : il1 = ii1
        BEEP
        SelectB1();
        t = MOUSE(0)
        WHILE MOUSE(0) <> 1
        IF lbreak = 1 THEN GOTO B1End
        END
        ax = MOUSE(5) : ttt = MOUSE(6)
        iCheckFlag = 0 : iDiverging = 1
        GDOS Checkpoint : iDiverging = 0
        IF iCheckFlag < 1 THEN BEEP : SLEEP : GOTO SelectB1
        al = ax : t1 = st : il1 = ii1
        BEEP
        SelectB1();
        t = MOUSE(0)
        WHILE MOUSE(0) <> 1
        IF lbreak = 1 THEN GOTO B1End
        END
        ax = MOUSE(5) : ttt = MOUSE(6)
        iCheckFlag = 0 : iDiverging = 1
        GDOS Checkpoint : iDiverging = 0
        IF iCheckFlag < 1 THEN BEEP : SLEEP : GOTO SelectB1
        al = ax : t1 = st : il1 = ii1
        BEEP
        B1End:
        BREAK OFF
        RETURN

SelectP1:
        BREAK ON : lbreak = 0
        SelectP1();
        t = MOUSE(0)
        WHILE MOUSE(0) <> 1
        IF lbreak = 1 THEN GOTO SP1End
        END
        ax = MOUSE(5) : ttt = MOUSE(6)
        iCheckFlag = 0
        GDOS Checkpoint
        IF iCheckFlag < 1 THEN BEEP : SLEEP : GOTO SelectP1
        al = ax : t1 = st : il1 = ii1
        BEEP
        SelectP1();
        t = MOUSE(0)
        WHILE MOUSE(0) <> 1
        IF lbreak = 1 THEN GOTO SP1End
        END
        ax = MOUSE(5) : ttt = MOUSE(6)
        iCheckFlag = 0
        GDOS Checkpoint
        IF iCheckFlag < 1 THEN BEEP : SLEEP : GOTO SelectP1
        al = ax : t1 = st : il1 = ii1
        BEEP
        SP1End:
        BREAK OFF : WINDOW 4 : INITCURSOR
        RETURN

SUBROUTINES
SC3 zeroIn(ax,bx,tel,iflag,*) STATIC
        SHARED gammaL, gammaR, bl, br, T4T1, P4P1, T2T1, p2p1, plp10, M24, t6, t3, x6, x3, u6, u3, rho6, rho3, xl, xr, bl1, tl, bl2, ur2, ur1
        Compute eps, the relative machine precision
        eps = 1e-10
        eps = eps/20
        tol1 = 1e-10 * eps
        IF (tol1 > 1e-10) GOTO 18
        Initialization
        a = ax
        b = bx
        IF iflag = 0 THEN ax = a : GDOS Check1 : fa = yy : ax = b : GDOS Check1 : D = yy
        IF iflag = 1 THEN ax = a : GDOS Check2 : fa = yy : ax = b : GDOS Check2 : D = yy
        IF iflag = 2 THEN ax = a : GDOS ScaleCalc : fa = yy : ax = b : GDOS ScaleCalc : D = yy
        IF iflag = 3 THEN ax = a : GDOS Scale : fa = yy : ax = b : GDOS Scale : D = yy
        IF iflag = 4 THEN ax = a : GDOS Scale8 : fa = yy : ax = b : GDOS Scale8 : D = yy
        IF iflag = 5 THEN ax = a : GDOS LmMtr : fa = yy : ax = b : GDOS LmMtr : D = yy
        Begin step
20      c = a
        fc = fa
        D = b - a
        e = 0
        IF (ABS(fc) >= ABS(D)) GOTO 40
        a = b
        b = c
        c = a
        fa = fb
        fb = fc
        fc = fa
        Convergence test
40      tol1 = 20*eps*ABS(b) + .5*tel
        m = .5*(c - b)
        IF (ABS(m) < tol1) GOTO 90
        IF (D = 0) GOTO 90
        Is bisection necessary
        IF (ABS(e) < tol1) GOTO 70
        IF (ABS(fe) <= ABS(fb)) GOTO 70
        Is quadratic interpolation possible
        IF (e <= e) GOTO 30
        Linear interpolation
        e = D/fa
        D = 20*eps*m

```

ORIGINAL PAGE IS
OF POOR QUALITY

COMPUTER PROGRAMMING OF FLOOR QUALITY

```

C = 10 - 8
GOTO 60
10  Inverse quadratic Interpolation
    Q = ta/fe
    R = fb/fe
    S = fc/fe
    P = ((2*P)*(Q*(R - S) + (R - S)*(S - P)))
    Q = (Q - 10)*(R - 10)*(S - 10)
    R = (Q - 10)*(R - 10)*(S - 10)
    S = (Q - 10)*(R - 10)*(S - 10)
    Adjust signs
60    IF (p > 90) THEN Q = -Q
    P = ABS(p)
    Is Interpolation acceptable
    IF ((2*P) >= (2*P)*Q + ABS(fe)*Q)) GOTO 70
    IF (p >= ABS(2*P)*Q)) GOTO 70
    S = 0
    D = P/Q
    GOTO 80
80  Bisection
    D = -D
    S = 0
    Complete step
    S = S
    If (D > 0) THEN S = S + D
    If (ABS(D) < fe) THEN S = S + fe*(tel1)*fe/(fe)
    If (tel1 = 0 THEN S = S + fe*(tel1)*tel1 : D = -yy
    If (tel1 = 1 THEN S = S + fe*(tel1)*tel2 : D = -yy
    If (tel1 = 2 THEN S = S + fe*(tel1)*tel3 : D = -yy
    If (tel1 = 3 THEN S = S + fe*(tel1)*tel4 : D = -yy
    If (tel1 = 4 THEN S = S + fe*(tel1)*tel5 : D = -yy
    If (tel1 = 5 THEN S = S + fe*(tel1)*tel6 : D = -yy
    If (tel1 = 6 THEN S = S + fe*(tel1)*tel7 : D = -yy
    If ((D/fe)/fe/ABS(fe)) > 0) GOTO 20
    GOTO 30
30  Done
    t = b
    GOTO bisection
    If (languayflag = 0 THEN yy = xx*(gamma4 + 10/20) - ((gamma4 - 10)*SQRT((gamma4*10)/(gamma4*10*7471)))**((xx - 10)/(SQRT((20*gamma4) + (gamma4 + 10)*(xx - 10))))**(-2*gamma4/(gamma4 - 10)) - 7471
    If (languayflag = 1 THEN yy = xx*(10 - (gamma4 - 10)*SQRT((gamma4*10)/(gamma4*10*7471)))**((xx - 10)/(SQRT((20*gamma4) + (gamma4 - 10))))**(-2*gamma4/(gamma4 - 10)) - 7471
    RETURN
    If (tel2) :
    yy = xx*(10 + (gamma4 - 10)*SQRT(20 - ((gamma4 - 10)*SQRT((10/7471)*(xx - 10)))/(SQRT((20*gamma4) + (gamma4 - 10)*(xx - 10))))**20*gamma4/(gamma4 + 10) + p1*p1*p10
    RETURN
    Bisection:
    t2 = (t6 - t3)*(xx - x6)/(x6 - x3) + t6
    x2 = (SQRT((t3 - t2)**2 + (x3 - x6)**2)*yy + SQRT(((t6 - t2)**2 + (x6 - x3)**2)*yy))/SQRT(((t6 - t3)**2 + (x6 - x3)**2))
    rne2 = (SQRT((t3 - t2)**2 + (x3 - x6)**2)*rme6 + SQRT(((t6 - t2)**2 + (x6 - x3)**2)*rme3))/SQRT(((t6 - t3)**2 + (x6 - x3)**2))
    If (rme > 10 THEN x2 = (x2 + v1)/20 ELSE x2 = (x2 - v1)*20/(20*rme + 10) + v1
    A2 = (t2 - t1)*x2*(v1 + v2) + v1
    yy = xx - x2
    RETURN
    Gcale:
    yy = (50/60)*(LOG((10 - (xx*(xx2 - xx2) - 10)/1m6)**.20)/(10 + (xx*(xx2 - xx2) - 10)/1m6)**.20)) - 20*ATN((xx*(xx2 - xx2) - 10)/1m6)**.20) + 6*(xx*(xx2 - xx2) - 10)/1m6
    RETURN
    Gcale0:
    yy = (50/60)*(LOG((10 - (xx*vv*(xx2 - xx2) - 10)/1m6)**.20)/(10 + (xx*vv*(xx2 - xx2) - 10)/1m6)**.20)) - 20*ATN((xx*vv*(xx2 - xx2) - 10)/1m6)**.20) + 6*(xx*vv*(xx2 - xx2) - 10)/1m6
    RETURN
    Lmext:
    yy = LOG((10 - SQRT((xx20*(xx - 11124/xx2) - 10)/1m6))) + SQRT((xx20*(xx - 11124/xx2) - 10)/1m6) + xx20*(xx - 11124/xx2)/(20*xx20*xx2)
    RETURN
    Serend:
    END SUB

```



Report Documentation Page

| | | |
|--|-----------------------------|--|
| 1. Report No. NASA CR-181722 | 2. Government Accession No. | 3. Recipient's Catalog No. |
| 4. Title and Subtitle Expansion Tube Test Time Predictions | | 5. Report Date September 1988 |
| | | 6. Performing Organization Code |
| 7. Author(s) C. M. Gourlay | | 8. Performing Organization Report No 8/88 |
| 9. Performing Organization Name and Address University of Queensland Department of M.E. St. Lucia, Queensland 4067 AUSTRALIA | | 10. Work Unit No. 505-62-81-61 |
| 12. Sponsoring Agency Name and Address National Aeronautics and Space Administration Langley Research Center Hampton, VA 23665-5225 | | 11. Contract or Grant No. NAGW-674 |
| | | 13. Type of Report and Period Covered Contractor Report |
| | | 14. Sponsoring Agency Code |

15. Supplementary Notes

Langley Technical Monitor: Griffin Y. Anderson
Final Report

16. Abstract

The interaction of an interface between two gases and a strong expansion is investigated and the effect on flow in an expansion tube is examined. Two mechanisms for the unsteady pitot-pressure fluctuations found in the test section of an expansion tube are proposed. The first mechanism depends on the Rayleigh-Taylor instability of the driver-test gas interface in the presence of a strong expansion. The second mechanism depends on the reflection of the strong expansion from the interface. Predictions compare favourably with experimental results. The theory is expected to be independent of the absolute values of the initial expansion tube filling pressures.

**ORIGINAL PAGE IS
OF POOR QUALITY**

| | | | |
|---|---|------------------------|------------------|
| 17. Key Words (Suggested by Author(s)) shock tunnel, stability, interface hypervelocity | 18. Distribution Statement Unclassified - Unlimited Subject Category 09 | | |
| 19. Security Classif. (of this report) Unclassified | 20. Security Classif. (of this page) Unclassified | 21. No. of pages 97 | 22. Price A05 |